DEVELOPMENT AND DEMONSTRATION OF STSim, A SIMULATION ENVIRONMENT FOR SPACE TECHNOLOGY SYSTEMS

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Final Report

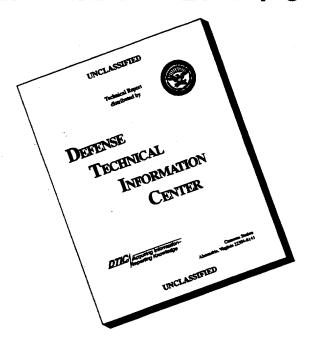
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1.0 PURPOSE/SCOPE

The purpose of this Phase I Small Business Innovative Research (SBIR) contract was to develop and demonstrate the Space Technologies Simulation (STSim), a simulation environment which has the following features:

- Incorporates on-orbit space experiment assets, i.e., sensors, satellites, communications networks, and command centers
- Supports all three Phillips Lab/SX (PL/SX) system phases, i.e., Definition, Acquisition, and
 Operations Phases
- Utilizes consistent software procedures, tools, and infrastructure
- Addresses issues at appropriate scope and level of fidelity
- Supports both analysis and operator-in-the-loop modes of operation
- Utilizes object-oriented software techniques

The specific STSim application chosen to demonstrate these features was a space-based optical sensor controlled by the forward user. The emphasis of STSim was on space experiment type assets, i.e., satellites (both bus and payload systems), communications networks, and command centers. More specifically, the satellite bus is a combination of Global Positioning System (GPS) Block IIA and Block IIR systems. The payload is an optical sensor which is controlled by commands from the ground, e.g., azimuth and elevation commands. The communications network is a three node system consisting of satellite, Falcon Air Force Base (FAFB), and PL nodes where FAFB serves as a relay node. The command center allows the user to send/receive both bus and payload commands/telemetry.

The following sections discuss the above STSim requirements (Section 2.0), the STSim development approach (Section 3.0), and STSim results (Section 4.0). Since the emphasis of the STSim program was on the final demonstration, only a summary of the results is presented in Section 4.0.

2.0 STSim REQUIREMENTS

The STSim requirements listed above are designed to support definition, acquisition, and operation of PL space experiments. In general, these phases are technically challenging as well as technically fluid. STSim is responsive to both of these aspects of space experiments.

2.1 INCORPORATE ON-ORBIT SPACE EXPERIMENT ASSETS

STSim is a specific application of the BCSi simulation environment (Fig. 1). All models of space experiment assets fall into command center (BCCmdCtr), communications network (BCCom), or physics-based environment (BCSim) simulation segments. The proctor and network manager segments of the BCSi simulation environment are not included in the current version of STSim, although they are options which may be added.

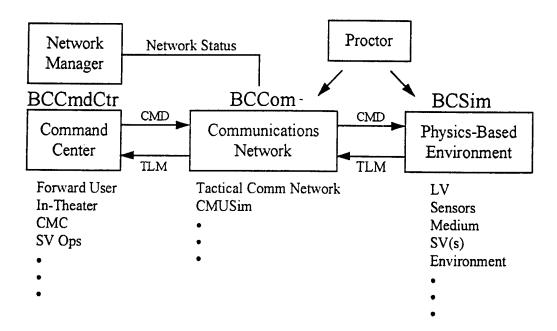


Figure 1. BCSi simulation environment.

BCCmdCtr software supports development of operator-in-the-loop Human Computer Interfaces (HCIs). These HCIs replicate operator interfaces such as telemetry screens and command

generation screens. The STSim HCI allows the user to send/receive both bus and payload commands/telemetry."

BCCom is a high-fidelity message-based communications modeling tool which includes features such as routing algorithms, buffer management, protocols, message priority, and node dynamics. BCCom supports both detailed analysis and operator-in-the-loop operations. BCCom is used in STSim to model the strawman three node space experiment communications network.

BCSim supports object-oriented development of physics-based models. Models may be continuous, multi-rate, and/or input/output-driven. BCSim also supports both analysis and operator-in-the-loop operations. STSim uses BCSim to model the satellite bus and payload systems.

2.2 SUPPORT ALL THREE PL/SX SYSTEM PHASES

STSim has the flexibility required to support all three PL/SX system phases, i.e., Definition, Acquisition, and Operations Phases.

2.2.1 Definition Phase

During the Definition Phase, the STSim environment can be used to derive detailed technical specifications. For example, the communications network segment of STSim (BCCom) can be used to define all system nodes and links. Nodes can be further defined to include buffer size and management algorithms, message processing rates, protocols, message routing, and message formats. Links can be further defined to include data rates and Bit Error Rates (BERs). The effects of each of these design parameters upon overall network performance can be assessed.

In a similar manner, detailed technical requirements of physics-based systems can also be derived using BCSim. For example, satellite subsystems and subsystem interfaces can be designed and analyzed, e.g., satellite attitude control laws, power system sizing, etc.

Finally, since both BCCom and BCSim support analysis and operator-in-the-loop modes of operation, STSim can be used to demonstrate prototype system operations to include operator HCIs. At the conclusion of the Definition Phase, then, the customer can clearly define the detailed technical requirements for communications networks, physics-based systems (e.g., satellites, sensors, etc.), and operator HCIs. These detailed technical requirements can serve as the basis for technical support of the Acquisition Phase.

2.2.2 Acquisition Phase

STSim can be used to support a number of aspects of the Acquisition Phase. First, the detailed technical requirements and models developed from the Definition Phase can provide both 'performance audit' and 'technical roadmap' information during system acquisition. For example, test results of system components can be integrated into STSim as they become available. Subsequent analysis can be used to provide both an ongoing audit of system performance and an assessment of the effects of component anomalies such as underperforming communications processors, higher BERs, etc.

Second, STSim can be used to exploit potential system upgrades. For example, technically sophisticated systems often require extended periods for system acquisition and test. During this time, new and/or improved technologies inevitably become available; technologies such as increased processor speeds, different network protocols, etc. STSim can be used to assess the utility of integrating these new/improved technologies.

And finally, STSim can be used to support actual component/subsystem testing by wrapping parts of STSim around the component of interest. For example, the STSim GPS satellite model can be used to drive ground control software or the command center software can be used to drive actual on-board satellite software. (Other BCSi software similar to STSim is currently being used in these capacities to support development of a commercial satellite program currently under development.)

2.2.3 Operations Phase

STSim can be used to support three aspects of the systems Operations Phase. First, it can be used to determine the performance of the current system under various loads and stresses. For example, the BCCom portion of STSim can be used to determine operational performance of the communications network under a variety of experiment message loadings and/or stress events such as link/node outage or degradation.

Second, various aspects of system anomalies can be analyzed using STSim. Again, with regard to the communications network, the high-fidelity, message-based features of BCCom can be used to identify specific nodes and specific effects of network anomalies. The effects can be determined via analysis and operator-in-the-loop modes of simulation. Once the problem has been identified, the solution or parameters of the solution can be determined. If the problem is a result of network issues such as buffer size, message processing rates, link BERs, etc., BCCom can be used to confirm potential solutions. If, on the other hand, the problem is embedded in the operational software, BCCom can support analysis of the parameters of the solution. Even though one would not use BCCom to debug operational software, it can be used to parameterize the solution, i.e., message processing rates, message formats, etc.

And third, various portions of STSim can support operator training for both satellite bus and payload subsystems.

2.3 CONSISTENT SOFTWARE PROCEDURES, TOOLS, AND INFRASTRUCTURE

STSim has been developed using a consistent set of BCSi procedures, tools, and infrastructure classes. The procedures are outlined in Section 3.0 and are grouped in object design, object development, and integrated system phases. Each phase supports the object-oriented approach and has specific tasks and reviews. Development of other applications will follow these same phases.

The major BCSi software segments used in STSim are consistent with the object-oriented approach. BCCmdCtr and BCSim are BCSi tools which support full object-oriented software development of HCIs and physics-based models, respectively. BCCom, the high-fidelity message-based network modeling tool, is not currently object-oriented. When used in operator-in-the-loop simulation environments, however, the network model is a separate process operating as an independent communications object.

Along with each of the STSim segments, there is an existing infrastructure developed during other internal/external projects. BCCmdCtr has been used to command and control several satellite systems as well as support missile warning. BCCom has been used to model a wide variety of communications networks, some for analysis and others for operator-in-the-loop operations. Network model applications have included both satellite command and control as well as missile warning. BCSim has been used to model satellites, launch vehicles, and sensors. A rich set of supporting classes such as FreeBody, SpaceVehicle, and LaunchVehicle has been developed which support a variety of other applications. Section 4.1.3 gives a brief overview of these classes.

The combination of procedures, tools, and infrastructure classes allows STSim to be tailored to the appropriate scope and level of fidelity during Definition, Acquisition, and Operations Phases of space experiments.

2.4 FLEXIBLE SCOPE AND LEVEL OF FIDELITY

As shown during the final demonstration, STSim is extremely flexible with regard to both scope and level of fidelity. With regard to STSim scope, depending upon the particular STSim configuration, various segments can be run standalone or integrated in an end-to-end simulation. For example, the communications network model and satellite operations can be run standalone for individual segment analysis. They may also be integrated with command center software to provide a simulation environment which extends from the satellite bus and payload systems through the communications network and to the forward user at PL.

Flexibility with regard to level of fidelity is also an integral part of STSim. For example, communications network models may be easily enhanced through the BCCom menu-driven interface and integrated with STSim. Subsystem models of satellites other than GPS Block IIA and IIR have been developed in support of numerous other simulation efforts and can be easily integrated. Such flexibility allows the user to tailor the simulation environment segments to the appropriate scope and level of fidelity.

2.5 <u>SUPPORT BOTH ANALYSIS AND OPERATOR-IN-THE-LOOP</u> MODES OF OPERATION

It is important that a simulation environment to be used in the defintion, acquisition, and operation of space-based experiments support both analysis and operator-in-the-loop modes of operation. Oftentimes, considerable insight is provided by an 'operator's eye' view of a detailed technical issue. Conversely, it is also important to be able to define the technical details of operational requirements. Obviously, both analysis and operator-in-the-loop modes must use consistent models.

As demonstrated in the Final Briefing, STSim supports both analysis and operator-in-the-loop modes of operation. The models used in both cases are the same; only the segment interfaces are modified.

2.6 <u>UTILIZE OBJECT-ORIENTED TECHNIQUES</u>

The fundamental feature of STSim which provides the capabilities mentioned above is the implementation of object-oriented design and development. Satellite subsystem models of one fidelity can be easily replaced with other models which have been tuned to the particular application. Software segments can be easily integrated to expand or restrict the scope of the simulation. As a result, the flexibility provided by the object-oriented approach makes STSim responsive to space experiment Definition, Acquisition, and Operations phases.

3.0 STSim DEVELOPMENT APPROACH

The approach used to develop STSim was to tailor the existing BCSi simulation environment to the space experiment application. Typically, development is conducted in three phases, each phase consisting of specific tasks and culminating with the following respective design reviews.

- Object Design Review BCSi reviews overall STSim architecture and the scope and level of fidelity of all STSim objects. BCSi demonstrates object motion and an initial version of the user interface. Customer reviews object definition and user interface.
- Object Development Review BCSi describes and demonstrates results of object development
 and upgrades to the user interface. Customer reviews object development with respect to
 scope and level of fidelity as well as the user interface with respect to preprocessing, runtime,
 and postprocessing data accessibility.
- Integrated System Review BCSi presents results of the integrated operations.

Due to the size of this project, only a final demonstration of the Integrated System Review was conducted. The status of object design and development was documented via monthly status reports. The following sections give a brief description of the tasks performed during all three software phases.

3.1 OBJECT DESIGN PHASE

The purpose of the Object Design Phase was to define simulation objects and demonstrate the STSim object dynamics and HCI. Specific tasks performed include:

- Identify simulation requirements
- Specify relevant simulation scenario
- Define simulation architecture, i.e., define top-level objects and interrelationships
- Design and implement the dynamic motion of top-level objects (full object functionality is added during the Object Development Phase)

- Design minor objects within each top-level object to appropriate scope and level of fidelity
- Conduct Object Design Review

3.2 OBJECT DEVELOPMENT PHASE

The purpose of the Object Development Phase was to develop those objects defined during the previous phase and perform the first iteration of the HCI. Specific tasks include:

- Prototype all objects to prescribed scope and level of fidelity
- Verify object design with available test or analytical results
- Integrate minor objects within appropriate top-level objects
- Conduct Object Development Review

3.3 INTEGRATED SYSTEM PHASE

The purpose of the Integrated System Phase was to integrate all major and minor objects to form the STSim simulation environment. Specific tasks include:

- Integrate all STSim objects
- Begin testing end-to-end STSim
- Begin final report
- Conduct Integrated Systems Review

4.0 STSim RESULTS

The major segments of STSim correspond to the scope described previously (Fig. 2). The satellite operations command center was developed using BCCmdCtr and included bus and payload operations. The communications network was developed using BCCom and included nodes for PL, FAFB, and satellite communications. The space-based platform was developed using BCSim and included subsystem models for both the payload experiment and satellite bus operations.

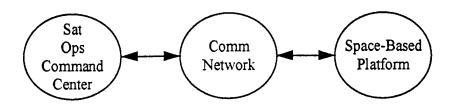


Figure 2. Top-level STSim software segments.

Sections 4.1 through 4.3 discuss each of these segments as they were presented in the final briefing, i.e., satellites, comm networks, and command centers. Each subsection discusses segment highlights, top-level design, and results. Section 4.4 gives a brief description other related options available, i.e., threat/launch vehicles, medium, and proctor functions.

4.1 STSim SATELLITE

4.1.1 Satellite Highlights

The satellite segment has the following features:

- · Variable fidelity satellite bus and payload modeling capability
- Six degree of freedom orientation
- Kepler propagator or simple geosynchronous propagator models

- Fully object-oriented design for easy interchangeability of components and instantiation of multiple occurrences
- Bus subsystems are hybrids of GPS IIA/IIR and include TT&C, Propulsion, Thermal, Attitude
 Controls, Structures, Power
- Payload model is a ground-controlled optical sensor

4.1.2 Satellite Design

The satellite class and object hierarchies are depicted in Figure 3. The class hierarchy denotes that the STSim satellite inherits from the SpaceVehicle class which, in turn, inherits from the FreeBody class. Stated another way, the STSim satellite is a SpaceVehicle which is a FreeBody. The SpaceVehicle and FreeBody classes are part of the BCSi software infrastructure as implemented within BCSim. Together, these two classes support the physical integration of dynamic components. More specifically, the FreeBody class supports determination of forces/torques, orientation, and graphical realizations. The SpaceVehicle class supports six degree of freedom space vehicle dynamics. Detailed descriptions of the architecture and use of these classes are provided in other documents (Ref. 1).

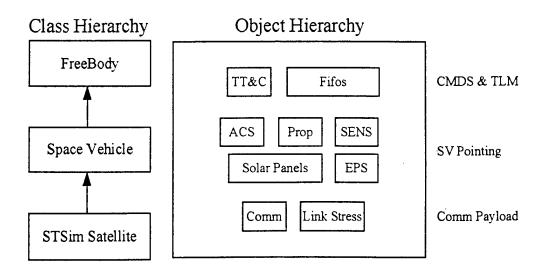


Figure 3. STSim satellite design.

The object hierarchy depicts the top-level subsystems of the STSim satellite. As indicated, these subsystems fall into the commands/telemetry, satellite pointing, and communications payload categories. In addition, the structure subsystem is modeled via the SpaceVehicle and FreeBody classes and does not appear explicitly within the object hierarchy. Features, design, and typical results of the major objects within the satellite hierarchy (i.e., structures, Electric Power Subsystem (EPS), Attitude Control System (ACS), propulsion, and payload) are discussed in the following subsections. The File In File Out (FIFO) and Link Stress objects support STSim satellite connectivity with other STSim segments such as the communications network model and command center and will not be discussed in detail.

4.1.3 Satellite Structures

- 4.1.3.1 <u>Satellite Structures Highlights</u>. The satellite structure model has the following features:
- Fully object-oriented architecture
- Automatically duplicates architecture of actual physical system via FreeBody/SpaceVehicle
 Classes
 - Attach components to base structure
 - Component defined by mass, moments of inertia, position/orientation, etc.
 - Virtual transmission of torque/forces and relative position/orientation
 - Supports 3-D graphical animation
 - Performs translation/rotation dynamics
- 4.1.3.2 <u>Satellite Structures Design</u>. The structures design hierarchy reflects the SpaceVehicle and FreeBody classes as well as the BCBlock class (Fig. 4). The BCBlock class supports object connectivity and controls object execution while the SpaceVehicle and FreeBody classes support functions described previously.

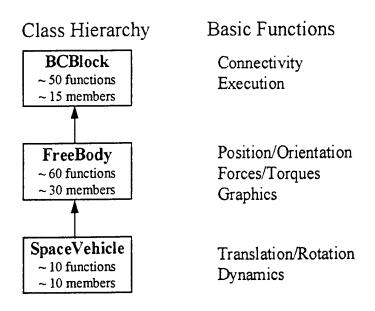


Figure 4. Satellite structures hierarchy.

When used together, these classes allow the developer to create a BCSim simulation of the satellite in software in a manner analogous to building the actual satellite in hardware. For example, attaching a sensor to the actual satellite structure establishes the orientation of the sensor vis-a-vis the satellite; and attaching a thruster establishes force/torque effects on the satellite. Similarly, the developer may "attach" a sensor or thruster to the satellite structure by specifying SpaceVehicle/FreeBody data members such as position and orientation values. After attaching the component, the developer may use any of the various member functions which determine orientations, forces, torques, dynamics, etc. Again, details of BCSim and existing infrastructure classes are contained in other documents (Ref. 1).

4.1.3.3 <u>Satellite Structures Results</u>. The results of the structure model were demonstrated during the final briefing and included 3-D articulated graphics, runtime control interfaces, and the dynamics effects of ACS and propulsion subsystems. Sun and earth motion were also included in the environment model. Plots depicting satellite dynamics, attitude control commands, and thruster forces for an initial capture scenario are presented in Section 4.1.5, Satellite Attitude Control Subsystem.

4.1.4 Satellite Electrical Power Subsystem

- 4.1.4.1 Satellite EPS Highlights. The satellite EPS model has the following features:
- Hybrid of GPS Block IIA/IIR configurations
- Models all power management functions, e.g., batteries, power regulation unit, and shunt dissipators
- GPS Block IIA solar array drive digital logic controller
- Supported by PowerLoad and PowerBus classes
- 4.1.4.2 <u>Satellite EPS Design</u>. The STSim satellite EPS model is a hybrid of an existing BCSi simulation of the GPS Block IIA EPS and the GPS Block IIR EPS. The Block IIR EPS, as described in the IIR Orbital Operations Handbook (OOH), is depicted in Figure 5. The class and object hierarchy as modeled in BCSim has an architecture consistent with IIR (Fig. 6). Solar array drive and battery models are IIA models. The Power Regulation Unit (PRU) and the EPS bus and power loading architecture are IIR designs.

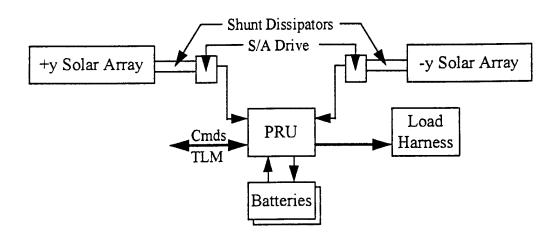


Figure 5. Satellite EPS subsystem.

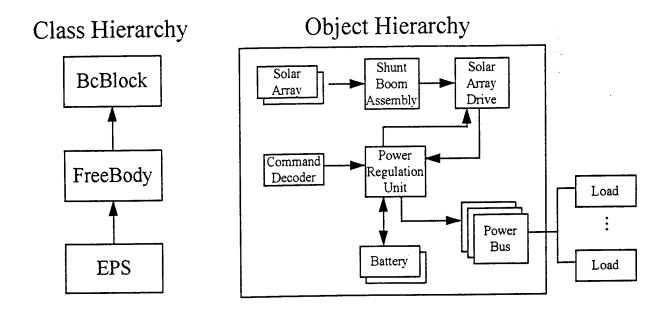
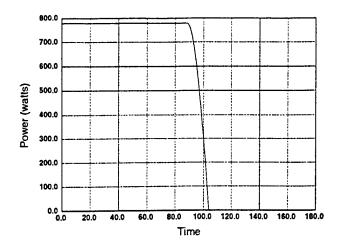


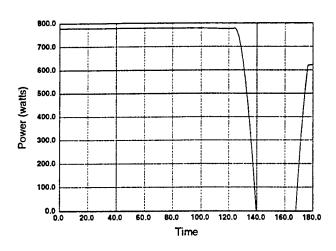
Figure 6. Satellite EPS hierarchy.

The EPS model has multiple power buses. Each bus can have multiple power loads attached to it via specifying individual impedances. By summing the bus impedance, the effects of component power loads on bus voltage can be modeled.

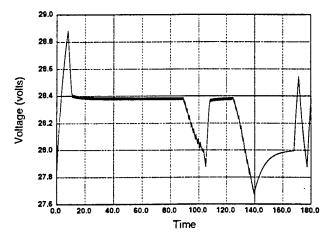
4.1.4.3 Satellite EPS Results. Figures 7 through 9 depict the results for a scenario wherein the solar panels are initially oriented to the sun and then are individually rotated via ground commands. Initially, both panels provide nearly 800 watts (Figs. 7a,b). Since this is considerably more than the power load required for this scenario (arbitrarily set to 600 watts), the power is directed to charging of the batteries as indicated by the increase in the battery voltage and the relatively small value of positive battery current (Figs. 8a,b). Since the power generated by the solar panels is still more than required, power is shunted as indicated by the drop in the net current coming out of the shunt boom assembly (Fig. 9b). After the initial transients settle, the bus voltage goes to 28.5 volts (Fig. 7c), the battery voltage and current go to their respective steady state charge values, and the boost current is not needed (Fig. 8c).



(a) +y panel power generated.

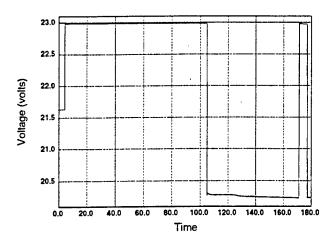


(b) -y panel power generated.

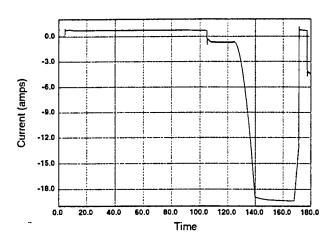


(c) Main bus voltage.

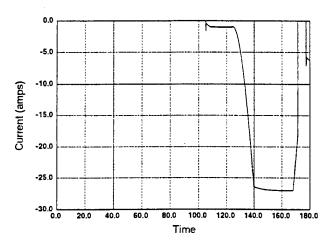
Figure 7. EPS panel power and bus voltage.



(a) Battery 1 voltage.

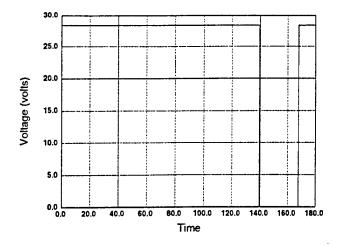


(b) Battery 1 current.

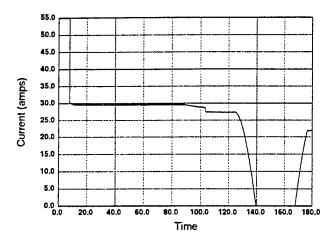


(c) Battery boost current.

Figure 8. EPS battery voltage, battery current, and boost current.



(a) Regulated voltage out of shunt boom assembly.



(b) Regulated current out of shunt boom assembly.

Figure 9. EPS shunt boom assembly output voltage and current.

The +y solar panel is rotated away from the sun starting at approximately 90 seconds into the scenario and faces completely away from the sun approximately 15 seconds later (Fig. 7a). As the +y panel is rotated, the bus voltage goes down a fraction of a volt (Fig. 7c), the batteries stop charging and are required to supply a small amount of boost current (Fig. 8). The battery boost voltage is fixed at approximately 20.2 volts (Fig. 8a). And finally, the net current out of the shunt boom is slightly reduced (Fig. 9c).

When the -y panel is rotated at approximately 125 seconds (Fig. 7b), the bus voltage again drops, the boost current from the batteries is increased considerably, and the power out of the shunt boom assembly drops to zero (i.e., the panels are supplying no power). Unlike the +y panel which stopped rotating when it faced away from the sun, the -y panel continued to rotate until it reached a fixed offset near the end of the scenario. The transients as the PRU adjusts between battery charging and batteries providing boost current are evident during the last ten seconds of the simulation run.

4.1.5 Satellite Tracking Telemetry and Control (TT&C)

4.1.5.1 <u>Satellite TT&C Highlights</u>. The satellite TT&C model has the following features:

- Receives GPS Block IIR commands
- Generates GPS Block IIR telemetry stream
- Records all commands received as a function of time
- Uses actual bit format for both commands and telemetry (excluding encryption)
- Decodes all seven types of commands (discrete, message, and configuration)
- Routes commands to appropriate subsystem
- Uses command database for decoding (343 discrete commands and 181 serial message commands)
- Transmits entire telemetry master frame (8 major frames, 64 minor frames, 4096 words)
- Uses telemetry master frame database (5968 items)
- Encodes actual sensed/measured values from subsystems
- Handles all types of telemetry (serial, analog, discrete logic)
- Uses the normal telemetry mode (but not Dwell or Dump modes)
- 4.1.5.2 <u>Satellite TT&C Design</u>. The satellite TT&C subsystem has been upgraded to reflect the GPS Block IIR architecture (Fig. 10). Starting with the commands received on-board the satellite, the Command Receiver class accepts the command and strips off any communications

network message headers. The resulting 20 bit command is then passed to the Command Decoder Unit (CDU). The CDU determines which of the seven the message types has been received, e.g., CDU configuration, CDU discrete, Payload Control Electronics (PCE) discrete, precursor, serial message, abort, and no operation commands.

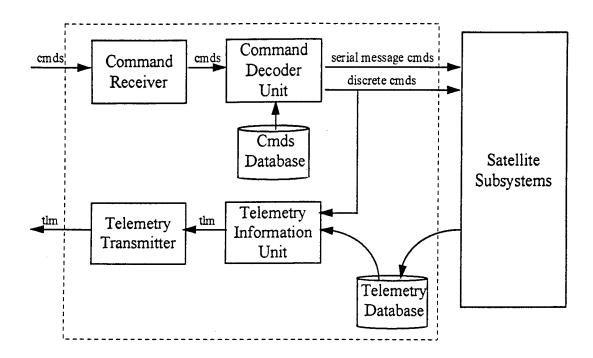


Figure 10. Satellite TT&C architecture.

Command processing depends upon the command type. CDU configuration commands apply to the CDU only and are not passed to any other subsystem. These commands turn on and/or swap CDUs.

The PCE and CDU discrete commands affect the payload and CDU subsystems, respectively. A 20-bit discrete command contains a 10-bit command code which is passed on to the appropriate subsystem for subsequent processing. The discrete commands database (Appendix A) is used to translate the 10-bit discrete command code into a command integer before it is passed to the corresponding subsystem.

Message commands are serial commands which start with a precursor command. The precursor puts the CDU into the message mode, setting the counter to the number of messages to follow. When in the message mode, only configuration commands or the abort command are accepted. Configuration commands are decoded and validated and then routed to other subsystems. Three types of configuration commands are processed: command words, data parameters, and checksums. The message command database is used to determine the command format (Appendix B). The abort message will immediately abort the message mode by returning the CDU to the non message mode.

When the message counter reaches zero, all messages have been received and the CDU exits the message mode. The CDU may also exit the message mode via the timeout feature (set to 42 seconds). If the entire message has not been received by the CDU timeout, the CDU will abort the message mode.

The no operations command is used for command verification and validation and ensures that the satellite is receiving commands. The command counter is incremented and will be evident in the telemetry stream.

The telemetry stream is constructed by the Telemetry Information Unit (TIU) on-board the satellite. The stream is constructed of one master frame per data cycle; each master frame consisting of 8 major frames; each major frame consists of 8 minor frames; and each minor frame consists of 64 words laid out in an 8x8 matrix. The size of one complete data cycle is 32,768 bits and can be transmitted at either 500 bps or 4000 bps.

The telemetry database has been created from the telemetry listing contained in the GPS Block IIR OOH (Appendix C). This database contains information about the telemetry measurands and the mapping of these measurands into the telemetry stream. Upon program initiation and reading of the telemetry database, measurand and telemetry stream mapping structures are created. Values in the measurand data structure may be updated by the appropriate satellite subsystems.

The mapping structure creates the telemetry stream using the current values in the measurand data structure.

In creating the telemetry stream, the TIU operates in one of three modes: Normal, Dump and Dwell. The Normal mode creates the stream from the nominal mapping information. In the Dump and Dwell modes, minor frame words 4 through 7, 12 through 15, etc. are replaced with the data requested by the Dump or Dwell modes. The STSim TT&C only operates in the Normal mode.

Finally, there are four measurand formats: Serial, Analog High, Analog Passive, and Discrete Logic. Information contained in the OOH specifies which format applies to each measurand.

4.1.5.3 <u>Satellite TT&C Results</u>. All commands are recorded to a log file during a specific run. These log files can be used for operator review and/or for script inputs. A small portion of the log file of a particular run is depicted in Figure 11.

DISCRETE Cmd 1 issued at 29.900000 DISCRETE Cmd 201 issued at 144,900000 DISCRETE Cmd 209 issued at 151,900000 DISCRETE Cmd 211 issued at 152,900000 DISCRETE Cmd 221 issued at 156.400000 DISCRETE Cmd 221 issued at 163,400000 DISCRETE Cmd 223 issued at 166.400000 Message Mode ENABLED for 3 msgs at 209.400000 Received MESSAGE 3000001 at 210.400000 Received MESSAGE 2000621 at 210.900000 Received MESSAGE 2000454 at 211.150000 MESSAGE issued and Mode terminated at 211.150000 Message Mode ENABLED for 3 msgs at 219.025000 Received MESSAGE 3000001 at 220.025000 Received MESSAGE 2000145 at 220.525000 Received MESSAGE 2000454 at 220.775000

Figure 11. Satellite TT&C commands log file.

The log file indicates several discrete commands were received. At approximately 209 seconds into the simulation, the message mode was enabled and a message command was received onboard the satellite. The message mode was terminated at approximately 211 seconds. Another message command was sent at approximately 220 seconds.

STSim telemetry is not logged, although this feature is available and has been incorporated in other BCSi simulation environments. Generation of telemetry on the satellite transmission through the communications network, and display at the PL/Command Center was demonstrated during the final briefing.

4.1.6 Satellite Attitude Control Subsystem (ACS)

4.1.6.1 <u>Satellite ACS Highlights</u>. The satellite ACS model has the following features:

- High-fidelity GPS IIA jet controller
- Jet select modified for GPS IIR
- Mass properties updated for GPS IIR
- Sensor architecture updated to use FreeBody class
- Solar panel controller is GPS IIA
- High-fidelity wheel control and thruster momentum dumping available
- 4.1.6.2 <u>Satellite ACS Design</u>. The STSim satellite ACS replicates the thruster control system on-board the GPS Block IIA, i.e., the STSim controller has the same architecture, controller gains, difference equations, and sample rates. A top-level block diagram of the control law architecture as implemented in the Jet Control Logic module is depicted in Figure 12.

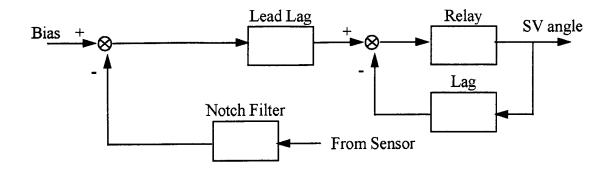
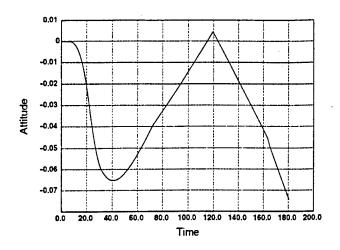


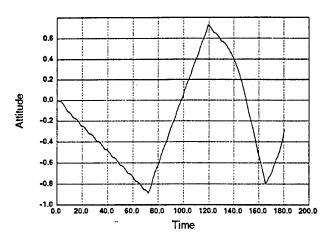
Figure 12. Satellite ACS control law architecture.

The outputs of the thruster controller are on/off commands for each satellite axis. These logical commands are converted to specific thruster commands in the Jet Select Logic module.

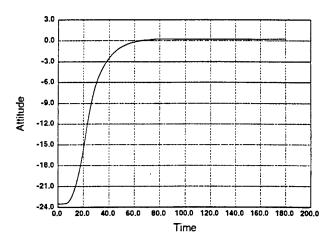
4.1.6.3 <u>Satellite ACS Results</u>. Results of a typical initial capture of the satellite are depicted in Figures 13 through 15. The initial roll and pitch angles of the satellite are zero and required no correction. The initial yaw angle of -23.5 degrees required controller action (Fig. 13). The yaw command was set to one to cause the satellite to rotate in the +yaw direction (i.e., about the +z axis). At approximately 20 seconds, a series of -yaw commands were issued to slow and eventually null the yaw rotation (Fig. 14). Selected thruster commands are depicted in Figure 15.



(a) Satellite attitude - roll.

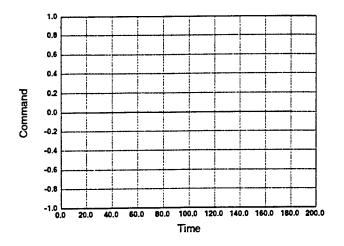


(b) Satellite attitude - pitch.

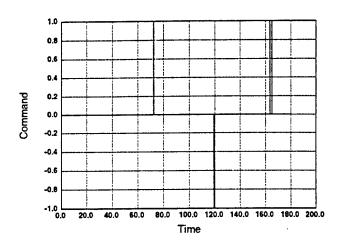


(c) Satellite attitude - yaw.

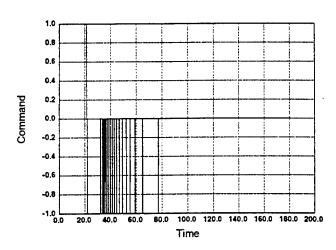
Figure 13. Satellite attitude - initial capture.



(a) Roll command.

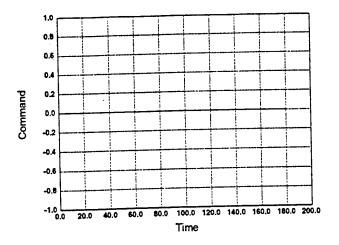


(b) Pitch command.

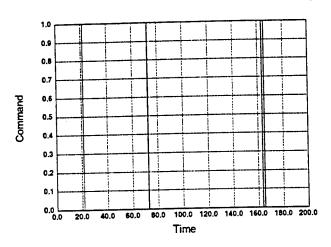


(c) Yaw command.

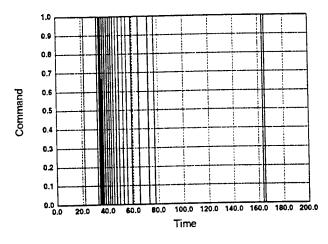
Figure 14. Satellite control commands - initial capture.



(a) Thruster #1 command.



(b) Thruster #6 command.



(c) Thruster #5 command.

Figure 15. Satellite thruster commands - initial capture.

The satellite pitch angle slowly drifts off null as the satellite propagates in its orbit. At approximately 70 seconds, the pitch angle exceeds the deadband value of .8 degrees and the satellite continues in a limit cycle as indicated by the attitude and thruster commands (Figs. 13b, 14b, 15b). The roll angle never exceeded the deadband value and therefore required no control action (Figs. 13a, 14a, 15a).

4.1.7 Satellite Propulsion Subsystem

- 4.1.7.1 <u>Satellite Propulsion Subsystem Highlights</u>. The satellite propulsion subsystem has the following features:
- Responds to changes in pressure, temperature, and mass of each propellant tank
- Responds to all latch valve commands and connectivity
- Determines thruster force as a function of propellant tank pressure and temperature
- 4.1.7.2 <u>Satellite Propulsion Subsystem Design</u>. The satellite propulsion subsystem model duplicates the architecture of the actual Block IIR system (Fig. 16). In particular, two tanks, four latch valves, and 16 thrusters are modeled. The characteristics of each of these components is described in the propulsion subsystem highlights listed above. The location and orientation of each thruster corresponds to Block IIR. All thrusters models inherited the FreeBody class, thereby making determination of thruster orientation and the effects of thruster forces and torques straightforward.

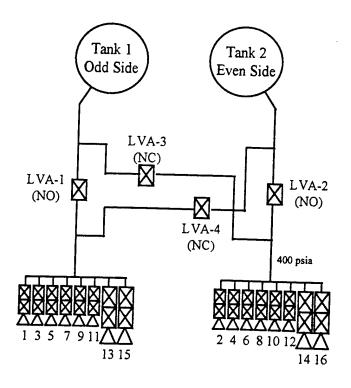
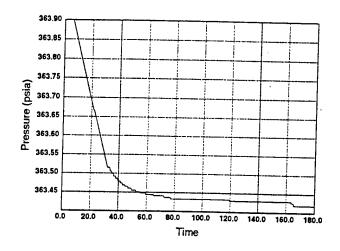
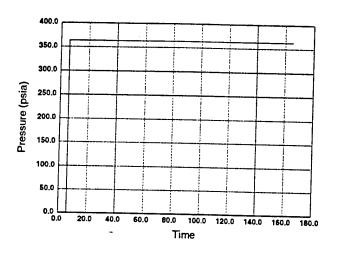


Figure 16. Satellite propulsion subsystem model.

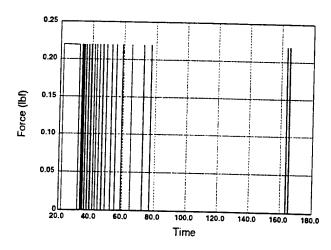
4.1.7.3 <u>Satellite Propulsion Subsystem Results</u>. The thruster results of the initial capture scenario portrayed in the ACS section (Section 4.1.6) are depicted in Figure 17. As the thruster pulses, the tank pressure is drawn down a small amount (note the scale of the axis). The pressure variation is not noticeable from the latch valve pressure scale. The actual thrust is approximately .22 lbf and corresponds the propellant tank pressure.



(a) Tank 1 pressure.



(b) Latch valve 1 pressure.



(c) Thruster #2 force.

Figure 17. Satellite thruster output - initial capture.

4.1.8 Satellite Optical Sensor Payload

- 4.1.8.1 <u>Satellite Optical Sensor Payload Highlights</u>. The satellite optical sensor payload model has the following features:
- Generates sensor field of view image information
- Commandable horizontal and vertical offset
- Optical characteristics are configurable (i.e., beam diameter at earth)
- Graphical representation of field of view
- 4.1.8.2 <u>Satellite Optical Sensor Payload Design</u>. The purpose of the payload on-board the STSim satellite was to demonstrate an architecture which could support an experiment which required a ground controlled optical sensor experiment. As such, the STSim satellite sensor model is not high-fidelity. Sensor position and orientation resulting from commands from the ground are transmitted to the command center; focal plane data is not transmitted. Higher fidelity sensor models can be quickly substituted for other applications due to the object-oriented nature of the STSim satellite model.

The class and object hierarchy of the optical sensor payload is depicted in Figure 18. As with other objects which require position and orientation information, the sensor inherits from the FreeBody class.

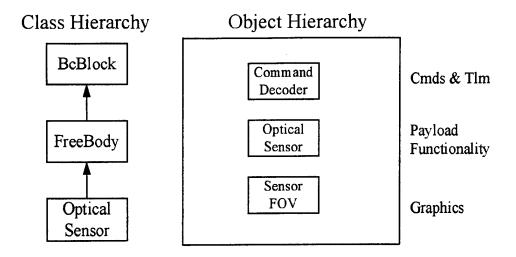


Figure 18. Satellite payload class/object hierarchy.

4.1.8.3 <u>Satellite Optical Sensor Payload Results</u>. The results of the optical sensor payload were demonstrated at the final briefing. Based on azimuth and elevation commands from the ground, the sensor reoriented and the corresponding sensor field of view was portrayed in the command center on the ground. Due to the visual and dynamic nature of the demonstration, no effort is made to portray the results in this report.

4.2 STSim COMMUNICATIONS NETWORK

4.2.1 Communications Network Highlights

The STSim communications network model has the following features:

- Based on BCCom, high-fidelity message-based modeling tool
- Contains satellite, FAFB relay, and PL nodes
- Processes commands, telemetry, and payload messages
- Includes message-based features, e.g., protocols, routing, buffers, etc.
- Menu-driven and postprocessing graphics

4.2.2 Communications Network Design

Since the fundamental purpose of this program was to demonstrate a capability, the communications network model was kept as simple as possible. The network model was developed using BCCom and supported both analysis and realtime operator-in-the-loop modes of operation. The three nodes in the system modeled message processing at the PL command center, the FAFB relay node, and the STSim satellite. Both bus and payload commands were transmitted from the command center to the satellite; bus and payload telemetry were transmitted from the satellite to the command center. More sophisticated communications networks can be, and have been, developed by adding nodes and/or processes at the nodes.

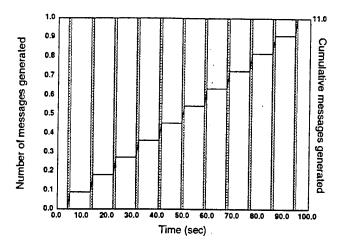
4.2.3 Communications Network Results

BCCom has a rich set of postprocessing graphics which are available for both the analysis and operator-in-the-loop operations. A brief summary of a short simulation run of the STSim communications network model is depicted in Table 1 and Figures 19 through 21. For this particular scenario, 11 bus commands were generated at the PL command center and transmitted through FAFB to the satellite. Eleven telemetry messages were also generated at the satellite payload and bus subsystems. Bus telemetry was transmitted through FAFB to PL while payload telemetry was sent directly to PL. All messages were generated at constant intervals.

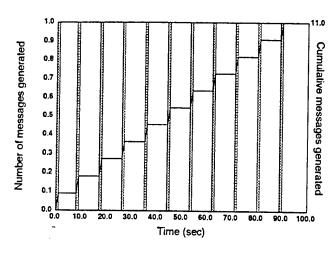
The summary of the message flow indicates the number of messages generated, the nodes these messages were transmitted to, and the average transmission times (Table 1). Note that the SV node corresponds to the satellite bus node and the S node corresponds to the satellite payload node. The message generation profile shows the message generation intervals and the cumulative number of messages generated for each node (Fig. 19). The average transmission times for each message indicates that the messages were quickly transmitted and that there was no noticeable message backup (Fig. 20). Finally, the time history file traces each message as it is processed through each layer within each node (Fig. 21). The time history file provides valuable information for the purpose of network model verification.

Table 1. Communications Network Message Flow Summary.

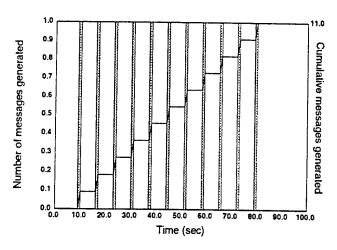
	Number of		Number of	
Source Node	Messages Generated	Destination Node	Messages Received	Average Time
PL	11	FAL	11	0.1333E-01
		SV	11	0.1165
SV	11	FALCON	11	0.1941
		PL	11	0.2529
S	11	PL	11	0.8423E-01



(a) Messages generated at node SV.

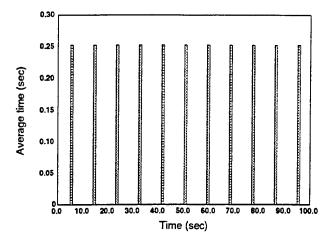


(b) Messages generated at node S.

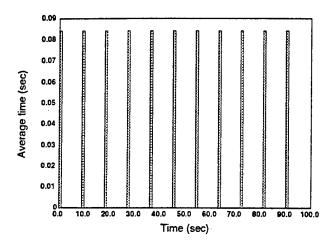


(c) Messages generated at node PL.

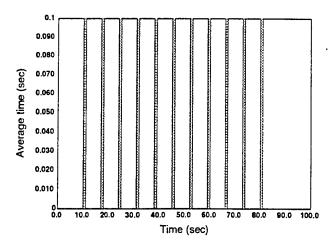
Figure 19. Communications network message generation.



(a) Average transmission time from SV to PL.



(b) Average transmission time from S to PL.



(c) Average transmission time from PL to SV.

Figure 20. Communications network average transmission times.

XXX.RUN Generated by BCCom (BCSi) 06-Jul-95 14:28:17

Time	Id	Node/Link	Process	Event
0.00000	0	S	NET	Generated PAYLOAD
0.00000	0	S	NET	Inserted msg in buffer
0.00000	0	S	NET	Message left buffer
0.00300	0	S	DATAPL	Inserted msg in buffer
0.00300	0	S	DATAPL	Transmitted message
0.00300	0	S	DATAPL	Message left buffer
0.00300	0	S	NET	Deleted msg from buffer
0.00600	0	S_PL		Successful transmission
0.00600	0	S	DATAPL	Deleted msg from buffer
0.08426	0	PL	PHYSFMSV	Received msg at node0
0.08426	0	PL	PHYSFMSV	Received msg at sink
5.00000	1	SV	NET	Generated TELEMETRY
5.00000	1	SV	NET	Inserted msg in buffer
5.00000	1	SV	NET	Message left buffer
5.05729	1	SV	DATA2FAL	Inserted msg in buffer
5.05729	1	SV	DATA2FAL	Transmitted message
5.05729	1	SV	DATA2FAL	Message left buffer
5.05729	1	SV	NET	Deleted msg from buffer
5.11458	1	SV_FALCON		Successful transmission
5.11458	1	sv	DATA2FAL	Deleted msg from buffer
5.19408	1	FALCON	PHYS2SV	Received msg at node
5.19408	1	FALCON	PHYS2SV	Received msg at sink
5.19408	1	FALCON	NET	Inserted msg in buffer
5.19408	1	FALCON	NET	Message left buffer
5.25138	1	FALCON	DATA2PL	Inserted msg in buffer
5.25138	1	FALCON	DATA2PL	Transmitted message
5.25138	1	FALCON	DATA2PL	Message left buffer
5.25138	1	FALCON	NET	Deleted msg from buffer
5.25293	1	PL_FALCON		Successful transmission
5.25293	1	PL	PHYSFMFA	Received msg at node
5.25293	1	PL	PHYSFMFA	Received msg at sink1
5.25293	1	FALCON	DATA2PL	Deleted msg from buffer

Figure 21. Communications network time history file.

4.3 STSim COMMAND CENTER

4.3.1 Command Center Highlights

The STSim command center manages both satellite bus and payload commands/telemetry. The STSim command center bus model has the following features:

- Generates GPS Block IIR command stream for SV
- Decodes and displays GPS Block IIR telemetry stream
- Includes command database (343 discrete and 181 serial message commands)
- Sends/receives actual bit formats (excluding encryption)
- User friendly displays for entering commands (by mnemonic or cmd ID) or viewing telemetry
- Includes telemetry master frame database (5968 items)
- Displays telemetry frames major/minor frame number and the contents on hexadecimal byte format
- Displays a sample telemetry view (i.e., roll, pitch, yaw)
- Records commands sent and view telemetry received to log files and telemetry screens

The STSim command center payload model has the following features:

- Supports operator-in-the-loop
- Processes focal plane position and orientation data for SV
- Other BCSi simulation applications have processed actual focal plane pixel data
- Forward user HCI uses BCSi command center software (i.e., readily changeable formats and data processing)
- Supports 2-D and 3-D graphics

4.3.2 Command Center Design

The design of the PL command center is a near mirror image of the satellite TT&C subsystem described in Section 4.1.5 (Fig. 22). The user generates the desired command via the command center HCI. The HCI uses the command database (the same one used on-board the satellite) to convert the command integer to the appropriate 20-bit command. The command transmitter sends the command to the satellite via the STSim communications network model.

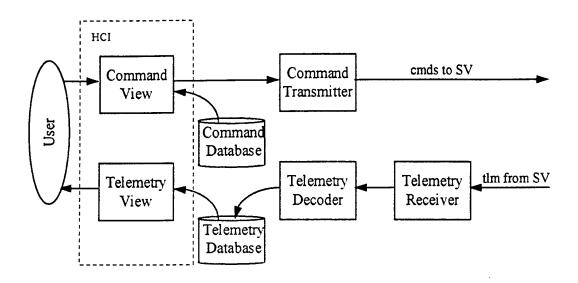


Figure 22. STSim command center design.

Telemetry from the satellite arrives at the telemetry receiver and is decoded using the telemetry database (again, the same database as used on-board the satellite). The telemetry database is also used to drive the telemetry screens at the command center.

The satellite payload telemetry is interpreted on the ground and the corresponding sensor viewpoint is displayed on the forward user console along with time, satellite position, and viewpoint information.

4.3.3 Command Center Results

Command center screens display the main window, command views, satellite bus telemetry, and forward-user payload telemetry. The command center main window consists of four pull-down menus across the top, simulation scenario status information, write message buttons, and a text window (Fig. 23). Command and telemetry screens are accessed from the pull-down menus. The scenario status information is self-explanatory. The write message buttons allow the operator to monitor message generation either by viewing information in the text window or in the log files.

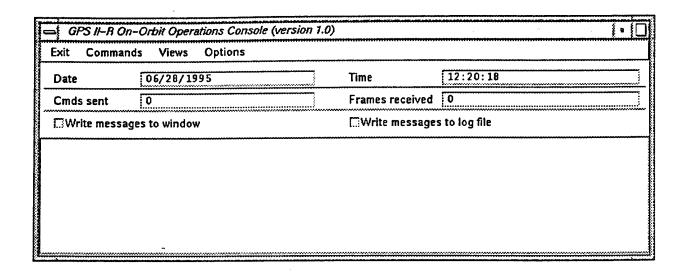


Figure 23. Command center main window.

Command views exist for both discrete and serial message commands (Figs 24 and 25). Both screens are supported by the commands database, i.e., when either the command mnemonic or command integer is entered, information such as command description, octal code, and parameter description is automatically filled in. Buttons are included for transmitting the command and closing the window.

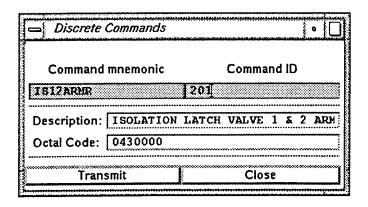


Figure 24. Command center discrete command view.

🛁 Message Comm	ands		
Comma	nd mnemonic	Command ID	
PCHIFTSR		18004	
Description:	PATCH IFTEST/SELT	'S	
Octal Code:	2600011	······	
# Parameters:	8		
Pa	rameter	Value	
CMX IFTEST ADDR	ESS		
CMX SELTS ADDRE	SS		
RECEIVE CONTROL	CONNECTION ADDRESS	[
RECEIVE CONTROL	SIZE		
SEND CONTROL CO	NNECTION ADDRESS		<u></u>
SEND CONTROL SI	ZE		
RECEIVE CONTROL	CONNECTION CODE		
SEND CONTROL CO	NNECTION CODE		
		L	
Subsystem:	TT&C SPU		
Tra	nsmit	Close	

Figure 25. Command center serial message command view.

The telemetry frame view allows the operator to view the bytes of each telemetry frame as they are received (Fig. 26). Another telemetry screen allows the operator to view the values of a few selected telemetry measurands. Additional telemetry screens with various screen formats can be easily created with the BCCmdCtr software.

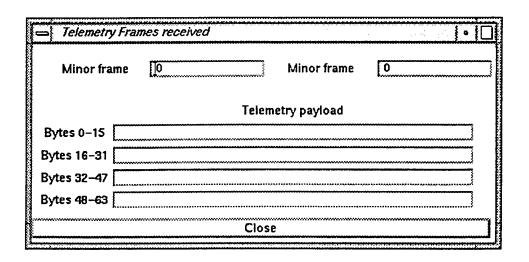


Figure 26. Command center telemetry frame view.

The command center forward user main view portrays the on-board sensor view (Fig. 27). This view is derived from the sensor and satellite position/orientation telemetry. Actual focal plane data has been transmitted in support of other projects, such a capability can be easily added to STSim.

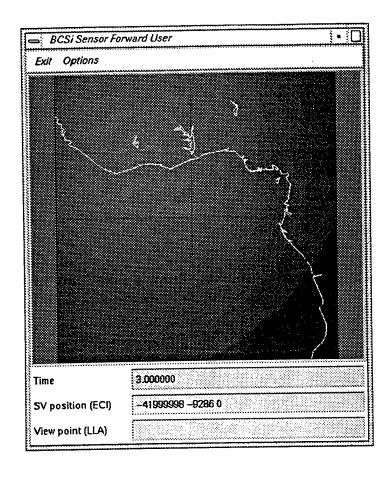


Figure 27. STSim forward user sensor viewpoint.

4.4 STSim OPTIONAL CAPABILITIES

Several BCSi simulation environment capabilities, in addition to those in the current version of STSim, have been developed as part of other simulation projects (Refs. 2,3,4). A brief listing of the highlights of threat/launch vehicle, transmission medium, and proctor options follows.

4.4.1 Threat/Launch Vehicle Option

The threat/launch vehicle segment of the BCSi simulation environment has the following features:

- Simulates a salvo of missiles
- Displays scenario in color 3-D graphics

- Loads different missile scenarios from threat input file
- Threat file is created using a dedicated off-line 3-D graphical environment
- Individual multiple-stage missiles are defined by user (e.g., mass, exit velocity, ...)
- Each missile can carry multiple re-entry vehicles
- Missiles are targeted by setting launch coordinates, pitch maneuver, and stage burn times
- Missiles may be used as satellite launch vehicles

4.4.2 Transmission Medium Option

The transmission medium segment of the BCSi simulation environment has the following features:

- Supports connectivity between "emitters" and "receivers"
- Supplies array of course filtered emitters which are within the line of sight of the requesting receiver
- Architecture supports bi-directional calculations of power from a specific emitter to receiver

4.4.3 Proctor Option

The proctor segment of the BCSi simulation environment has the following features:

- Realtime anomaly inputs to satellite and/or communications network
- Provides realtime contingency planning
- May be initiated/terminated any time during scenario
- Monitors operator actions
- Stores inputs for later playback

5.0 SUMMARY

As demonstrated during the Final Briefing, the STSim simulation environment achieved the specified requirements. In particular, the STSim environment:

- Supports PL assets
- Supports software development phases
- Uses BCSi software tools, procedures, and infrastructure
- Supports analysis and realtime operations
- Has flexible scope and level of fidelity
- Utilizes object-oriented techniques

In short, STSim can be a valuable tool in the support of definition, acquisition, and operation of PL space experiments.

6.0 RECOMMENDATIONS

Recommendations regarding STSim future work follow:

- Expand the utility of the software to the mission and campaign level by using an open architecture which will allow integration with standard protocols such as DIS (Distributed Interactive Simulation) and ADS (Advanced Distributed Simulation).
- Provide a user friendly interface and detailed user documentation to allow third party module
 C++ software development by engineers.
- Expend the modularity of the software to allow the exchange of software modules with associated hardware modules, thereby providing a framework for building a Hardware in the Loop (HIL) capability.
- Develop a strategy for validating the simulation model against real flight data, e.g., payload,
 bus subsystems, and /or mission operations.
- Use STSim to provide support to a PL space experiment. The specific nature of the support
 would depend on the space experiment phase of development, i.e., definition, acquisition, or
 operations.

REFERENCES

- 1. Baer, C.A., et al, <u>BCSim User's Manual</u>, BCSi-95-751071-002, BCSi, Inc., Colorado Springs, CO., July 1995.
- 2. Baer, C.A., et al, <u>Space Systems Technology Simulation (SSTSim) Final Report</u> (draft), BCSi-95-410014-001, BCSi, Inc., Colorado Springs, CO., June 1995.
- 3. Baer, C.A., et al, <u>Global Positioning System Simulation (GPSSim) Executive Summary</u>, BCSi-93-751071-001, BCSi, Inc., Colorado Springs, CO., June 1993.
- 4. Baer, C.A., et al, <u>Defense Satellite Communications System (DSCS) Simulation</u>, RDA-TR-18-0307-0001-001, RDA Logicon, Colorado Springs, CO., February 1993.

APPENDIX A GPS IIR DISCRETE COMMAND BY COMMAND NUMBER TABLE

n Type CMD 20 Bit 10 Bit TMD D 0415100 071 HEX TLM 0 D 0415100 075 A441012 D 0415200 055 A441101 D 0414300 063 A441102 D 0414300 063 A441102 D 0414300 065 A441106 D 0414200 056 A441106 D 0415200 065 A441106 D 0413201 065 A41166 D 0413201 065 A71166 D 0413201 065 A71166 D 0413201 065 A71166 D 04132601 065 A71166 D <th>:</th> <th>: : i</th> <th></th> <th></th> <th>ommand</th> <th>Command Bit Definitions</th> <th>y.</th> <th>Telemetry Verification (MAF/MIF/WRD/BIT)</th> <th>/erification</th>	:	: : i			ommand	Command Bit Definitions	y.	Telemetry Verification (MAF/MIF/WRD/BIT)	/erification
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DR 0433101 0D9 A/3/16/2 DR 0432200 0D2 A/4/16/2 D 0427701 0BF A/1/64/5 D 0427600 0BE A/1/64/5 D 0447701 13F A/8/64/5 DR 0447600 13E A/1/16/5 DR 0434100 0E1 A/1/16/5 DR 0433000 0D8 A+J66/2/16/5 DR 0435201 0EA A+J66/2/16/5 DR 0435600 0EB A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0435600 0EB A/3/16/5 DR 0435600 0E A/3/16/5 DR 0435600 0E A/3/16/5	RMA	RMA YAV	V GYRO 1 & 2 OFF	DR		0434001	0E0		
DR 0432200 0D2 A/4/16/2 D 0427701 0BF A/7/64/5 D 0427600 0BE A/8/64/5 D 0447701 13F A/8/64/5 DR 0447600 13E A/8/64/5 DR 0433000 0E1 A/1/16/5 DR 0433000 0D8 A+J66/2/16/5 DR 0435201 0EA A+J66/2/16/5 DR 0435600 0EB A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0435600 0E A/3/16/5	RMA		/ GYRO 2 ON/1 OFF	DR		0433101	600	A/3/16/2	A/4/16/2
D 0427/01 08F A/7/64/5 D 0447701 13F A/8/64/5 D 0447701 13F A/8/64/5 DR 0447600 13E A/1/16/5 DR 0433000 0D8 A+J66/2/16/5 DR 0435201 0EA A+J66/2/16/5 DR 043500 0DB A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0436101 0F1 A/3/16/5 DR 0435500 0DB A/3/16/5	ADS KMA KMA YAW		SYRO 1 ON/2 OFF	DR		0432200	002	A/4/16/2	A/3/16/2
D 0447701 13F A/8/64/5 DD 0447701 13F A/8/64/5 DR 0433000 0D8 DR 0433000 0D8 DR 0435600 0EE A/3/16/5	A MA	EMA PMA	MARY LOW RAIE ON	0		0427/01	180	A/7/64/5	
D 0447701 13F A/8/64/5 D 0447600 13E A/1/16/5 DR 043300 0DB A/1/16/5 DR 0435201 0EA A+J66/2/16/5 DR 0433300 0DB A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0436101 0F1 A/3/16/5 DR 0436101 0F1 A/3/16/5	NA C	ALA ANA	ANT TIGHT ANTE ON	٥		0427600	OBE		A/7/64/5
D 0447600 13E DR 0434100 0E1 A/1/16/5 DR 0433000 0D8 A+J66/2/16/5 DR 0435201 0EA A+J66/2/16/5 DR 0433300 0DB A/3/16/5 DR 0435600 0EE A/3/16/5 DR 0436101 0F1 A/3/16/5 DR 0433500 0DD A/3/16/5	Y MA	KMA KEU	UNDANI LOW RAIE ON	a		0447701	13F	A/8/64/5	
DR 0434100 0E1 A/1/16/5 DR 0433000 0D8 A+J66/2/16/5 DR 0435201 0EA A+J66/2/16/5 DR 0433300 0DB A+J66/2/16/5 DR 0435600 0EE A/3/16/5 DR 0436101 0F1 A/3/16/5 DR 0433500 0DD A/3/16/5	RMA	RMA RED	UNDANT HIGH RATE ON	٥		0447600	13E		A/8/64/5
DR 0433000 0DB DR 0435201 0EA A+J66/2/16/5 DR 0433300 0DB DR 0435600 0EE A/3/16/5 DR 0436101 0F1 DR 0433500 0DD	MTC	PTC FWD	DISABLE	DR		0434100	0E1	A/1/16/5	
DR 0435201 0EA A+J66/2/16/5 DR 0433300 0DB DR 0435600 0EE A/3/16/5 DR 0436101 0F1 DR 0433500 0DD	MTC	PTC FW	D ENABLE	DR		0433000	8Q0		A/1/16/5
DR 0433300 0DB DR 0435600 0EE A/3/16/5 DR 0436101 0F1 DR 0433500 0DD	MTC	PTC RE	V DISABLE	DR		0435201	0EA	A+J66/2/16/5	
DR 0435600 0EE A/3/16/5 DR 0436101 0F1 DR 0433500 0DD	MTC		V ENABLE	DR		0433300	8 00		A/2/16/5
DR 0433500 0DD 0F1	MTC		ARE DISABLE	DR		0435600	0EE	A/3/16/5	
DR 0433500 0DD	MTC	PTC SPA	RE ENABLE	DR		0436101	0F1		A/3/16/5
	ADS MTC PTC SPA	PTC SPA	RE COIL TO FORWARD MODE	DR		0433500	000		A/4/64/6

		A/1/16/1		A/2/16/1		A/3/16/1	A/4/64/7		A/6/16/0		A/6/16/4		A/5/16/0		A/5/16/4		A/6/64/0	A/5/64/0	A/6/64/1	A/5/64/1	A/6/64/2	A/5/64/2	A/6/64/3	A/5/64/3		A/6/10/4		A/6/10/3		A/6/10/0		A/6/10/1		A/6/10/2		A/6/11/4		A/6/11/3		A/6/11/0		A/6/11/1
A/4/64/6	A/1/16/1		A/2/16/1		A/3/16/1			A/4/64/7		A/6/16/0		A/6/16/4		A/5/16/0		A/5/16/4	A/5/64/0	A/6/64/0	A/5/64/1	A/6/64/1	A/5/64/2	A/6/64/2	A/5/64/3	A/6/64/3	A/6/10/4		A/6/10/3		A/6/10/0		A/6/10/1		A/6/10/2		A/6/11/4		A/6/11/3		A/6/11/0		A/6/11/1	
0E4	ODE	0D7	0E5	0EC	0F3	003	ODC	0E3	000	0EB	၁၁၀	ODF	0F9	0F2	0F4	0FB	0F6	0EF	0F5	0FE	0E8	0E7	0FA	0F0	108	0AE	08D	0A5	089	0A4	040	0AD	104	960	0C4	0CB	0D1	600	OFC	OFF	057	0CA
0434400	0433600	0432700	0434501	0435401	0436300	0432301	0433401	0434301	0430000	0435300	0431400	0433701	0437100	0436201	0436401	0437301	0436600	0435701	0436500	0437601	0435000	0434700	0437200	0436000	0441000	0425601	0421500	0424500	0421101	0424401	0610000	0425501	0440400	0422600	0430401	0431301	0432100	0431100	0437400	0437700	0612700	0431200
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DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	DR	۵	۵	۵	۵	۵	۵	اً ۵	۵	Q	۵	۵	۵		۵	۵	٥	۵	۵
		П	\neg	RYC REV ENABLE	\Box			7					ISOLATION LATCH V			XSTRAP LATCH VAL	Ī	1				XSTRAP LATCH VALVE 3 CLOSE			REA EVEN SYS PWR	REA EVEN SYS PWR					REA EVEN SYS 0.2LB Y ARM	T	T	REA EVEN SYS 5LB ?	REA ODD SYS PWR	REA ODD SYS PWR I	REA ODD SYS C-B H	REA ODD SYS C-B H	REA ODD SYS 0.2LB Y DISARM			
-	\dashv	_		4	-	\dashv		MTC		_		4	_		:	\downarrow	1	_	4	_	_		_	_	4	4	4	+	4	_	REA	4	4	REA	REA	REA	REA	REA	REA	REA	REA	REA
ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	KCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS	RCS
PCSREVR	RYCFDISR	RYCFENAR	RYCRDISR	RYCRENAR	RYCSDISR	RYCSENAR	RYCSFWDR	RYCSREVR	IS12ARMR	IS12DARR	XS34ARMR	XS34DARR	IS12ENAR	IS12DISR	XS34ENAR	XS34DISR	ISO10PNR	ISO1CLSR	ISOZOPNR	ISO2CLSR	XST30PNR	XST3CLSR	XST40PNR	XST4CLSR	EVENENAR	EVENDISR	EVCBHONR	EVCBHOFR	EV2XARMR	EV2XDISR	EVZYAKMK	EVZYDISR	EV5ZARMR	EV5ZDISR	ODDENAR	ODDDISK	ODCBHONR	ODCBHOFR	OD2XARMR	OD2XDISR	ODZYARMR	0D2YDISR
140	141	142	143	144	145	146	147	148	201	202	203	204	205	206	207	208	209	210	211	212	213	214	215	216	217	218	219	220	221	222	223	224	622	226	227	228	229	230	231	232	233	234

	REA ODD SYS 5LB Z /	1 -1.	W	٥٥	၁၁	0431001	9000	A/6/11/2	A/6/11/2
SPUABONR	TT&C	SPU		٥		0423301	960		3
SPUAONR	TT&C	SPU	SPU A PWR ON/SPU B PWR OFF	۵		0427201	0BA		
SPUBONR	TT&C	SPU	SPU A PWR OFF/SPU B PWR ON	O		0426100	081		
SPUACNTR	TT&C	SPU	SPU A IN CONTROL OF I/O	٥		0425700	0AF	A/7/10/4	A/7/11/4
SPUBCNTR	TT&C	SPU	SPU B IN CONTROL OF I/O	۵		0426601	086	A/7/11/4	A/7/10/4
SPUARSTR	TT&C	SPU	SPU A CPU RESET, REBOOT	۵		0426700	087		
SPUBRSTR	TT&C	SPU	SPU B CPU RESET, REBOOT	O		0427500	080		
SPAMNRMR	TT&C	SPU	SPU A MEMORY LO/HI NORM	O		0446001	130		A/7/10/2
SPAMSWPR	TT&C	SPU	SPU A MEMORY HI/LO SWAP	O		0447201	13A	A/7/10/2	
SPBMNRMR	TT&C	SPU	SPU B MEMORY LO/HI NORM	۵		0447101	139		A/7/11/2
SPBMSWPR	TT&C	SPU	SPU B MEMORY HI/LO SWAP	۵		0446501	135	A/7/11/2	
SPABIONR	TT&C	SPU	SPU A 1/0 ON & SPU B 1/0 ON	۵		0447300	138	A/7/10/6	
SPUAIONR	TT&C	SPU	SPU A I/O ON/SPU B I/O OFF	٥		0445501	12D	A/7/10/6	A/7/11/6
SPUBIONR	TT&C	SPU	SPU A I/O OFF/SPU B I/O ON	٥		0446400	134	A/7/11/6	A/7/10/6
SCPUNRMR	TT&C	SPU	SPU CPU I/O NORM			0423400	060 		A/7/10/3
SCPUXSTR	TT&C	SPU	SPU CPU I/O CROSS-STRAP	O		0427000	088	A/7/10/3	
SADAONR	TT&C	SPU	SPU A ADE PWR ON, SPU B ADE OFF	۵		0424600	0.46	A/7/10/3	A/7/11/3
SADBONR	TT&C	SPU	SPU A ADE PWR OFF, SPU B ADE PWR ON	Q		0426400	0B4	A/7/11/3	A/7/10/3
SADOFFR	TT&C	SPU		Q		0423700	99F		A/3/10/3
TIUAONR	TT&C	TIC	TIU A PWR ON/TIU B PWR OFF	O		0436701	0F7		
TIUBONR	TT&C	₽	TIU A PWR OFF/TIU B PWR ON	D		0437501	OFD		
GEDAONR	TT&C	GED	GED A ON	۵		0420601	980	A/7/64/0	
GEDAOFR	TT&C	GED	GED A OFF	۵		0421701	08F		A/7/64/0
GEDBONR	TT&C	GED	GED B ON	۵		0423100	660	A/8/64/1	
GEDBOFR	TT&C	GED	GED B OFF	۵		0425001	0A8		A/8/64/1
LLEDAONR	TT&C	LLED	LLED A ON	۵		0424000	0A0	A/6/64/7	
LLEDAOFR	TT&C	LLED	LLED A OFF	D		0425100	0A9		A/6/64/7
LLEDBONR	TT&C	LLED	LLED B ON	D		0422201	092	A/8/64/4	
LLEDBOFR	TT&C	LLED	LLED B OFF	۵		0421201	08A		A/8/64/4
PCEAONR	TT&C	PCE	PCE-A ON/PCE-B OFF	۵		0447401	13C		
PCEBONR	TT&C	PCE	PCE-A OFF/PCE-B ON	Q		0446301	133		
PCEOFFR	TT&C	PCE	PCE A & B OFF	۵		0445200	12A		
KG10NR	TT&C	KG	KG-46 1 ON/KG-46 2 OFF	DR		0440601	106	A/8/16/5	A/8/16/1
KG2ONR	TT&C	κG	KG-46 2 ON/KG-46 1 OFF	DR		0441500	100	A/8/16/1	A/8/16/5
KGOFFR	TT&C	χ O	KG-46 1 OFF/KG-46 2 OFF	DR		0442300	113	A/8/16/1	
COMIONR	TT&C	SBT	←	DR		0440501	105		A/7/16/2
ATOIONR	TT&C	SBT	S-BAND DOWNLINK 1 ATO MODE	DR		0441701	10F	A/7/16/2	
COMZONR	TT&C	SBT	S-BAND DOWNLINK 2 ON	DR		0441101	109		A/7/16/6
AT020NR	TT&C	SBT	S-BAND DOWNLINK 2 ATO MODE	DR		0442000	110	A/7/16/6	
PRN1ENAR	TT&C	SBT	S-BAND RCVR-1 PRN INHIBIT OFF	DR		0440100	101	A/6/16/3	
PRN1DISR	TT&C	SBT	S-BAND RCVR-1 PRN INHIBIT ON	DR		0442600	116		A/6/16/3

414	BC2BIT2R	EPS	PRU	BCC 2 V/T BIT 2 SET SHIFT	٥		0417201	07A		A/2/11/5
Н	BCC10FFR	EPS	PRU	BCC 1 OFF/BCC B/U ON	O		0415700	06F	A/2/64/5	
-	BCC20FFR	EPS	PRU	BCC 2 OFF/BCC B/U ON	٥		0411201	04A	A/2/64/6	
	CHRGBHIR	EPS	PRU	BCC B/U HIGH RATE ENABLE V/T	٥		0412701	057		A/2/64/1
	CHRGBLOR	EPS	PRU	BCC B/U TRICKLE CHARGE RATE; DISABLE V/T	۵		0412000	050	A/2/64/1	
-	BURSETR	EPS	PRU	BCC B/U V/T BITS/SHFT/DISA RST	۵		0426200	082	A/2/62/2	A/2/64/0
	VTBSHFTR	EPS	PRU	BCC B/U V/T SHIFT TO 16 CELL OPS	۵		0420700	087	A/2/64/4	
	VTBDISR	EPS	PRU	BCC B/U V/T DISABLE CONTROL	۵		0417600	07E	A/2/64/0	
\dashv	BUBIT1R	EPS	PRU	BCC B/U V/T BIT 1 SET SHIFT	۵		0421600	08E		A/2/64/2
\dashv	BUBIT2R	EPS	PRU	BCC B/U V/T BIT 2 SET SHIFT	٥		0422500	095		A/2/64/3
	OCUAENAR	EPS	oco	OCU ENABLE SIDE A	٥	ပ္ပ	0420001	080	A/4/10/4	
\dashv	OCUADISR	EPS	OCO	OCU DISABLE SIDE A	٥		0412401	054		A/4/10/4
	OCUBENAR	EPS	OCO	OCU ENABLE SIDE B	۵	ပ္ပ	0421401	08C	A/4/11/4	
	OCUBDISR	EPS	OCO	OCU DISABLE SIDE B	O		0420100	081		A/4/11/4
	AKMAARMR	EPS	OCO	PRIMARY AKM ARM	O	ပ္ပ	0411000	048		A/4/10/7
_	AKMADISR	EPS	noo	DISARM AKM SIDE A	٥		0413001	850	A4/10/7	
-	AKMFIRAR	EPS	OCO	FIRE AKM SIDE A	D		0413700	05F		
-	AKMBARMR	EPS	OCO	REDUNDANT AKM ARM	۵	ပ္ပ	0410400	044		A/4/11/7
\dashv	AKMBDISR	EPS	OCO	DISARM AKM EED SIDE B	۵		0420501	280	A/4/11/7	
-	AKMFIRBR	EPS	OCO	FIRE AKM SIDE B	۵		0426501	980		
	SAAARMR	EPS	S/A	ARM S/A PYROS SIDE-A	Q	၁၁	0420400	084		A/4/10/5
\dashv	SABARMR	EPS	S/A	ARM S/A PYROS SIDE-B	Q	၁၁	0421000	088		A/4/11/5
	SAADISR	EPS	S/A	DISARM S/A PYROS SIDE-A	۵		0414000	090	A/4/10/5	
+	SABDISR	EPS	S/A	DISARM S/A PYROS SIDE-B	Q		0423001	960	A/4/11/5	
\dashv	SH1ABFAR	EPS	S/A	FIRE S/A SHEAR 1 +/-Y PYROS SIDE-A	۵		0413200	05A		
\dashv	SH1ABFBR	EPS	S/A		۵		0424101	0A1		
-	SHZABFAR	EPS	S/A	FIRE S/A SHEAR 2 +/-Y PYROS SIDE-A	۵		0412300	053		
\dashv	SH2ABFBR	EPS	S/A		۵		0420200	082		
-	SN1ABFAR	EPS	S/A		۵		0417401	07C		
\dashv	SN1ABFBR	EPS	S/A		a		0426301	0B3		
-	SNZABFAR	EPS	S/A	FIRE S/A SNUBBER 2 +/-Y PYROS SIDE-A	۵		0416501	075		
-	SNZABFBR	EPS	S/A	FIRE S/A SNUBBER 2 +/-Y PYROS SIDE-B	۵		0425400	0AC		
+	SN3ABFAR	EPS	S/A	FIRE S/A SNUBBER 3 +/-Y PYROS SIDE-A	۵		0415601	99E		
-	SN3ABFBR	EPS	S/A	+/-Y PYROS	۵		0423501	060		
\dashv	SN4ABFAR	EPS	S/A	+/-Y PYROS	۵		0414701	290		
-	SN4ABFBR	EPS	S/A	FIRE S/A SNUBBER 4 +/-Y PYROS SIDE-B .	۵		0422701	260		
	WAAARMR	EPS	OCO	ARM W-SENSOR PYROS SIDE-A	۵	၁၁	0411401	04C		A/4/10/6
	WABARMR	EPS	OCO	ARM W-SENSOR PYROS SIDE-B	۵	ပ္ပ	0410001	040		A/4/11/6
	WAADISR	EPS	OCO	DISARM W-SENSOR PYROS SIDE-A	O		0612400	054	A/4/10/6	
	WABDISR	EPS	OCO	DISARM W-SENSOR PYROS SIDE-B	۵		0612020	020	A/4/11/6	
	WABTFAR	EPS	OCO	FIRE W-SENSOR LOWER-TIE PYROS SIDE-A	۵		0610300	043		
\dashv	WABTEBR	EPS	OCO	FIRE W-SENSOR UPPER-TIE PYROS SIDE-B	۵		0614620	990		
\dashv	WAETFAR	EPS	OCO	FIRE W-SENSOR LOWER-TIE PYROS SIDE-A	۵		0616220	072		

					A/2/10/7	A/2/10/0		A/2/11/7	A/2/11/0				A/2/16/2	A/2/16/6			A/1/16/2	A/1/16/6			A/5/16/2	A/5/16/6			A/7/41/0		A/7/41/1		A/7/42/1			A/6/41/0		A/6/42/0	A/7/42/0		A/7/41/5	A/7/42/4	A/7/42/4	A/7/41/3	AI714212	A/7/42/2
						A/2/10/7	A/2/10/0		A/2/11/7	A/2/11/0					A/2/16/2	A/2/16/6			A/1/16/2	A/1/16/6			A/5/16/2	A/5/16/6		A/7/41/0		A/7/41/1		A/7/42/1	A/6/41/0		A/6/42/0			A/7/42/0	AJ714214	A/7/41/5	A/7/41/5	A/7/42/2	A/7/41/3	A/7/41/3
05D	051	04C	078	06F	080	077	052	089	07F	059	05E	062	118	10A	111	103	110	10B	114	102	0A2	131	093	138	058	061	062	059	05C	065	092	09B	0A4	0AD	064	058	07C	073	06A	890	07A	071
0613500	0612100	0611400	0617020	0615720	0426001	0416700	0412201	0427101	0417701	0413100	0413601	0414201	0443001	0441201	0442101	0440301	0443501	0441300	0442401	0440200	0424201	0446100	0422300	0447000	0613000	0614100	0614200	0613120	0613420	0614520	0622200	0623300	0624400	0625500	0614400	0613300	0617400	0616300	0615220	0615000	0617200	0616120
																										œ		œ		۳	 					œ						
٥	٥	۵	DR	DR	۵	٥	٥	٥	٥	D	۵	۵	DR	DR	DR	DR	DR	DR	DR	DR	۵	۵	۵	۵	DR	DR	DR	DR	DR	DR	۵	٥	۵	۵	DR	DR	DR	DR	DR	DR	DR	DR
FIRE W-SENSOR LOWER-TIE PYROS SIDE-B		FIRE W-SENSOR INT	FIRE W-SENSOR SPOOL PYROS SIDE-A	FIRE W-SENSOR SPOOL PYROS SIDE-B	+X PNL BATT-2 CELL		+X PNL BATT-2 BYPASS MODE TO CELL SHORT		+X PNL BATT-1 CELL BYPASS	+X PNL BATT-1 BYPA	BATT PRES MON TO CALIBRATE MODE	BATT PRES MON TO	AKM HEATERS HIGH PWR ON	AKM HEATERS LOW PWR ON	AKM HEATERS HIGH	AKM HEATERS LOW PWR OFF	DAMPERS HEATERS SIDE-A ON	DAMPERS HEATERS SIDE-B ON	DAMPERS HEATERS SIDE-A OFF	DAMPERS HEATERS SIDE-B OFF		RWA HEATERS SIDE-B ON	RWA HEATERS SIDE			CAFS 28 VDC OFF	RAFS 1 28 VDC ON		RAFS 2 28 VDC ON		L1 XMIT B ENABLE	L1 XMIT B DISABLE	L2 XMIT B ENABLE	L2 XMIT B DISABLE	CAFS HEATER 28VDC ON	CAFS HEATER 28 VDC OFF						J CTDU RCVR A 28V OFF B OFF
ocn	000	OCO	noo	OCO	BATT	BATT	BATT	BATT	BATT	BATT	BATT	BATT	AKM	AKM	AKM	AKM	DMP	DMP	DMP	dW Q	RWA	RWA	RWA	RWA	AFS	AFS	AFS	AFS	AFS	AFS	ב	-	L2	L2	CAFS	CAFS	CTDU	CTDU	CTDU	CTDU	CTDU	CTDU
EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	EPS	PSS	PSS	PSS	PSS	MSS	MSS	MSS	MSS	MSS	MSS	MSS	MSS	NAV	NAV	NAV	NAV	NAV	NAV	LBS	LBS	LBS	LBS	NAV	NAV	ITS	ITS	ITS	ITS	ITS	ITS
WAETFBR	WAIBFAR	WAIBFBR	WASPFAR	WASPFBR	B2C17ONR	B2C170FR	B2BYPASR	B1C17ONR	B1C170FR	B1BYPASR	BPRSCALR	BPRSNRMR	AKMHHONR	AKMHLONR	AKMHHOFR	AKMHLOFR	DMPHAONR	DMPHBONR	DMPHAOFR	RAPHBOFR	RWAHAONR	RWAHBONR	RWAHAOFR	RWAHBOFR	FREQ30NR	FREQ30FR	FREQ10NR	FREQ10FR	FREQ20NR	FREQ20FR	L1XBENAR	L1XBDISR	L2XBENAR	L2XBDISR	FS3HTONR	FS3HTOFR	IXMTAONR	IXMTBONR	IXMTOFFR	IRCVAONR	IRCVBONR	IRCVOFFR
457	458	459	460	461	462	463	464	465	466	467	468	469	601	602	603	604	605	909	209	809	609	610	611	612	700	701	702	703	704	705	706	707	708	602	710	711	712	713	714	715	716	717

1/12 DC CONV A STRY	I 1/12 DC CONV A STRY
	L1 XMIT A ENABLE
	L1 XMIT A DISABLE
	L2 XMIT A ENABLE
,,,	L2 XMIT A DISABLE
NO	L1/L2 DC CONV B ON
STBY	L1/L2 DC CONV B STBY
HPA NORM	L1/L2 CONV TO L1 HPA NORM
HPA XSTRAP	L1/L2 CONV TO L1 HPA XSTRAP
HPA NORM	L1/L2 CONV TO L2 HPA NORM
HPA XSTRAP	L1/L2 CONV TO L2 HPA XSTRAP
MOD IPA NOF	L1/L2 CONV TO L1 MOD IPA NORM
MOD IPA XST	L1/L2 CONV TO L1 MOD IPA XSTRAP
MOD IPA NORI	L11/L2 CONV TO L2 MOD IPA NORM
MOD IPA XSTR	L1/L2 CONV TO L2 MOD IPA XSTRAP
SYNTH NORM	L1/L2 CONV TO L1 SYNTH NORM
	L1/L2 CONV TO L1 SYNTH XSTRAF
SYNTH NORM	L1/L2 CONV TO L2 SYNTH NORM
SYNTH XSTRAP	12 SY
	L3 CONV A ON
	L3 CONV A STBY
	L3 CONV B ON
	L3 CONV B STBY
A NORM	L3 CONV TO L3 HPA NORM
PA XSTRAP	
	_
NTH XSTRAP	티
	L3 XMTR A ENABLE
mi	L3 XMTR A DISABLE
ON BOFF	L1/L2 CONV A 28 V ON B OFF
ON A OFF	L11/L2 CONV B 28 V ON A OFF
) B OFF	L1/L2 CONV A AND B OFF
N B OFF	L3 CONV A 28 V ON B OFF
N A OFF	L3 CONV B 28 V ON A OFF
OFF	L3 CONV A AND B OFF
II NORM	MDU DC CONV BMI NORM
TO BMI A XSTI	MDU DC CONV B TO BMI A XSTRAP
U MEM XSTRAP	Σ

O
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	A/1/41/0		A/1/42/0		A/1/41/4	A/1/42/4	A/7/41/7	A/7/42/6	A/7/42/6	A/3/16/0	A/4/16/0	A/4/16/0	A/3/16/4	A/4/16/4	A/4/16/4										A///41/2
AJ5/42/1		A/1/41/0		A/1/42/0	A/1/42/4	A/1/41/4	A/7/42/6	A/7/41/7	A/7/41/7	A/4/16/0	A/3/16/0	A/3/16/0	A/4/16/4	A/3/16/4	A/3/16/4									A/7/41/2	
09F	0A0	0A9	0B2	088	085	08E	၁90	07E	075	OED	0F8	0E6	0E2	ODA	0E9	=	127	122	12B	12C	123	120	129	063	05A
0623720	0624020	0625120	0626220	0627320	0620500	0621620	0615420	0617620	0616500	0435500	0437001	0434601	0434200	0433201	0435101	0443601	0444701	0444201	0445301	0445400	0444300	0444000	0445100	0614320	0613220
0	0	٥	٥	٥	O	٥	DR	DR	DR	DR	DR	DR	DR	DR	DR	۵	۵	٥	Q	۵	a	۵	۵	DR	l DR
L3 XMTR B DISABLE	MDU DC CONV A ON	MDU DC CONV A STBY	MDU DC CONV B ON	П	1	MDU DC CONV FSU VCXO XSTRAP	MDU A 28 VDC ON B OFF	MDU B 28 VDC ON A OFF	MDU A AND B OFF	BDP 28 VDC A ON, B OFF	Γ	BDP 28 VDC A	BDW 28 VDC A ON, B OFF	BDW 28 VDC A & B OFF			BDP INITIALIZE 2 (ALT)	BDW LOWBAND ON A (BDW LOWBAND ON B CONVERTER	BDW CONV/ELEC B-A, A-B	BDW CONVIELEC A-A,	BDY A ON, BDY B OFF		RAP 28VDC OFF	
13	MDE	MDO	MDO	MDU	MDO	MDC	MDC	MDC	MDU	809	BDP	BDP	BDP	BDP	BDP	BDP	408	BDP	BDP	BDP	BDP	BDP	BDP	RAP	RAP
1 BS	NAV	NAV	NAV	NAV	NAV	NAV	NAV	NAV	NAV	NDS	SQN	NDS	SQN	NDS	SQN	NDS	SON	SQN	NDS	NDS	NDS	SQN	NDS	RAP	RAP
I 3XBDISR	MDLICVANR	MDUCVASR	MDUCVBNR	MDUCVBSR	FSUNRMR	FSUXSTR	MDUCAONR	MDUCBONR	MDUCOFFR	BDPAONR	BDPOFFR	BDPBONR	WAPWRONR	WPWROFFR	WBPWRONR	BDPINITR	BDPINI2R	BDWAONR	BDWBONR	BDWXSTPR	BDWNRMR	BDYAONR	BDYBONR	RAPOFFR	RAPONR
761	782	783	764	765	766	767	768	769	770	108	802	803	804	805	806	807	808	809	810	811	812	813	814	815	816

REFERENCE

A-1. GPS IIR Orbital Operatons Handbook (OOH), Volume III - Command and Control, G73-OOH-0033B, Martin Marietta Corp. Philadelphia, PA., 13 February 1995.

APPENDIX B GPS IIR MESSAGE COMMAND BY COMMAND NUMBER TABLE

П			CMD Bit Definition	nition		Command	ے	
Mamonic	C/C & Comp	Command/Daramater Description	200	20 Bit	16 Bit	No of	Parameter Bit Field (16	
GROCMDIR	NDS GBD	GRD	2000	3	Š	- वाका	C-104 A A A A A BEREED	CHINGHE
COCCION	000 000	COD MENON CAD		07			U= I UMANANABBBBBBB	
5	TNP MOIL	MOLI SERIAL CMD DATA		3			D=ABBBBBBBBBBBBBBP	
Γ	TNP MDU	MDU PULSE TYPE SMCs						
FINPGCHR	TNP MDU	FINALIZE PROGRAM CHANGE	MDU PUI SE	2304067	CAIR			
CLEARUPR	TNP MDU	CLEAR UPLOAD	MDU PULSE	2310045	C812			
PFALLBKR	TNP MDU	PROGRAM FALLBACK COMMAND	MDU PULSE	2314053	CC15			
PRORSTR	TNP MDU	PROCESSOR RESET	MDU PULSE	2320046	5100			
BBRESETR	TNP MDU	BASEBAND RESET	MDU PULSE	2324050	D414			
HWPULS1R	TNP MDU	SPARE HW PULSE 1	MDU PULSE	2330072	0810			
NEDTESTR	TNP MDU	NED TEST	MDU PULSE	2334064	DC1A			
	TNP MDU	MDU STORED TYPE SMCs	MDU STORED					
B2HSGMR	TNP MDU	HSG MODE SEL BLOCK II-S/W 1	MDUSTORED	2300123	6202			DEFAULT
BZRHSGMR	TNP MDU	HSG MODE SEL BLOCK IIR-S/W 1	MDU STORED	2304135	C42E			DEFAULT
COLDSONR	TNP MDU	COLD START ON-S/W 2	MDU STORED	2300207	500			DEFAULT
COLDSOFR	TNP MDU	COLD START OFF (WARM START)-S/W 2	MDU STORED	2304211	C444			
CLTXENAR	TNP MDU	CLTX ENABLE-S/W 3	MDU STORED	2300410	C084			
CLTXDISR	TNP MDU	CLTX DISABLE-S/W 3	MDU STORED	2304406	288			DEFAULT
L3DATONR	TNP MDU	L3 C/A + DATA ON-H/W 4	MDU STORED	2301025	C10A			
L3CAR	TNP MDU	L3 C/A ONLY-H/W 4	MDU STORED	2305033	CSOD			DEFAULT
AAFSENAR	TNP MDU	AUTONOMOUS AFS SW ENABLE-S/W 5	MDU STORED	2302013	C205			
AAFSDISR	TNP MDU	AUTONOMOUS AFS SW DISABLE-SW 5	MDU STORED	2306005	C602			DEFAULT
SOENAONR	TNP MDU	STATUS QUEUE ENABLE ON-S/W 6	MDU STORED	2300324	5085			
SQENAOFR	TNP MDU	STATUS QUEUE ENABLE OFF-S/W 6	MDU STORED	2304304	C462			DEFAULT
SWSP9ONR	TNP MDU	SOFTWARE SPARE 9 ON-S/W 7	MDUSTORED	2320114	D026			
SWSP90FR	TNP MDU	SOFTWARE SPARE 9 OFF-SW 7	MDUSTORED	2324102	D421			DEFAULT
ASONR	TNP MDU		MDU STORED	2320230	D04C			
ASOFFR	TNP MDU	A-S OFF-S/W 8	MDU STORED	2324226	D44B		100 00 000 000 000 000 000 000 000 000	DEFAULT
DUMPONR	TNP MDU	MEMORY DUMP ON-S/W 9	MDU STORED	2320427	8800			
DUMPOFFR	TNP MDU	MEMORY DUMP OFF-S/W 9	MDU STORED	2324431	P48 C			DEFAULT
MRSTENAR	TNP MDU	MDU RESTART ENABLED S/W 10	MDUSTORED	2321012	D105			
MINIENAR	TNP MDU	MDU INITIALIZATION ENABLED-S/W 10	MDU STORED	2325004	D 2 02			DEFAULT
IDBYPASR	TNP MDU	IDD BYPASS ON-S/W 11	MDU STORED	2322024	D20A			DEFAULT
IDDONR	TNP MDU	IDD BYPASS OFF-S/W 11	MDU STORED	2326032	a 09a			
SWS100NR	TNP MDU	SOFTWARE SPARE 10 ON-SW 12	MDU STORED	2320325	DOGA			
SWS100FR	TNP MDU	SOFTWARE SPARE 10 OFF-SW 12	MDU STORED	2324333	D460			DEFAULT
WDMONENR	TNP MDU	WATCHDOG MON ENABLE ON-HW 13	MDU STORED	2330120	D828			
WDWONDIR	TNP MDU	WATCHDOG MON DISABLE OFF-HWV 13	MDUSTORED	2334136	DC2F			DEFAULT
HWSPZONK	DOM dN I	HARDWARE SPARE 2 ON-HW 14	MDUSIORED	2330204	D842			
HWSP2OFR	TNP MDU	HARDWARE SPARE 2 OFF-HW 14	MDU STORED	2334212	DC45			DEFAULT
HWSP10NR	TNP MDU	HARDWARE SPARE 1 ON-HW 15	MDU STORED	2330413	D885			
HWSP10FR	TNP MDU	HARDWARE SPARE 1 OFF-HW 15	MDU STORED	2334405	22 22 23			DEFAULT
L2BONR	TNP MDU	L2 SEL B ON-H/W 16	MDU STORED	2331026	B060			DEFAULT
L2BOFFR	TNP MDU	9	MDU STORED	2335030				
L2AONR	TNP MDU	L2 SEL A ON-H/W 17	MDUSTORED	2332010	DAOA			DEFAULT
L2AOFFR	TNP MDU	L2 SEL A OFF-HW 17	MDU STORED	2336006	DECC			
PORTEONR	TNP MDU	PORT ERROR RESET ENABLED-HW 18	MDUSTORED	2330311	D864			
PORTEOFR	TNP MDU	PORT ERROR RESET INHIBITED-HW 18	MDU STORED	2334307	සාය			DEFAULT
SWS30NR	TNP MDU	SOFTWARE SPARE 3 ON-S/W 19	MDU STORED	2310117	C827			
SWS30FFR	TNP MDU	SOFTWARE SPARE 3 OFF-SW 19	MDU STORED	2314101	CC20			DEFAULT

	DEFAULT		DEFAULT		DEFAULT		DEFAULT		DEFAULT																																						DEFAULT			XX=00 OFF DEFAULT	XXXXX=00000 DEFAULT (ALL OFF)
																																																	D=0pP	D=00XXpP	D=00XXXXXpP
CBAD	CC4A	C88A	CCSD	C904	CDCC	CAOB	CEOC	C86B	၁૭၁၁		E011	E024	E037	EOVE	E05D	E068	E07B	6083	E09A	EOAF	EOBC	EOCS	EODG	E0E3	EOFO	E107	E114	E121	E132	E14B	E158	E16D	E17E	E18C	E19F	E1AA	E1B9	E100	E1D3	E1E6	E1F5	E208	E21B	E22E	E23D	E244	E257				
2310233	2314225	2310424	2314432	2311011	2315007	2312027	2316031	2310326	2314330		2340043	2340111	2340156	2340235	2340272	2340320	2340367	2340422	2340465	2340537	2340570	2340613	2340654	2340706	2340741	2341017	2341050	2341102	2341145	2341226	2341261	2341333	2341374	2341431	2341476	2341524	2341563	2341600	2341647	2341715	2341752	2342021	2342066	2342134	2342173	2342210	2342257		270000D	207020D	2704D
MILISTOBED	MDU STORED	MDU STORED	MDU STORED	MDU STORED	MDU STORED	MDU STORED	MDUSTORED	MDUSTORED	MDU STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	MDU SVID STORED	\neg		MDU S/W & CTDU	MDU SAW & CTDU
SOFTWARE SPARE 4 ON-SAN 20	SOFTWARE SPARE 4 OFF-S/W 20	SOFTWARE SPARE 5 ON-S/W 21	SOFTWARE SPARE 5 OFF-S/W 21	SOFTWARE SPARE 6 ON-S/W 22	SOFTWARE SPARE 6 OFF-S/W 22	SOFTWARE SPARE 7 ON-S/W 23	SOFTWARE SPARE 7 OFF-SW 23	SOFTWARE SPARE 8 ON-S/W 24	SOFTWARE SPARE 8 OFF-S/W 24	MDU SVID STORED TYPE SMCs	SVID 01	SVID 02	SVID 03	SVID 04	SVID 05	SVID 06	SVID 07	SVID 08	80 QI/XS	SVID 10	SVID 11	SVID 12	SVID 13	SVID 14	SVID 15	SVID 16	SVID 17	SVID 18	SVID 19	SVID 20	SVID 21	SVID 22	SVID 23	SVID 24	SVID 25	SVID 26	SVID 27	SVID 28	SVID 29	SVID 30	SVID 31	SVID 32	SVID 33	SVID 34	SVID 35		SVID 37	MDU S/W AND CTDU TYPE SMCs	SPARE COMMAND	SEL L3 XMIT MODE	SEL XMIT SLOT
TNP MDI	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU
SWSAONR	SWS40FFR	SWS5ONR	SWS5OFFR	SWSBONR	SWS6OFFR	SWS70NR	SWS70FFR	SWS8ONR	SWS80FFR		SVID01R	SVID02R	SVID03R	SVIDO4R	SVIDO5R	SVIDOGR	SVID07R	SVIDOBR	SVID09R	SVID10R	SVID11R	SVID12R	SVID13E	SVID14R	SVID15R	SVID16R	SVID17R	SVID18R	SVID19R	SVID20R	SVID21R	SVID22R	SVID23R	SVID24R	SVID25R	SVID26R	SVID27R	SVID28R	SVID29R	SVID30R	SVID31R	SVID32R	SVID33R	SVID34R	SVID35R	SVID36R	SVID37R		SWCMDSPR	L3XMTMDR	ITXSMITR
07339	07340	07341	07342	07343	07344	07345	07346	07347	07348	00520	07501	07502	07503	07504	07505	07506	07507	07508	07509	01570	07511	07512	07513	07514	07515	07516	07517	07518	07519	07520	07521	07522	07523	07524	07525	07526	07527	07528	07529	07530	07531	07532	07533	07534	07535	07536	07537		07701	07702	07703

1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	XXXXXXXX=0000000 DEFAULI (ALL OFF)	XXXXXXXX=00000000 DEFAULT (ALL OFF)	XXXXXXXX=00000000 DEFAULT (ALL OFF)	XXXXX=11111 DEFAULT (16)	SEE COMMANDS 07722-07725	L=0, AA=00 DEFAULT	XXX=000 (15 MIN) DEFAULT		XX=00, YY=00 DEFAULT	X=0 (OFF) DEFAULT	X=0 (OFF) DEFAULT	X=1 (ON) DEFAULT	WWW. DELYCLI	XXXXXXXX=UUUUUU DEFAULI	XXXXXXXX=UUUUUU DEFAULI	XXXXXXX=UUUUUU DEFAULI	XXXXXXX=0000011 (3)	(2)				EXTENSION OF CMD 07720								THE TILL REQUIRES ONLY ONE	COMMAND TO FOLLOW THE					SEE FIGURE 20-1 FOR 12 BIT	DUMP ADDRESSES	DUMP ADDRESSES	SEE FIGURE 20-1 FOR 12 BIT	OIMIT AUCKESSES	SEE FIGURE 20-1 FOR 12 BIT DUMP ADDRESSES	SEE TABLE 20-2 FOR 12 BIT	DWELL ADDRESSES	DWELL ADDRESSES
22.5	D=11XXXXXXXXXpP (AL	XX D=01XXXXXXXXΦP (AL	XX XXXXXXXP D=01XXXXXXXX				D=0XXXpP XX		YpP			D=XpP					N		D=01XXXXXpP	D=10XXXXXpP			D=XXXXX00000000		D=XXXXXXX000P		D=XXXXXX000P	D=XXXXXXXXXXI	DEXXXXXX		8 6						D dxxxxxxxxxx	IO AXXXXXXXXX			D=XXXXXXXXXXXXP DI		D=XXXXXXXXXXP D	D=XXXXXXXXXXXXP
	270D	271D	271D	2714D		27200D	27220D	2724002	27260D	273000D	273200D	273400D	2/30	2/4D	2/4D	2/4D	275D	2716D	2716D	2716D	2716D	2746050 E614	27D		122D	123D	125D	1260	1300		24	300001	340000	2000000	2400001		31D	350		210	25D		320	36D
	MDU S/W & CTDU	MDU SAW & CTDU	MDU S/W & CTDU	MDU S/W & CTDU	MDU S/W & CTDU	MDU S/W & CTDU	-	-			_	-+	MDU S/W & CIDU	MDU S/W & CIDU	MDU S/W & C1DU	MDU SWW & CIDU	MOLOS/W & CLOO	MOLISAN & CTOL	MDU S/W & CTDU	MDU S/W & CTDU	MDU S/W & CTDU	MDU S/W & CTDU	MDU S/W & CTDU																					
	SEL ACTIVE RCV SLOTS (0-7)	SEL ACTIVE RCV SLOTS (8-15)	SEL ACTIVE RCV SLOTS (16.23)	SEL NEXT WORD	NOT USED SEE-COMMANDS 07722-07725	NAVIGATION MODE CONTROL	SEL AUTONAV RNGE INTERVAL	REQUEST SMC STATUS TLM	COMSEC CONFIGURATION	RTO MODE	RAP MODE	NON-STANDARD CODE (NSC)	COMMANDED DOMP STAKT PAGE	COMMANDED DUMP START WORD	COMMANDED DIAG START PAGE	COMMANDED DIAG END PAGE	DOST EDSOB TUBERLOS	HODDING EREC.NORMAL MODE	HOPPING FRED-BER TEST MODE	FIXED FREQ-NORMAL MODE	FIXED FREQ-BER TEST MODE	INITIALIZE MEMORY BETWEEN LIMITS	SPARE COMMANDS 21-31	RAP SERIAL CMD DATA	MDU SMC PRECURSOR	RAP SMC PRECURSOR	BDP SMC PRECURSOR	BDW SMC PRECURSOR	SPU-A SMC PRECURSOR			TILI NORMAI MODE-FORMAT 1-LOW RATE	TILL NORMAL MODE-FORMAT 2-1 OW RATE	TIU NORMAL MODE-FORMAT 1-HIGH RATE	TIU NORMAL MODE-FORMAT 2-HIGH RATE		TIU DUMP MODE-FORMAT 1-LOW RATE	TILL DI IMP MODE, FORMAT 2-1 OW RATE		TIU DUMP MODE-FORMAL I-HIGH KALE	TIU DUMP MODE-FORMAT 2-HIGH RATE		TIU DWELL MODE-FORMAT 1-LOW RATE	TIU DWELL MODE-FORMAT 2-LOW RATE
	TNP MDU	TNP MDU	DOM GNT	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	TNP MDU	DOM JAN	TNP MDU	TNP MDU	TNP MDU		TNEWDO	TNP MOL	TNP MDU	TNP MDU	TNP MDU	TNP MDU	RAP RAP	TACCDU	TT&C CDU	TACCDU	TRCCDU		200		118C 111	TRO TIL	TT&C TIU	TT&C TIU		TT&C TIU	TIR CALL	2	TI&C TIU	TT&C TIU		TT&C TIU	TT&C TIU
	IRCVLOWR	IRCVMEDR	IRCVHIR	NEXTWODR		NAVMCTLR	ANAVINTR	REACTDUR	MCOMSECR	RTOCMDR	RAPCMDR	NSCCODER	UMPSIPG	DMPSTWRD	DIAGSTPG	DIAGENPG	UNGRUSI	NOPHODE	BERHOPR	INORMODR	IBERMODR	MEMINITR			MDUPRER	RAPPRER	GBDPPRER	GBDWPRER	SPUAPRER	אומטופ	i i	TNORM11 R	TINDRADIR	TNORMIHR	TNORM2HR		TDMP1LR	d Kaylor		TDMP1HR	TDMP2HR		TDWL1LR	TDWL2LR
	07704	07705	07706	+	07708	60770	077710	07711	07712	07713	07714	07715	1	+	077718	077719	07//0	17//0	07703	07774	07725	07726	07727	00080	00060	03150	00260	09450	0360	36/60	0000	3000	20000	06603	40660		9060	90000	20000	20660	80660		60660	09910

SEE TABLE 20-2 FOR 12 BIT D=XXXXXXXXXXXXXXX DWELL ADDRESSES	D=XXXXXXXXXXXX DEXXXXXXXXXXXXXXXXXXXXXXX																						OCCUPATION OF COLUMN	C-123 16-BIL DALA WORUS																						
D=XXXXXX	XXXXXX																																													
		-	-	-		-		2		4					3				,	4				1	Λ .					9							4					8				
		0	000	3	0101	0102		0103		0104					0105				0108	0200					020					0202						0203	0300					9301			0300	7000
Z2D	36D	2400001	2401000	2000	2401003	2401005		2401006		2401011					2401012				2401014	2402000					2402003					2402005						2402006	2403001					2403002			2403004	Z#05557
		CMDX	CMDX	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RBOOT	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD	RLOAD DAD	RICAN	RLOAD	RLOAD	RLOAD	RDUMP	RDUMP	RDUMP	RDUMP	RDUMP	RDUMP	RDUMP	ROUMP	KDOMP	NOOWIL
TIU DWELL MODE-FORMAT 1-HIGH RATE	TIU DWELL MODE-FORMAT 2-HIGH RATE	CDU COMMAND OPCODE	16 BIT CDU COMMAND TPANSEED (PAM ADDRESS)	LOGICAL ADDRESS	GO (EXECUTE CMDS)	READ I/O PORT	I/O PORT (ID OF PORT TO READ)	WRITE I/O PORT	I/O PORT (ID OF PORT TO WRITE)	INFORMATION (DATA TO I/O PORT) CHECKSUM OF RAM	UPPER RAM ADDRESS (16 BITS)	LOWER RAM ADDRESS (16 BITS)	UPPER RAM RANGE (16 BITS)	LOWER RAM RANGE (16 BITS)	CHECKSUM OF ROM	ROM ADDRESS	UPPER ROM RANGE (16 BITS)	LOWER ROM RANGE (16 BITS)	NOOP (NO OPERATION)	UPLINKED MEMORY LOAD	UPPER RAM ADDRESS (16 BITS)	LOWER RAM ADDRESS (16 BITS)	RAM RANGE	DATA	LOAD ROM TO RAM ROM ADDRESS	UPPER ROM RANGE (16 BITS)	LOWER ROM RANGE (16 BITS)	UPPER RAM ADDRESS (16 BITS)	LOWER RAM ADDRESS (16 BITS)	LOAD RAM TO RAM	UPPER RAM START (16 BITS)	LOWER RAM START (16 BITS)	OFFER RAW KANGE (19 BILS)	LIPPER RAM DEST (16 BITS)	LOWER RAM DEST. (16 BITS)	ZERO UPPER MEMORY	DUMP RAM DATA	UPPER RAM ADDRESS (16 BITS)	LOWER RAM ADDRESS (16 BITS)	UPPER RAM RANGE (16 BITS)	LOWER RAM RANGE (16 BITS)	DUMP ROM DATA	ROM ADDRESS	UPPER ROM RANGE (16 BITS)	LOWER ROM RANGE (16 BITS)	DUMP SPU ERROR BUFFER
TT&C TIU	TT&C TIU	TT&CSPU	TT&C SPU	TRCSPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TACSPU	TT&CSPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TIRCSPU	TINC SPU	TRUST	TT&C SPU	TRCSPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TISCSPU	TT&C SPU
TDWL1HR	TOWI 2HR	CDUCMDOR	VERBANDE	N CONT	EXECCMDR	READIOPR		WRITIOPR		BAMCHKSR					ROMCHKSR				NOOPCMDR	LDMEMRBR					ROMRAMLR					RAMRAMLR						ZEROMEMR	RAMDUMPR					ROMDUMPR				SEBFDMPR
1,000	70017	10000	10000A	10100A	10101	10102	10102A	10103	10103A	10103B	10104A	10104B	10104C	10104D	10105	10105A	10105B	10105C	10106	10200	10200A	10200B	10200C	10200D	10201	102018	10201C	10201D	10201E	10202	10202A	10202B	102020	102020	10202E	10203	10300	10300A	103008	103000	10300D	10301	10301A	10301B	103010	10302

																					0-123 16-BIT DATA WORDS																					3-30 MACR WORDS								
-								2									4					က				4			:			•	4				-	-	3				1		-			က	+	
0200		0501	0502	0503	0504	92 202	920	0507			8030	0090	0801	080	00/00	0701	1000					1100				1101			:		1102	1103	1104				1105	3	1300				1301		1302		1303	- 28		
2405001		2405002	2405004	2405007	2405010	2405013	2405015	2405016			2405020	2406001	2406002	2406004	2407000	2407003	2420000					2421001				2421002					2421004	2421007	2421010				2424043	2121212	2423000				2423003		2423005		2423006	2423011		
MODES	MODES	MODES	MODES	MODES	MODES	MODES	MODES	MODES	MODES	MODES	MODES	ERRORS	ERRORS	ERRORS	MEMCHK	MEMCHK	UPLINK	UPLINK	UPLINK	UPLINK	UPLINK	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUTLM	SPUILM	O O CILINI	SPUILM	OPICIEM OPICIEM	SPITIM	SPUTLM	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD	STCMD
SELECT MODE	MODE	SET GRND MODE SW FLAG TRUE	SET GRND MODE SW FLAG FALSE	SET AUTON MODE SW FLAG TRUE	SET AUTON MODE SW FLAG FALSE	ENABLE MOMENTUM MANAGEMENT	DISABLE MOMENTUM MANAGEMENT	COMMAND RMA ON/OFF	PARAMETER 1	PARAMETER 2	ALL RMA OFF	DUMP ADA ERROR BUFFER	DUMP INTERRUPT ERROR BUFFER	DUMP SINGLE BIT ERROR BUFFER	ENABLE MEMORY CHECKING	DISABLE MEMORY CHECKING	MEMORY LOAD	UPPER START ADDRESS (16 BITS)	LOWER START ADDRESS (16 BITS)	RANGE	DATA	SPU TLM TABLE LOAD	TABLE NUMBER	TABLE RANGE	ELEMENTS TO LOAD	INITIALIZE MEMORY DUMP	UPPER DUMP ADDRESS (16 BITS)	LOWER DUMP ADDRESS (16 BITS)	UPPER DUMP RANGE (16 BITS)	LOWER DUMP RANGE (16 BITS)	INITIALIZE DUMP PREV MEM LOAD	PERFORM CHECKSUM PREV MEM LOAD	INITIALIZE CHECKSUM	OFFER DALF ADDRESS (19 DILS)	LOWER HALF AUDRESS (16 BILS)	OFFER HALF KANGE (16 BILS)	COVER HALF KANGE (10 DILS)	TIMMODE	UPLOAD A MACRO	MACROID	MACROSIZE	MACRO WORDS	DELETE A MACRO	MACRO ID	DUMP RANGE OF MACROS	MACRO ID AND NUMBER	ABORT ALL MACROS	START A MACRO	MACRO ID	UPPER START TIME LOWER START TIME
TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&C SPU	TRCSPU	1180.070	T &C SPO	S C S P C	T & C OP O	TI&C SPU	TT&CSPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&CSPU	TT&C SPU	TT&C SPU	TI&C SPU
MODESWTR	\vdash	GNDMSFTR	GNDMSFFR	-	H	_	~	RMA-ONR			RMA-OFFR	DPADERBF	DPINERBF	DPSBERBF	MEMCKENR	MEMCKDIR	LDSPMEMR					LDSPTABR				SPUDUMPR					DMPLSTLR	CHKLSTLR	SPUCHKSR					MIDSLIMIN	I DMACROR				DLETMACR		DUMPMACR		ABTAMACR	STRTMACR		
10500		10501	10502	10503	10504	10505	10506	10507	10507A	10507B	10508	10600	10801	10602	10700	10701	11000	11000A	11000B	10000	11000D	11180	11100A	11100B	11100C	11101	11101A	11101B	11101C	111010	11102	11103	1104	X X X X X X X X X X	111048	200	- 10g	111054	1130	11300A	113008	11300C	11301	11301A	11302	11302A	11303	11304	11304A	11304G

-						2					-		7		2			-		2			7			83										-			
1305		1500	1501	1600	1801	1700			1701		1702		1/03		4704			1705		2400		1000	1047		00.0	2402													
2423012		2425000	2425003	2426000	2426003	2427001			2427002		2427004	-	742/00/		2427010			2427013		2444001		000777	2444002			2444004													
STCMD	STCMD	CVSTORE	CVSTORE	ATTMON	ATTMON	SPM	SPM	SPM	MdS	SPM	SPM	SPM	M C	SPM	SPM	SPM	SPM	SPM	SPM	EPHSUP	EPHSUP	FFHSOP	EPHSOF	EPHSUP	EPHSOF	EPHSUP	EPHSUP	EPHSUP	EPHSUP	dilSHdi		EPHSOP	EPHSUP	EPHSUP	EPHSUP	EPHSUP	EPHSUP	EPHSUP	EPHSUP
ABORT A MACRO	MACRO ID	DUMP CVF QUEUE	DUMP CVF ERROR QUEUE	ATTMON ON	ATTMON OFF	SET AVG SPIN PERIOD	SPIN PERIOD UPPER HALF	SPIN PERIOD LOWER HALF	SET NUMBER OF REMAINING PULSE PAIRS	PULSE PAIRS	SET SPM THRUSTER SELECTION	THRUSTER SELECTION	SEL SPIN FRAC OF SPIN PERIOD	SPIN PER FRAC LOWER HALF	SET CEP FIRST PULSE DELAY	PULSE DELAY UPPER HALF	PULSE DELAY LOWER HALF	SPM STATE CHANGE	SPMSTATE	INCREMENT Z-TIME	UPPER HALF Z-TIME (16 BITS)	LOWER HALF Z-IME (16 BILS)	NEVV Z-1 IME	OPPER HALF 2-1 IME (16 BILS)	LOVVER HALF 2-11ME (16 BILS)	LOAD BACKUP EPHEMERIS	COEFFICIENT REFERENCE TIME UPPER (16 BITS)	COEFFICIENT REFERENCE TIME LOWER (16 BITS)	BU EPHEM INCLINATION 1 UPPER	B I COM TOTAL INC.		BU EPHEM INCLINATION 1 LOWER	BU EPHEM INCLINATION 2 UPPER	BU EPHEM INCLINATION 2 MIDDLE	BU EPHEM INCLINATION 2 LOWER	BU EPHEM INCLINATION 3 UPPER	BU FPHEM INC. INATION 3 MIDDLE	BU EPHEM INCLINATION 3 LOWER	TT&C SPU BU EPHEM INCLINATION 4 UPPER
TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	T SC OFC	T&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TIRCSPU	TACSPU	TT&C SPU	I &C SPU	S C C C C C C C C C C C C C C C C C C C	Tec SPU	I &C SPU	IT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPIT		I &C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU
ABT-MACR		DMPCVFQR	DMPCVFER	-	Н	AVGSPNPR			NBRPPRSR		SSPMPPR	COTOT	TCI OFNER		CEPIDELR			SPMSTCGR		INCZTIMR		C. C	NEVVZ I IMIK			LDBUEPHR							:						
11305	11305A	11500	11501	11600	11601	11700	11700A	11700B	11701	11701A	11702	11702A	11703	117038	11704	11704A	11704B	1705	11705A	12400	12400A	124008	12401	12401A	B1067	12402	12402P 01	12402P 02	12402P 03	12402P	12402P	3/07	90	12402P 07	12402P 08	12402P 09	12402P	12402P 11	12402P 12

12402P 13		TT&C SPU	BU EPHEM INCLINATION 4 MIDDLE	EPHSUP				
12402P 14		TT&C SPU	BU EPHEM INCLINATION 4 LOWER	EPHSUP				
12402P 15		TT&C SPU	BU EPHEM INCLINATION 5 UPPER	EPHSUP				
12402P 16		TT&C SPU	BU EPHEM INCLINATION 5 MIDDLE	EPHSUP				
12402P 17		TT&C SPU	BU EPHEM INCLINATION 5 LOWER	EPHSUP				
12402P 18		TT&C SPU	BU EPHEM INCLINATION 6 UPPER	EPHSUP				
12402P 19		TT&C SPU		EPHSUP				
12402P 20		TT&C SPU	BU EPHEM INCLINATION 6 LOWER	EPHSUP	:	:		† !
12402P 21		TT&C SPU	BU EPHEM RIGHT ASCENSION 1 UPPER	EPHSUP				
12402P 22		TT&C SPU	BU EPHEM RIGHT ASCENSION 1 MIDDLE	EPHSUP				
12402P 23		TT&C SPU	TT&C SPU BU EPHEM RIGHT ASCENSION 1 LOWER	EPHSUP				
12402P 24		TT&C SPU	BU EPHEM RIGHT ASCENSION 2 UPPER	EPHSUP				
12402P 25		TT&C SPU	BU EPHEM RIGHT ASCENSION 2 MIDDLE	EPHSUP				
12402P 26		TT&C SPU	BU EPHEM RIGHT ASCENSION 2 LOWER	EPHSUP				
12402P 27		TT&C SPU		EPHSUP				
12402P 28		TT&C SPU	BU EPHEM RIGHT ASCENSION 3 MIDDLE	EPHSUP)
12402P 29		TT&C SPU	BU EPHEM RIGHT ASCENSION 3 LOWER	EPHSUP				
12402P 30		TT&C SPU	BU EPHEM RIGHT ASCENSION 4 UPPER	EPHSUP				
12402P 31		TT&C SPU	BU EPHEM RIGHT ASCENSION 4 MIDDLE	EPHSUP				
12402P 32		TT&C SPU	BU EPHEM RIGHT ASCENSION 4 LOWER	EPHSUP				
12402P 33		TT&C SPU	BU EPHEM RIGHT ASCENSION 5 UPPER	EPHSUP				
12402P 35		TT&C SPU	BU EPHEM RIGHT ASCENSION 5 MIDDLE	EPHSUP				
12402P 36		TT&C SPU	BU EPHEM RIGHT ASCENSION 5 LOWER	EPHSUP				
12402P 37				EPHSUP	1			:
12402P 38		TT&C SPU	BU EPHEM RIGHT ASCENSION 6 MIDDLE	EPHSUP				
12402P 39				EPHSUP				
12403	DMPBEPHR	TT&CSPU	DUMP BACKUP EPHEMERIS	EPHSUP	2444007	2403		

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						2			,							1		2			_						2	:	2			2							2	-					4			
2404	2405	2900	2901	3201	3202	3203		3300	3				3307	3500		3501		3700			3701		3800	3801	4100	4101	4102	:	4103			4104			4105	4102	410/	2008	3				8001	8002	8003			
2444010					4	2462006		2463001	1			4	2463002	1	<u> </u>	2465001	_	2467000		_	2467003	4	_	1	1	4	2501004	•	2501007	-		2501010		4	1	2501015	4	+	+				2600003	_	2600006			
EPHSUP	•						TUBCEL			101	101		<u> </u>						PSMON			_						ROMGI					RDMGT				KUMICI	MAN	T	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN
CHANGE TO BACKUP EPHEMERIS	CHANGE FROM BACKUP EPHEMERIS	ENABLE ESA RAD BIAS	DISABLE ESA RAD BIAS	ENABLE SK SNP ARRAY SLEW FLAG	DISABLE SK SNP ARRAY SLEW FLAG	THRUSTER CONFIGURATION	THRUSTER FOLION	SET CMDED PW FOR EACH THRUSTER	THEFIELD SEI ECTION	RIBNTIME LIDDER HALF	BUDNITIME OF CANED LAY E	DONIN IIME LOVVEN MALF	STOP TPF	SELACTUATOR	ACTUATOR	SEL MOMENTUM UNLOADING ACTUATOR	UNLOAD ACTUATOR	ENABLE/DISABLE SPECIFIED CAPABILITY	CAPABILITY	CAPABILITY STATUS	AMP HOUR DISCHARGE (AHD) SELECTION	AHD SELECTION	ENABLE LOAD SHEDDING	DISABLE LOAD SHEDDING	ENABLE KEUMAN	DISABLE REDMAN	SEI REDMAN HEALTH STATUS MATRIX	COMPONENT SET DESIRED COMPONENT STATE	UPDATE REDMAN SWITCHING FLAGS	DEVICE	DEVICE STATUS	UPDATE TESTING FLAGS	TEST FLAGS	IEST FLAG STATUS	DUMP HEALIH MAIRIX	DUMP DEVICE FAILURE LOG	DOMP DEVICE SWITCHING LOG	SETTION OF EVALUATION	STAPTING ADDRESS OF DATCH	CONNECTION	SIZE OF PATCH CONNECTION	PATCH CONNECTION CODE	DISCONNECT PATCH	READJUST PAGE REGISTERS	CHANGE PAGE REGISTERS	ADDRESS STATE	TYPE OF PAGE REGISTER	PAGE CONTENTS
TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	II&C SPU	TION CALL	TRCSPU	TIAN CALL	TIRC SPIT	100 787	2000	T & C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TI&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	I &C SPU	TT&C SPU	TIRCSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TIRCSPU	TIRCSPU	II&C SPU	T &C SPO	T & C & P U	TI&C STO	0 0 0 0	TT&CSPU	TT&CSPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU
BEPHENAR	BEPHDISR	ESARBENR	ESARBUIR	SNPFENAR	SNPFDISR	THRICNFR		TCMDPWDR				0.101.010	STOPTPER	SELACTR		SELUNLDR		PSMONCFR			SELAHDR		LDSHDENR	LDSHDDIR	KUMNENAK	RDMNDISR	SRMCMATR		UPRMSWFR			UPRMTSFR			DMPRMHMR	UMPRMDFK	UMPRMUSK	+	+				PCHDISCR	PCHPGADR	CHGPAGER			
12404	12405	12900	12901	13201	13202	13203	132034	+	+	13300	133000	333	1330	13500	13500A	13501		-	13700A	13700B	13701	13701A	13800	13801	14100	14101	14102	14102A	+	1_	14103B	14104	14104A	_	+	+	+	2000	+	18000A	180008	1800C	18001	18002	18003	18003A	18003B	18003C

	8										3
	2600011 8004										2000
PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN		PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	PATCH MAN	INVENTION OF ACT
TT&C SPU PAGE NUMBER	TT&C SPU PATCH IFTEST/SELTS	T&C SPU CMX IFTEST ADDRESS	TT&C SPU CMX SELTS ADDRESS	RECEIVE CONTROL CONNECTION	TT&C SPU ADDRESS	IT&C SPU RECEIVE CONTROL SIZE	TT&C SPU SEND CONTROL CONNECTION ADDRESS	T&C SPU SEND CONTROL SIZE	T&C SPU RECEIVE CONTROL CONNECTION CODE	T&C SPU SEND CONTROL CONNECTION CODE	TTAC COLL DISCONNIECT ICTECTICEL TO DATCH
TT&C SPU	TT&C SPU	TT&CSPU	TACSPU		TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	TT&C SPU	IIOS CALL
	PCHIFTSR										avultura
18003D	18004	18004A	18004B		18004C	18004D	18004E	18004F	18004G	18004H	18005

REFERENCE

B-1. GPS IIR Orbital Operatons Handbook (OOH), Volume III - Command and Control, G73-OOH-0033B, Martin Marietta Corp. Philadelphia, PA., 13 February 1995.

APPENDIX C GPS IIR TELEMETRY BY WORD TABLE

Memorie Memo																				:																	
Mithemorie		Comments					Power Flag Word	Power Flag Word	Power Flag Word	Power Flag Word	6								,						Power Flag Word	Power Flag Word	Power Flag Word	Davier Flag \0/000	י איפו י ומא ייטות							Zero-filled in Format	Zero-filled in Format
Minemonie		Conversion Data					0=Not in Deadband	0=Not in Deadband	0=Not in Deadband	0=Not in Deadband																											
Minemonie		Units	Celsius	Celsius	Ceisius		į				radians	radians	radians	radians	radians	radians	radians	radians	radians	radians	radians	radians	radians	Celsius					radians	radians	radians	radiane	radians	radians	radians	Celsius	Celsius
Minemonic LITOC		Mode Post Post Post Post Post Post Post Post	All Power-Up	All Power-Up	All Posses Lin	All Power-Up	Normal	Normal	Normal Thruster	Normal Thruster	Normal	Normal	Thruster	I hruster Nermal	Normal	Thruster	Thruster	Normal	Normai	Thruster	Normal	Normal	Thruster	All Power-Up	Normal Thruster	Normal Thruster	Normal Thruster	Normal	Normal	Normal	Thruster	Normal	Normal	Thruster	Thruster	All Power-Up	All Power-Up
Minemonic LIOC		T Ape	Ą	₽ 5	₹ 2	5 2	S	S	ဟ	v	S	ဟ	တ	טמ	ာ ဟ	S	S	S	2)	າ ທ	S	ဟ	S	γ	ဟ	ဟ	v	U,	S	S	טמ	ט	S	S	S	A de	. ₽
Minemonic Minemonic		Comp	TCS	27.	3	SAD	SPUA	SPUB	SPUA	SPUB	SPUA	SPUA	SPUA	SPUA alia	SPUB	SPUB	SPUB	SPUA	SPUA	SPUA	SPUB	SPUB	SPUB	SAD	SPUA	SPUB	SPUA	SPILB	SPUA	SPUA	SPUA PIGO	SPIIR	SPUB	SPUB	SPUB	Als VIS	S/A
S 0 a Display LTDC TLM Des 7 8 4.4.YACCT PXYACCT +X-YACCT PXYACCT +X-YACCESS PNI 7 8 4.X-YACCT PXYACACT +X-YACCT +X-YACTA +X-YAC		s/s	MSS	SSW	<u>8</u>	2 8	TI&C	787	18C		ADS	ADS	SQ.	S S	ADS	ADS	ADS	ADS.	3	§ §	ADS	ADS	ADS.	§ 83	TRC	7% T	11&C	T&C	ADS	ADS.	200	ADS	ADS	ADS	ADS.	7 E	EPS
S 0 a Display LTCC 7 8 +X+YACCT PXMYACCT 7 8 +X-YACCT PXMYACCT 7 8 +X-YACCT PXMYACCT 7 8 +X-YACCT PXMYACCT 7 8 +X-YACCT PXMYACCT 7 8 +X-YACVLT PXMYACCT 7 8 +X-YACYLT PXMYACCT 7 8 +X-YACYLT PXMYACCT 7 1 +X-YACYLT PXMYACCT 4 1 +Y-SADDAST PY-SADDAB 5 1 +Y-SADDAB PY-SADDAB 7 16 +Y-SADDAB PY-SADDAB 7 1		TLM Description	+X+Y ACCESS PNL TEMP	+X-Y ACCESS PNL TEMP	SPILA +V SAN STEPPEN	SPU B +Y SAD STEPPED	A DEAD	A DEAD	+Y SADPOT B DEADBAND INDICATOR	+Y SADPOT B DEADBAND INDICATOR	11-1	-1	L. IL				+Y ACTUAL SADPOT (2 OF 2)	+Y ESTIMATED SADPOT (1 OF 2)	+Y ESTIMATED SAUPOT (2 OF 2)	ESTIMATED SAL	ESTIMATED SAC	+Y ESTIMATED SADPOT (2 OF 2)		5				+Y SADPOT B VALID INDICATOR	+Y SOLAR ARRAY ERROR (1 OF 2)	SOLAR ARRAY	TY SOLAR ARRAY ERROR (1 OF 2)	+Y SOI AR ARRAY FRROR (1 OF 2)	+Y SOLAR ARRAY ERROR (2 OF 2)	+Y SOLAR ARRAY ERROR (1 OF 2)	SOLAR ARRAY E	+Y S/A MIDDLE HNGE DMP TMP	
N + 0 0 0 / V / V + 4 + 4 + 4 + 4 + 4 + 4 + 4 + 4 + 4 +		700				T	1					-	$\neg \vdash$	7				\neg											1	1	\neg	_	1			7	\Box
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+Y S/A PNL TEMP (INBOARD)	S POT	+Y SAD POS POT 2 TAP		. 12	+1 S/A UNSHUNI EU CURRENI +V SHIINT TEMP	+Y SHUNT TAP VOLTAGE (T2259)	+Y SHUNT TAP VOLTAGE (T2260)			1	٠.,١	-X PAYLOAD PNL TEMP E	SPU A -Y SAD STEPPED	SPU B-Y SAD STEPPED	-Y SADPOT A DEADBAND	-Y SADPOT A DEADBAND	INDICATOR	-Y SADPOT B DEADBAND INDICATOR	Y SADPOT B DEADBAND	-Y ACTUAL SADPOT (1 OF 2)	-Y ACTUAL SADPOT (2 OF 2)	-Y ACTUAL SADPOT (1 OF 2)	-Y ACTUAL SADPOT (2 OF 2)	-Y ACTUAL SADPOT (1 OF 2)	-Y ACTUAL SADPOT (2 OF 2) -Y ACTUAL SADPOT (1 OF 2)	-Y ACTUAL SADPOT (2 OF 2)	-Y ESTIMATED SADPOT (1 OF 2)	·Y ESTIMATED SADPOT (2 OF 2)	. Y ESTIMATED SADPOI (1 OF 2)	-Y ESTIMATED SADPOT (1 OF 2)	-Y ESTIMATED SADPOT (2 OF 2)	-Y ESTIMATED SADPOT (1 OF 2)	Y SAD TEMP	-Y SADPOT A VALID INDICATOR	-Y SADPOT A VALID INDICATOR			-Y SADPOT B VALID INDICATOR	Y SOLAR ARRAY ERROR (1 OF 2)	V SOLAR ARRAY ERROR (2 OF 2)	- Y SOLAR ARRAY ERROR (2 OF 2)	-Y SOLAR ARRAY ERROR (1 OF 2)	-Y SOLAR ARRAY ERROR (2 OF 2)
PYSAT	PYSATAP1	PYSATAP2	PYSATOP1	PYSATOP2	PYSHNTT	PYSHTVT1	PYSHTVT2	MXPYACCT	MXMYACCT	MXMYCYLT	MXPNLDT	MXPNLET	MYSADAST	MYSADBST	MYSADDAA		MYSADDAB	MYSADDBA	MYSADDRR	MYSADPAA	MYSADPAA	MYSADPAA	MYSADPAA	MYSADPAB	MYSAUPAB	MYSADPAB	MYSADPEA	MYSADPEA	MYSAUPEA	MYSADPEB	MYSADPEB		MYSADT	<	MYSADVAB	$\overline{}$	7-	MYSADVBB .	MYSAERRA	MYSAEKKA	MYSAERRA	MYSAERRB .	MYSAERRB
+YSAT	+YSATAP1	+YSATAP2	+YSATOP1	+YSATOP2	+YSHNTT	+YSHTVT1	+YSHTVT2	-X+YACCT	XYACCT	-X-YCYLT	-XPNLDT	-XPNLET	-YSADAST	-YSADBST	-YSADDAA		-YSADDAB	-YSADDBA	-YSADDBB	-YSADPAA	-YSADPAA	-YSADPAA	-YSADPAA	-YSADPAB	-YSADPAB	-YSADPAB	-YSADPEA	-YSADPEA	-YSADPEA	-YSADPEB	-YSADPEB	-YSADPEB	-YSADT	-YSADVAA	-YSADVAB	┼──	+	\dashv	-YSAERKA	+	+-		-YSAERRB
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Thruster	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up		All Power-Up	All Power-Up	All Power-Up	All Power In	All Power-1 in	All Power-Up	All Power-Up		All Power-Up	All Power-Up	All Power-up	All Power-Up	All Power-Up	All Power-Up	SSOH	All Power-Up	All Power-Up		All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	SSOH
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-Y SOLAR ARRAY ERROR (1 OF 2)	-Y SOLAR ARRAY ERROR (2 OF:2)	YOUN MIDD IT UNION DAYS TEMP	Y S/A CHITE THISE DIMP LEMP	-Y S/A PNI TEMP (OLITBOARD)	SAD POS POT 1 T	-Y SAD POS POT 2 TAP	-Y SAD POS POT 1 TOP		-Y S/A UNSHUN ED CURREN	- 16			REATO CAT BED TEMP	10.23 MHZ CLOCK SIGNAL TO MDO A	10.23 MHZ CLOCK SIGNAL TO MDU	8	REA10 VALVE TEMP	REALL CALBED LEMP	DEA12 CATOED TEMP	PEA12 VALVE TEMP	REA13 CATBED TEMP			13.4 MHZ CLOCK SIGNAL TO MDU B		KEA14 CAI BED IEMP	REA14 VALVE LEMP	REA15 VALVE TEMP	REA16 CATBED TEMP	16 EOMS REQUEST	REA16 VALVE TEMP	1/30A AKLIHEKKKEPOKI REANI CATRED TEMP	REA01 VALVE TEMP	REA02 CATBED TEMP	REA02 VALVE TEMP	REA03 CATBED TEMP	READS VALVE LEWIP	READ VALVE TEMP	REA05 CATBED TEMP	REA05 VALVE TEMP	REA06 CATBED TEMP	REA06 VALVE TEMP	REAO7 CATBED TEMP	REA07 VALVE TEMP	REA08 CATBED TEMP	SEC 8,16 DATAENDADDR	READS VALVE LEMP	SEC 9,16 DATAENDADDR
MYSAERRB	MYSAERRB	MYSAIHGI	MYSAMHGI	MYSAT	MYSATAP1	MYSATAP2	MYSATOP1	MYSAIOP2	MYSAUNC	MYSHNII	MYSHTVI1	MYSHIVI2	L108D1	L10MHZA		L10MHZB	L10VT	1180	112001	7,007	113BDT	113MH7A		L13MHZB	L13VT	L148U1	L15BDŤ	L15VT	L16BDT	16EOMREQ	L16VT	1/50ASM	LIVI	L2BDT	L2VT	L3BDT	LSVI	14/T	LSBDT	LSVT	LEBDT	LevT	L78DT	ראער	LGBBT	8DATAEND	L8V	9DATAEND
-YSAERRB	-YSAERRB	-YSAIHGI	-YSAMHGI	-YSAT	-YSATAP1	-YSATAP2	-YSATOP1	-YSAIOP2	-YSAUNC	-YSHNII	-YSHTVT1	-YSHIVI2	10801	10MHZA		10MHZB	10/1	1801	12001	7.67	13BDT	13MH7A		13MHZB	13VT	14801	14VI 15BDT	15VT	16BDT	16EOMREQ	16√T	1/50ASM	155	ZBDT	2VT	3807	JAPAT	T/A	SBDT	5VT	GBDT	6VT	7BDT	.TVT	8BDT	8DATAEND	BVI .	9DATAEND
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		1=Thruster ADS Flag Word	1=Thruster ADS Flag Word	TLM (Error) Flag Word 52 (first word)	TLM (Error) Flag Word 52	(first word)	i Livi (Errol) riag vvold ∞ (first word)	TLM (Error) Flag Word 60	(first word)	3062	82	157	(lower half-first word)	RDMGMT Flag Word 54	(lower half-filst word)	(lower half-first word)	RDMGMT Flag Word 62 (lower half-first word)	RDMGMT Flag Word 52	(lower half-first word)	RDMGMI Flag Word 54	RDMGMT Flag Word 60	(lower half-first word)	RDMGMT Flag Word 62		ADS Flag Word	ADS Flag Word		+	Mode Flag Word	Mode Flag Word	Mode Flag Word		Mode Flag Word		Mode Flag Word
	1=Cmd Accepted 0=Cmd Rejected	0=RWA 1=Thruster	0=RWA 1=Thruster	0=No ADA Error 1=ADA Fror	0=No ADA Error 1=ADA	Error	Error	0=No ADA Error 1=ADA	Епог				0=Usabled 1=Enabled	0=Disabled	1=Enabled	0≕Disabled 1≕Enabled	0=Disabled 1=Enabled	0=Test Disabled	1=Test Enabled	0=Test Disabled	0=Test Disabled	1=Test Enabled	0=Test Disabled	0=Not Using B/U Ephem	1=Using B/U Ephen	0=Not Using B/U Ephem	0=Ideal SNP 1=Low Beta SNP	0=Ideal SNP 1=Low		0=ideal SNP 1=Low Beta SNP	0=ideal SNP 1=Low Beta SNP		_	0=C# 1=KN 2=SSH 3=SHES 4=EAH 5=SK	1
Celsius																						,													
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READS VALVE TEMP	CDU COMMAND ACCEPT/REJECT STATUS	ACTUATOR INDICATOR	ACTIVATOR INDICATOR	ACT ACIDIN BODD ACA	ACA ERNOR INCOME.	ADA ERROR INDICATOR	ADA ERROR INDICATOR		ADA ERROR INDICATOR	ADA EXCEPTION REPORT	SEC A,16 DATAENDADDR	ADC ERROR CUMU COUNT	ARRAY DRIVE ELECTRONICS		ARRAY DRIVE ELECTRONICS	ABBAY DRIVE ELECTBONICS		ARKAT URIVE ELECTRONICS	SPU ADE XSTRAP		SPU ADE ASTRAP	SPU ADE XSTRAP		SPU AUE ASTRAP	ADL BACKUP MODE INDICATOR	ACT SOCIAL DISCOSTOR		ADL SUBMODE	ADL SUBMODE	ADI SLIBMODE		ADL SOBWOOL	CURRENT ADS MODE		CURRENT ADS MODE
T/401	AT					ADAERRA /	ADAFARA	1		T	_		ANEENA	Τ	ADEENA	GNEEND		ADEENB	ADEXSTRA	7	ADEXSIRA	ADFXSTRB	1	ADEXSTRB	ADLBKUPA			ADDMODEA	ADUMODEA	ADI MODER	ACCURACION OF THE PERSON OF TH	ADUMODEB	ADSMODEA		ADSMODEA
7/10	ACPTSTAT	ACTINDA	ACTINIDA	400	ADAERRA	ADAERRA	AGGACA		ADAERRB	ADAEXSM	ADATAEND	ADCERROR	ADCENIA	VIII I	ADEENA	ON LINE	ADECINO	ADEENB	ADEXSTRA		ADEXSTRA	ADEXSTRR		ADEXSTRB	ADLBKUPA		AULBAUFB	ADUMODEA	ADUMODEA	ADIMODER	ADUMODED	ADUMODEB	ADSMODEA		ADSMODEA
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Mode Flag Word	Mode Flan Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	2004					*	<u> </u>										See Antenna Config Table		See Antenna Config Table	254		0 ATTMON Record Word (first word)	1
0=Off 1=RN 2=SSH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	0=Off 1=RN 2=SSH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	1			0=EA 1=EH 2=SS 3=SA				1=Armed 0=Disarmed	1=Armed 0=Disarmed	1=On 0=Off	1=On 0=Off								1=CPU A Not OK 0=CPU A OK	1=CPU A Not OK 0=CPU A OK	1=Pos 1 Selected 0=Pos 2 Selected	1=Pos 1 Selected	V-ros z selected		2=HCI 1 LE 4=HCI 2 L	2 TE 15=SPARE	11 LE
						Celsius	Celsius	Celsius	chicia				radians	radians	radians	radians	radians	radians	radians									
Normal	Thruster	Normal	Thruster	Normal	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Normal	Normal	Thruster	Normal	Normal	Thruster	Thruster	All Power-Up	All Power-Up	All Power-Up	All Danier 1 in	HOSS	SSOH		Early Orbit	Early Orbit
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SPUB	SPU B	SPUA	SPU A	SPU B	SPUB	AKM	AKM	AKM	AKM	AKM	AKM	AKM	SPUA	SPUA	SPUA	SPUB	SPUB	SPUB	SPUB	SPU	SPU	SBT	FR.	BOY	BDY		SPUA	SPUA
TT&C	TRC	TT&C	TRC	TT&C	TT&C	PSS	PSS	3 8	SS.	PSS	PSS	PSS	ADS	ADS	ADS	S S	ADS	ADS	ADS	TI&C	TI&C	TT&C		NDS NDS	8		T&C	T&C
CURRENT ADS MODE	CURRENT ADS MODE	CURRENT ADS SUBMODE	CURRENT ADS SUBMODE	CURRENT ADS SUBMODE	CURRENT ADS SUBMODE	AKM TEMP 1A	AKM TEMP 18	AKM TEMP 2B	OCU A PYRO (AKM) ARMED	OCU B PYRO (AKM) ARMED	AKM HEATER HIGH POWER ON/OFF	AKM HEATER LOW POWER ON/OFF	ALPHA ANGLE (1 OF 2)	ALPHA ANGLE (2 OF 2)	ALPHA ANGLE (1 OF 2) AI PHA ANGLE (2 OF 2)	ALPHA ANGLE (1 OF 2)	ALPHA ANGLE (2 OF 2)	ALPHA ANGLE (1 OF 2)	ALPHA ANGLE (2 OF 2)	SPU AMEOK BIT1	SPU A MEOK BIT2	S-BAND ANT SW A POSITION	S-BAND ANT SW B POSITION	ANALOG SOH INT MASK	BDY-P INTERSTATBT.ANSOH		ATTITUDE MEASUREMENT ID	ATTITUDE MEASUREMENT ID
ADSMODEB	ADSMODEB	ADSSUBMA	ADSSUBMA	ADSSUBMB	ADSSUBMB	AKM1AT	AKMIBI	AKM2BT	AKMARMA	AKWARMB	AKMHRTA	AKMHRTB	ALPHAA	T	ALPHAA AI PHAA	-	1	- 1	ALPHAB	AMEOKB1	AMEOKB2	ANTSELA	ANTSELB		ASOHSERR		ATMESIDA /	ATMESIDA /
ADSMODEB	ADSMODEB	ADSSUBMA	ADSSUBMA	ADSSUBMB	ADSSUBMB	AKM1AT	AKMIBI	AKM2BT	AKWARWA	AKMARMB	AKMHTRA	AKMHTRB	ALPHAA	ALPHAA	ALPHAA	ALPHAB	ALPHAB	ALPHAB	ALPHAB	AMEOKB1	AMEOKB2	ANTSELA	ANTSELB	ASOHIMSK	ASOHSERR		ATMESIDA	ATMESIDA
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ATTMON Record Word	1	(first word)	ATTMON Record Word (first word)	ATTMON Record Word			ATTMON Record Word (first word)				3012													3051		
1=CEP 2=HCI 1 LE 3=HCI 1 TE 4=HCI 2 LE 5=HCI 2 TE 0 AND 6-15=SPARE	1=CEP 2=HCI 1LE 3=HCI 1TE 4=HCI 2LE 5=HCI 2TE 0	55	1=CEP 2=HCI 1 LE 3=HCI 1 TE 4=HCI 2 LE 5=HCI 2 TE 0 AND 6-15=SPARE	1=CEP 2=HCI 1 LE 3=HCI 1 TE 4=HCI 2 LE 5=HCI 2 TE 0	1=CEP 2=HCI 1 LE 3=HCI 1 TE 4=HCI 2 LE 5=HCI 2 TE 0	PARE	1=CEP 2=HCI 1 LE 3=HCI 1 TE 4=HCI 2 LE 5=HCI 2 TE 0 AND 6-15=SPARE	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Running 0=Not Running	1=Running 0=Not Running	1=Not Bypassed 0=Bypassed	1=Diode 0=Short				1=Not Bungesed	0=Bypassed	1=Diode 0=Short		and the state of t					8
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ATTITLIDE MEASUREMENT ID		ATTITUDE MEASUREMENT ID	ATTITUDE MEASUREMENT ID	ATTITIINE MEASI IDEMENT ID		ATTITUDE MEASUREMENT ID	ATTITUDE MEASUREMENT ID	S-BAND DWNLNK 1 ATO		ATTMON RUNNING FLAG	ATTMON RUNNING FLAG	X BATT 1 CELL 17 BYPASSED	X BATT1 CELL 17 BYPASS OPEN	-X BATT 1-8 TEMP A	-X BATT 1-9 TEMP A	-X BATT 1-9 TEMP B	-X BATT 19-PACK VOLTAGE	-X BATT 2 CELL 17 BYPASSED	+X BATT2 CELL 17 BYPASS OPEN		+X BATT 2-9 TEMP A	+X BATT 2-9 TEMP B	+X BATT 2 9-PACK VOLTAGE	HIGH BAND/LOW BAND	AUD BATT1 (1 OF 2)	AHD BATT1 (2 OF 2)
ATMESIDA	CO CO	ATMESIDA	ATMESIDB	ATMERINE		ATMESIDB	ATMESIDB	ATO1	ATO2	ATTMONA	ATTMONB	B1C17BY	B1C17OP	B1P8AT	B1P9AT	B1P9BT	B1PK9V	B2C17BY	B2C17OP	B2P8AT	B2P8BT R2P9AT	B2P9BT	B2PK9V	BANDSLCT	DASTINED!	BATTAHDA
ATMERIDA	COLOR	ATMESIDA	ATMESIDB	dogadata		ATMESIDB	ATMESIDB	ATO1	ATO2	ATTMONA	ATTMONB	B1C17BY	B1C17OP	B1P8AT	BIPGAT	B1P9BT	B1PK9V	В2С17ВУ	B2C170P	B2P8AT	B2P8BT R2P9AT	B2P9BT	B2PK9V	BANDSLCT	DATIALIDA	BAT1AHDA
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AHD BATT1 (1 OF 2)	AHD BATT1 (2 OF 2)	-X BATT 1 CURR	AHD AT NIGHT/DAY BATT1 (1 OF 2)	AHD AT NIGHT/DAY BATT1 (2 OF 2)	AHD AT NIGHT/DAY BATT1 (1 OF 2)	AHD AT NIGHT/DAY BATT1 (2 OF 2)	BATT1 PRESSURE AT NIGHT/DAY (1 OF 2)	BATT1 PRESSURE AT NIGHT/DAY (2 OF 2)	BATT1 PRESSURE AT NIGHT/DAY (1 OF 2)	BATT1 PRESSURE AT NIGHT/DAY (2 OF 2)	-X BATT 1 CELL PRESSURE			BATT1 VOLTAGE AT NIGHT/DAY (1 OF 2)	BATT1 VOLTAGE AT NIGHT/DAY (2 OF 2)	-X BATT 1 VOLTAGE	BATT 1 VT LOWER CMDS EXECUTED	BATT 1 VT LOWER CMDS EXECUTED	AHD BATT2 (1 OF 2)	AHD BATT2 (2 OF 2)	AHD BATT2 (1 OF 2)	AHD BATT2 (2 OF 2)	+X BATT 2 CURR	AHD AT NIGHT/DAY BATT2 (1 OF 2)	AHD AT NIGHT/DAY BATT2 (2 OF 2)	AHD AT NIGHT/DAY BATT2 (2 OF 2)	BATT2 PRESSURE AT NIGHT/DAY (1 OF 2)	BATT2 PRESSURE AT NIGHT/DAY (2 OF 2)	BATT2 PRESSURE AT NIGHT/DAY (1 OF 2)	BATT2 PRESSURE AT NIGHT/DAY (2 OF 2)			BATT2 VOLTAGE AT NIGHT/DAY (2 OF 2)
BAT1AHDB	BAT1AHDB	BAT1CUR	BATINDA	BAT1NDA	BATTNDB	BALINDB	BAT1PREA	BATIPREA	BAT1PREB	BATIPREB	BAT1PRES	BAT1VLTA	BAT1VLTA	BAT1VLTB	BAT1VLTB	BAT1VOLT	BAT1VTLA	BAT1VTLB	BAT2AHDA	BAT2AHDA	BAT2AHDB	BAT2AHDB	BATZCUR	BATZNDA	BATZNDA	BATZNDB	BAT2PREA	BAT2PREA	BAT2PREB			BATZVLTA	BATZVLTA
BAT1AHDB	BAT1AHDB	BAT1CUR	BATINDA	BATINDA	BATINDB	BALINDB	BAT1PREA	BAT1PREA	BAT1PREB	BAT1PREB	BAT1PRES	BAT1VLTA	BAT1VLTA	BAT1VLTB	BAT1VLTB	BAT1VOLT	BAT1VTLA	BAT1VTLB	BAT2AHDA	BAT2AHDA	BAT2AHDB	BAT2AHDB	BATZCUR	BATZNDA	BATZNDA	BATZNDB	BAT2PREA	BAT2PREA	BAT2PREB	BAT2PREB	BAT2PRES	BAT2VLTA	BATZVLTA
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7 60 8 0 7 16 BAT2VLTB BAT2VLTB 1 56 8 0 7 16 BAT2VLTB BAT2VLTB BAT2VLTTB BAT2VTLB BAT2V	BATT2 VOLTAGE AT NIGHT/DAY (1 OF 2)	BATT2 VOLTAGE AT NIGHT/DAY (2 OF 2)	+X BATT 2 VOLTAGE	BATT 2 VT LOWER CMDS EXECUTED	BATT 2 VT LOWER CMDS EXECUTED	BCC 1 CHARGE RATE	BCC 1 CHARGE RATE	BCC 1 CHARGE RATE TRICK/HIGH		BCC 1 V/T BIT 1 ON/OFF	BCC 1 V/T BIT 2 ON/OFF	BCC 1 SHFT V/T 16/17 CELL	BCC 2 CHARGE RATE	BCC 2 CHARGE RATE	BCC 2 CHARGE RATE TRICK/HIGH	BCC 2 V/T ENABLED/DISABLED	BCC 2 V/T BIT 1 ON/OFF	BCC 2 V/T BIT 2 ON/OFF	BCC 2 SHFT V/T 16/17 CELL	BCC B/U CHARGE RATE		BCC B/U CHARGE ON/BCC1 OFF	BCC B/U CHARGE ON/BCC2 OFF	BCC B/U CHARGE RATE TRICK/HIGH	ENABI	•		BCC B/U SHFT V/T 16/17 CELL	BCC 1 CHARGER ON/OFF
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1=0 0=0#	volts	volts	mA	volts	volts	volts	Celsius	Celsius		volts			0=Output 1=Input											volts	volts	volts	volts	volts	1=On 0=Off	1=0 0=0	volts	volts	Celsius	volts			0 0 0 0 0		volts				volts		volts	Celsius			
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PRU	BDD/X	BDD/X	BDD/X	BDD/X	BDD/X	BDD/X	BDD/X	BDD/X	BDP-MP	BDD/X	BDD/X	BDP-IP	BDD/X	BDP	BOP	BDP	ВОР	BDP-IP	BDP-IP	BDD/X	BDD/X	BDP-IP	BDD/X	ВОР	BDP	BDP	90	ВОР	ВОР	ВОР	8DP	BDP	TCS	909	90	80	BDP	BDP-IP	BDP	BDD/X	BDP	BDP-IP	BDD/X		BDD/X	806	80P-IP	BUP-IF	BDD/X
EPS FPS	SON	SON	SON	SON	SON	SON	SON	-	_	NDS	NDS	NDS	SON	SON	SON	NDS	SON	-	-	8	88	SON	80N	82	NDS	9 <u>8</u>	8	828	NDS	SON	SCN	SON	MSS	8	88	8	SON	90N	SON	SQN	808	SON	<u>8</u>		8	8	8	2 2	38
BCC 2 CHARGER ON/OFF	BDD/BDX +12V ANALOG MONITOR	BDD/BDX +250V ANALOG MONITOR	BDD/BDX +28V CURRENT	BDD/BDX +5V LOGIC VOLTAGE	BDD/BDX -12V ANALOG MONITOR	BDD/BDX -5V LOGIC VOLTAGE	BDD/BDX TEMP 1	BDD/BDX TEMP 2	SEC B,16 DATAENDADDR	BDD/BDX BIAS VOLTAGE	COMMAND ERROR COUNT	IP BDX/D GIM CNTRL FLG	BDP BDD/BDX DATA I/O	BDD COLLECT INTERVAL	BDD LOW THRESHOLD	DISABBDD MEMOVERWRIT	SELECT BDD SUB FRAME	BDX/D EOM ERROR FLAG	GIM RESET ACKNOW-BDX/D	BDX/D GIM PARITY	BDX/D GIM PARITY ENABLE	GIM RESET REQUEST-BDX/D	NO OPERATION ERR CNT	BDP +15V ANALOG MONITOR	BDP + 5V LOGIC VOLTAGE	BDP +5V REGULATED	BDP -15V ANALOG MONITOR	BDP -5V LOGIC VOLTAGE	BDP A 28 VDC ON/OFF	BDP B 28 VDC ON/OFF	BDP EXTRA SENSOR POWER	BDP GROUND	-X BUS PNL/GBD(BDP) I/F TEMP A	BDP IP PROGRAMMING VOLTAGE	BDP L3 EVINITXFERFLG	START L3 MRO	BDP TO L3 DATA XFER IN PROGRESS	BDX/D LAST EV MSG XFER	BDP MP PROGRAMMING VOLTAGE	BDX/D POWER	BDP POWER		BDD/BDX POWER SUPPLY A 28 VDC	BDD/BDX POWER SUPPLY B	28 VDC	8DP TEMP	BDX/D PLINK EV XFERFLG	P BDX/D GIM ERROR FLG	BDX/D POWER SELECT
BCC2	BDP12V	BDP250V	BDP28C	BDP5V	BDM12V	BDM5V	BD1T	BD2T	BDATAEND	BDBV	BDCMDER	BDCONER	BDDATA	BDDINTVL	BDDLTHR	BDDMOVRT	BDDSUBFR	BDEOMER	BDGIMAC	BDGIMPAR	BDGIMPEN	BDGIMRQ	BDNOERR	BDPP15V	BDPP5V	BDPP5VR	BDPM15V	BDPM5V	BDPAPWR	BDPBPWR	BDPEXSNS	BDPGND	BDPIFT	ВОРІРРУ	BDPL3EVT	BDPL3MRO	BOPI 3XFR	BDPLNK	BDPMPPV	BDPOWER	BDPPWR	BDPROIN	BDPSA28V		BDPSB28V	BDPT	BDQPLNK	BORECER	BDSELECT
BCC2	BC+12V	BD+250V	BD+28C	BD+5V	BD-12V	BD-5V	BD1T	BD2T	BDATAEND	BOBV	BDCMDER	BDCONER	BDDATA	BDDINTVL	BDDLTHR	BDDMOVRT	BDDSUBFR	BDEOMER	BDGIMAC	BDGIMPAR	BDGIMPEN	BDGIMRQ	BDNOERR	BDP+15V	BDP+5V	BDP+5VR	BDP-15V	BDP-5V	BDPAPWR	BDPBPWR	BDPEXSNS	BDPGND	BOPIFT	BDPIPPV	BDPL3EVT	BDPL3MRO	BDPI3XFR	BDPLNK	BDPMPPV	BDPOWER	BDPPWR	BDPROIN	BDPSA28V		BDPSB28V	ВОРТ	BDQPLNK	BORECER	BDSELECT
2 11 11 2 2	-	6 4 24 8 0 7 8	6 24 8 0 7	5 7 24 8 0 7 8	6 2 24 8 0 7 8	5 8 24 8 0 7 8	5 24 8 0 7	6 24 8 0 7	0 8	3 24 8 0 7	NA NA NA 0	NA NA NA 1 NA 1	2 2	NA NA NA NA 2 NA 2	NA NA NA NA 5 NA 1	4	NA NA NA NA	ξ S	NA NA NA 6	NA NA NA O	NA NA NA NA 1	NA NA NA NA 5 NA 1	NA NA NA NA O NA 8	1 7 24 8 0 7 8	1 6 24 8 0 7 8	8 0 7	24 8	8 0 7	A 3 16 1 0 0 1	A 4 16 1 0 0 1	-	2 1 24 8 0 7 8	8 0 7	8 24 8 0	NA NA NA 5	NA NA NA O NA 1	A 1 64 1 7 7 1	NA NA NA 2	3 24 8	NA NA NA NA 7	NA: NA NA O	NA NA NA 7	1 3 24 8 0 7 8			4 24 8 0 7	NA NA NA 5 NA	NA NA NA	NA NA NA NA 6 NA 1

9	149	SSOH Byte 3430	SSOH Byte 3428	SSOH Byte 3429	170		170	SSOH Byte 3433		SSOH Byte 3435	145		SSOH Byte 3113 Format	171	SSOH Byte 3434	3055	3061	171	282	3010	172	173	173	173	173	170	172		3009	173	7	173	1/3	3064	147	170	147	3066	171	145	SSOH Byte 3431	170	171	170	150	7	171	3064	3064
						1=0 0=0			1=0n 0=0f				O=Output 1=Input																																				
		volts	volts	volts				Celsius		Celsius					Celsius												i	Celsius												a la la la	Celsius	200							
SSOH	SSOH	All Power-Up	All Power-Up	All Power-Up	SSOH	All Power-Up	SSOH	All Power-Up	All Power-Up	All Power-Up	SSOH	SSOH	All Power-Up	SSOH	All Power-Up	HOSS .	SSOH	HOSS HOSS	ם פוסט	HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	All Power-Up	SSOH	SSOH	SSOH	HOSS HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	HOSS	1000	All Pound IIn	All Power-Up	HOSS	SSOH	SSOH	SSOH	SSOH	HOSS	500	ביטאא
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BDD/X	BDP-IP	BDW	BDW	BOM	BDP-IP	BDW	BDP-IP	BON	BDW	BDW	BDP-1P	BDW	BDW	BDP-IP	BDW	8	BOP 1	בים הים	200	BDP-IP	80P-IP	BDP-IP	ВОР-ІР	BDP-IP	BDP-IP		80P-IP	2	80b	BDP-IP	BDW	RDP-IP	BDP-IP	ВОР	BDP-IP	BDP-IP	BDP-IP	909	0.00	ROW	BDW	BDP-IP	BDP-IP	BDP-1P	BDP-IP	BDW 6	807-P		7
SON	8	88	8	8	2	SON	SQ.	8	NDS	80N	SON	SON	NDS	NDS	88	SQ.	2 2	╁	+	888	+	-	SON		+	3		MSS	+	+	9 2	+-	800	├	-	-	+	2 2	+	+	88	╁			-	8 8	+	3 2	3
8	BDXU SOH RECEIV	>	BUWPSV BDW +5V LOGIC VOLTAGE	BLWWD2V BDW -5.2V ANALOG MONITOR		\neg	BDWARIER 1705A ARITH ERR-BDW	-		BDW CHASSIS TEM		BDWCVCFG BDW CONF/ELECSTAT	ار	BDWDIAG DIAG SUCCESSFUL-BDW		BUNUSISI DISCRETESI		1	_	BDWGIMRQ GIM RESETREQUEST-BDW	1	1	BDWHBDC HI BAND DELAYCALFAIL		BUNNHBIC HI BANDIHRESHCALFAIL			-X BUS PNL/GBD(BD	1		BOWLECV BOW LOBANDSIAI	Ť			BDW PARITY ENABL	MEMORYPARITY ER	BUWPARUE BUW OUD/EVEN PARITY	BUNDERSTR PROCESSOR	1	BDW RF HIGH BAND		BDWRSTAC USART RESETACKNW-BDW		1.	<u> </u>	BOW ELEC STATUS	BOWSMER SOFT MEMORY ERK-BOW RDWSMSG DISABLE BOW STAT MSG	DISABLE BOW SIA	٦
5 NA	4 24 24 24 24	7 24 8 0 7 8	-	NA MA NIA	7	3 16 1 4 4 1	7 4 24 8 0 7 8 BOWARIER	0 / 0 0 5	1 4 4	6 24 8 0 7 8	NA NA NA 2 NA 1	NA NA NA 6 NA 1 BDWCVCFG	1 64 1 2 2 1	NA NA 5 NA 1	2 4		NA NA NA 1	-	NA NA NA NA 2 NA 1 BDWFUNC	NA NA NA 5 NA 1	NA NA NA 3 NA 5	NA NA NA 1	-				NA NA NA 1	6 58 8 0 7 8	3 NA 1	NA N	NA N	NA NA NA 6 NA 1	NA:NA NA 1	NA NA NA 6 NA 1	NA NA NA 1 BDWPAR	NA 1 NA 1 BOWPAKEK	NA NA NA 1 BOWPARCE	NA NA NA 6 NA 1	NA NA NA 6 NA 1 BOWRECER	2 24 8 0 7 8 BDWRFHBT	RDWRFLBT	NA NA NA 6 NA 1 BOWRSTAC	NA NA NA 3 NA 1 BDWSACMD	NA NA NA 1 BOWSEEPR	NA NA NA 0 NA 4 BOWSHRCV	NA NA NA NA 2 NA 1 BUNVSICI	NA NA NA 1	NA NA NA 5 NA 1	Tall Charles

324	3012	2996	3055	171	2996	3055	3003	3000	3000	3002	3003	3010	3003	3003	3003	3000	3002	147	147	3011	3011	3002	3003	3002	2984	62	82	107	000	219	3012	2996	SSOH Byte 3416	SSOH Byte 3398	SSOH Byte 3394	SSOH Byte 3402	SSON Byte 3414	SSOH Byte 3417	SSOH Byte 3399	SSOH Byte 3403	SSOH Byte 3415	SSOH Byte 3401	252	2972 145	3	SSOH Byte 31 L3 Format	2993	158	2972	3010	188	202
															المام ل	Ceisius																	mA	volts	mA	mA	volts	mA	volts	volts	mA	voits			0=Output	1=Input						
SSOH	SSOH	SSOH	SSOH	SSOH	HOSS	SSOH	SSOH	SSOH	SSCH SCH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH All Power I In	SSOH	HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	HOSS S	E 200	E 25	HOSS CH	1000	HOSS	SSOH	HOSS	SSOH	HOSS	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	1000	HOSS		All Power-Up	SSOH	SSOH	HOSOH	HOSS.	HOSS	1
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\vdash	BUPCNIRL FOR BD	- :	I IMED SI		1.	DESCRIPTION OF TOOM OF THE PERSON OF THE PER	十	T-	DISABBOXEVCOLLE	RST BDX/D POINTEPS & CO.	DISABLE BOY CHAINTON	\top	+	+		BDX PROCESSOR INIT	DISABLE BDX/D MRO	1.	BOX DOUTEVEN PARILY	BOY DOMED OF FOT	DISABI E BOX/D SOH MSGS	SEND BOX/D SOH	SEND BOX/D STATI	FNABI F RDX/D SVS TEST	TMP BUF TAKOUTFI GS BDX	BDX TMP BUFF I/P PNT	BDX TMP BUFF O/P PNT		XRAY TRIG CNT(HI-LO)	BDX TRIGGER ENABLE	BUN BUW COINCIDENCE	RDV 416 SV CUBBENIT	BDY +16-5V ANALOG MONITOR	BDY +28V CURRENT	BDY +5.25V ANALOG MONITOR	BDY +7V CURRENT	BDY +7V ANALOG MONITOR		BUY -16-5V ANALOG MONITOR	BDY - 7/ CHRRENT	BDY -7V ANALOG MONITOR	COMMAND ERROR COUNT	RESET BDY SET COMMANDS	IP BDY GIM CNTRL FLG				RST BDY POINTERS & FLOS		-BDY		
BDWSTAT	BUNNSIORE	BOWS S	BDVV ISISI	BUNVOPLD	DOVYANII -	RIXCMBGT	RICCON	BDXCTIME	BDXEVT	BDXFI RST	BOXELING	BDXGMECK	RUXGMEAR	BDXGMRST	BOXIFT	BDXINIT	BDXMRO	BUXPAR	BUXBAND	BOXGICT	BDXSOH	BDXSOHSD	BDXSTAT	BDXSTST	BDXTBFTO		BDXTBOP			BDXTRIG		BOX PIEC	BDVP16V	BDYP28C	BDYP525V	BDYP7C	вруруу	BDYM16C	BDYM16V RDVM525V	BDYM7C	BDYM7V	BDYCMDER	BDYCMRST	BDYCONER		BDYEFRE	BDYFOMER	BDYFLRST	BDYFUNC	BDYGIMAC	BDYGIMRO	!
BDWSTAT	ROMETET	DUMBISI	DOWING I	BUNYANT	BOWERET	BDXCMRST	BDXCOIN	BDXCTIME	BDXEVT	BDXFLRST	BOXFUNC	BDXGMECK	BDXGMPAR	BDXGMRST	BOXIFT	BDXINIT	BUXMRO	BUAPAK	BUX PANE	BOXSICT	BDXSOH	BDXSOHSD	BDXSTAT	BDXSTST	BDXTBFTO	BDXTBIP	BDXTBOP	BDXTBQUE	BDXTC	BDXTRIG	BOXYANT	BDY+16C	BDY+16V	BDY+28C	BDY+5.25	BDY+7C	BDY+7V	BOY-18C	BDV-16V	BDY-7C	BDY-7V	BDYCMDER	BDYCMRST	BDYCONER	4140	BOYEERF	100	+	+	\vdash	BDYGIMRQ	
NA NA NA NA 6 NA 2	NA NA NA	_	NA NA NA		NA NA NA	-		NA NA NA NA 2 NA 2	NA NA NA NA 3 NA 1	NA NA NA NA 5 NA 1	NA NA NA 1 NA 1	NA NA NA NA 6 NA 1	NA NA NA NA 2 NA 1	-	6 58 8 0	NA NA NA 2	NA NA NA NA NA S	NA NA NA 2	NA NA NA 7	NA NA NA NA 6 NA 1	-	NA NA NA NA 7 NA 1	NA NA NA NA 7 NA 1	NA NA NA NA 6 NA 1	NA NA NA NA 2 NA 1	NA NA	NA NA NA NA 0 NA 16	NA NA NA O NA	NA NA NA	NA NA NA NA 6 NA 1	NA NA NA	3 24 8 0	1 24 8 0 7	5 24 8 0 7	ς.	1 24 8 0 7	8 0 7	2 24	24 8 0 7	24 8 0 7	24 8 0 7	NA NA NA NA O NA 8	NA NA NA NA 1	NA NA NA NA 0 NA 1	£ 50	NA: NA NA	NA NA NA NA 4 NA 1	¥ V	NA NA NA O	NA NA NA 6	NA NA NA NA 1 1	

ATTOMAN Record Word (second word)	ATTOMAN Record Word (second word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (first word)	ATTOMAN Record Word (second word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (first word)	ATTOMAN Record Word (first word)	ATTOMAN Record Word (first word)	ATTOMAN Record Word (second word)	ATTOMAN Record Word (second word)	ATTOMAN Record Word (second word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (third word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (fourth word)	ATTOMAN Record Word (fourth word)					
																								1=CPU A NOT OK 0=CPU A OK	1=CPU A Not OK 0=CPU A OK	1=Normal 0=Xstrap	1=Xstrap 0=Normal	
Sesit	pisec	pisec)ISBC	Sec	Sec	Desit	Desir	HSec	pisec	Sec	HSBC	pisec	oesit	nsec	11500	hsec	pisec	pisec	pisec	Sec	рес	Sesid	pesid					volts
Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up
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SPUA	SPUA	SPUA	SPUA	SPUA	SPUA	SPUA	SPUA	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPUB	SPU	SPU	MD	₹	PRU
TT&C	11&C	7&C	T&C	T&C	T&C	T&C	T&C	T&C	TT&C	T&C	TT&C	T&C	T&C	TT&C	TT&C	T&C	J&C	T&C	TT&C	17&C	T&C	T & C	11&C	TT&C	TT&C	₽ P	J.	EPS
26 BIT COUNTER	26 BIT COUNTER	26BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	26 BIT COUNTER	SPU B MEOK BIT 1	SPU B MEOK BIT 2		MDU CONV B TO BMI A (AND A TO B) XSTRAP	SV BUS VOLTAGE (AT PRU)
BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BMEOKB1	BMEOKB2	BMINRM	BMIXST	BUSVOLT
BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRA	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BITCNTRB	BMEOKB1	BMEOKB2	BMINRM	BMIXST	BUSVOLT
28	7 26	92	82	82	8	82	28	8	7 28	82	82	83	92	82	8	82	8	8	8	8	8	8	8	-	-	-	-	8
0	0	0 7	0 7	0 7	0 7	0 7	0	2 9	0	0 7	0 7	2 9	2 9	2 9	0 7	0 7	0 7	0 7	0 7	0 7	0	0	0 7	0	-	-	-	0
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	3062	2978	2979	2979	2978	2977	2978	2977	88			Loral mnemonic = "CDU-			Loral mnemonic ⇒ "CDU- BPWR"	Binary equivalent of decimal values 0 to 127		RDMGMT Flag Word 52 (lower half-first word)	RDMGMT Flag Word 54 (lower half-first word)	RDMGMT Flag Word 60	RDMGMT Flag Word 62 (lower half-first word)	RDMGMT Flag Word 53	RDMGMT Flag Word 55	RDMGMT Flag Word 61	RDMGMT Flag Word 63	(lower rian-second word)		RDMGMT Flag Word 55	RDMGMT Flag Word 53	(upper nair-second word) RDMGMT Flag Word 63	(upper half-second word)	RDMGMT Flag Word 61	(apper mail-second word)	3004	3005	3037	3008	3007	3004	4/
Celsius										volts	Celsius	1=Enabled O=Disabled	volts	s	1≂Enabled 0=Disabled		amps	O=Test Disabled 1=Test Enabled	O=Test Disabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	0≖Disabled 1=Enabled	0=Disabled	0=Disabled	0=Disabled	Celsius	1=Overcurrent 0=No Overcurrent	0=Test Disabled	0=Test Disabled	0=Test Disabled	1=Test Enabled	0=Test Disabled								
All Power-Up C	SSOH	SSOH	HOSS	HOSS	SSOH	SSOH	HOSS	SSOH	SSOH		All Power-Up Ce	All Power-Up	ļ	<u> </u>	All Power-Up	All Power-Up		Normal	Thruster	Normal	Thruster	Normal	Thruster	Normal	Thrister	٩	All Power-Up	Normal	Thaielor	i Dienii i	Normal	Thruster	SSOH	SSOH	SSOH	SSOH	SSOH HOSE	HOSS	HOSS	נוססס
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MSS	SDS NDS	8	SON	8 <u>8</u>	8	NDS	8	SON	8	28 1	ည္တို ၂	11&C	TT&C	TT&C	TT&C	TA	EPS.	TT&C	T&C	787	TT&C	T&C) 	18C	TT&C	MSS	TT&C	TT&C	, L	2	2% L	7 7 7	808	8	8	8	2 2	NDS	SON	23.51
-X PAYLOAD PNUCAFS I/F TEMP B	CAL FAILED REPORTS	C-BAND ARIES PWR SETTIN	DISABLE BDP DATA C-BAND	DISABLE BDW DATA C-BAND	ENABLE ARIES POWER	HPA SELECT A/B	ENABLE NDM POWER	ENABLE C-BAND XMIT PWR	SEC C, 16 DATAENDADDR	CDU A CONV +5VDC OUT	COO A CONVIEND	CDU A CONFIGURE PWR	CDU B CONV +5VDC OUT	CDU B CONV TEMP	CDU B CONFIGURE PWR	CDU COMMAND COUNT	BUS CURR TO CDU	CDU COMMAND VERIFICATION	CDU COMMAND VERIFICATION	CDU COMMAND VERIFICATION	CDU COMMAND VERIFICATION	COMMAND DECODER UNIT	COMMAND DECODER UNIT	COMMAND DECODER UNIT	COMMAND DECODER UNIT	+X BUS PNL/CDU I/F TEMP B	CDU DPC OVERCURR FAULT	CDU POWER	CDU POWER		CDU POWER	CDU POWER	CLEAR EVENT MEMORY	DURATIONOFCONFIGCHNG-HI	DURATIONOFCONFIGCHING-LO	ININI NXI CONFIGCHNG-MSB	ZTIME FORCONFIGCHING-LSB	ZTIME FORCONFIGCHNG-LSB	CONFIGURATION CHANGE EN	
CAFSIFT	CALFALSM	CARESPWR	CBDPDATA	CBDWDATA	CBNDATES	CBNDHPA	CBNDNDM	CBNDXMIR	CDATAEND	CDUACVSV	2000	CDUAPWR	CDUBCV5V	CDUBCVT	CDUBPWR	CDUCMDCT	CDUCUR	CDUCVA	CDUCVA	CDUCVB	CDUCVB	CDUENA	CDUENA	CDUENB	CDUENB	CDUIFT	CDUOVRC	CDUPWRA	CDUPWRA	1	CDUPWRB	CDUPWRB	\neg			CFCCHINH	CFGCHSTH	T	CFIGERR	٦
\vdash	-+	3 CARESPWR	CBDPDATA	CBDWDATA	CBNDARES	CBNDHPA	CBNDNDM			CUCACVSV	+		4	CDUBCVT	CDUBPWR		CDUCUR	CDUCVA	CDUCVA	CDUCVB	CDUCVB	CDUENA	CDUENA	CDUENB	CDUENB	CDUIFT	CDUOVRC	CDUPWRA	CDUPWRA		CDUPWRB	CDUPWRB	CEVTMEM	+	-	CFCCHINE	1	\vdash	CFIGCHG	1
1 58 8 0 7	NA NA NA 7	NA NA NA 5 NA	MA NA NA	NA NA NA S	NA NA NA	NA NA NA	NA NA NA		M M M		3	16 1 1 1	8 S	0	7 16 1 5 5 1	7 1 7	8 7 8	8 52 1 0 0 1	4 54 1 0 0 1	8 60 1 0 0 1	4 62 1 0 0 1	8 53 1 0 0 1	4 55 1 0 0 1	8 61 1 0 0 1	-		A 43 1 4 4 1	7 55 1 6 6 1	5 53 1 6 6 1		7 2 1 6 6 1	5 61 1 6 6 1	NA NA NA	NA NA NA 1	NA NA NA O	NA NA NA NA O NA 8	NA:NA NA O NA	NA NA NA O NA	NA NA NA NA O NA 1	

CHANFAK	CHANPAR	BDW CHANNEL PARITY FLAG INDIC U/L OVER MAX	SQN	9	တ	HOSS		1=U/L Over Range	3066
9	CHKOVERA		TI&C	SPUA	တ	Power-Up		0=U/L In Range	
8	CHKOVERB A		TT&C	SPUB	S	Power-Up		1=U/L Over Range 0≕U/L In Range	
8₹	CHKSUMA C		T&C	SPUA	တ	Power-Up			Word 1 of 2 (first 8 bits)
X	CHKSUMA		T&C	SPUA	တ	Power-Up			Word 2 of 2 (second 8 bits)
≅	CHKSUMB C	OF MEM CHECKSUM	TRC	SPUB	ဟ	Power-Up			Word 1 of 2 (first 8 bits)
₹	CHKSUMB C		TT&C	SPUB	ဟ	Power-Up			Word 2 of 2 (second 8 bits)
S		ED CHECKSUM RESULT	T&C	SPUA	ဟ	Early Orbit	counts		
S	CKSUMA (NDED CHECKSUM RESULT	TT&C	SPUA	ဟ	Early Orbit	counts		
ত	CKSUMA	KSUM RESULT	T&C	SPU A	ဟ	Normal	counts		
ΣŠ	CKSUMA		TT&C	SPUA	ဟ	Normal	counts		
Š	CKSUMA (KSUM RESULT	TT&C	SPUA	တ	Thruster	counts		
Š	CKSUMA (COMMANDED CHECKSUM RESULT (2 OF 2)	TT&C	SPUA	တ	Thruster	counts		
Δ	CKSUMB (COMMANDED CHECKSUM RESULT (1 OF 2)	TRC	SPUB	တ	Early Orbit	counts		
Š	CKSUMB (COMMANDED CHECKSUM RESULT (2 OF 2)	TT&C	SPUB	တ	Early Orbit	counts		
Š	CKSUMB (COMMANDED CHECKSUM RESULT (1 OF 2)	TT&C	SPUB	တ	Normal	∞unts		
Š	CKSUMB (COMMANDED CHECKSUM RESULT (2 OF 2)	TT&C	SPUB	ဟ	Normal	counts		
Š	CKSUMB (COMMANDED CHECKSUM RESULT (1 OF 2)	TT&C	SPUB	တ	Thruster	counts		
N S	CKSUMB (COMMANDED CHECKSUM RESULT (2 OF 2)	TT&C	SPUB	ဟ	Thruster	∞unts		
IN	CKSUMERA	CHECKSUM ERROR-4K BLOCK NUMBER	TT&C	SPUA	S	Early Orbit		Binary equivalent of values 0-32	TLM (Error) Flag Word 52 (first word) Range = 0-32
l IS	CKSUMERA N	CHECKSUM ERROR-4K BLOCK NUMBER	TT&C	SPUA	ဟ	Normal Thruster		Binary equivalent of values 0-32	TLM (Error) Flag Word 52 (first word) Range = 0-33
SG	 	JM ERROR	T&C	SPUB	ဟ	Early Orbit		Binary equivalent of values 0-32	TLM (Error) Flag Word 60 (first word) Range = 0-34
l S	CKSUMERB N	CHECKSUM ERROR4K BLOCK NUMBER	TRC	SPUB	ဟ	Normal Thruster		Binary equivalent of values 0-32	TLM (Error) Flag Word 60 (first word) Range = 0-35
l l		UPLINK CHECKSUM STATUS) 	SPUA	ဟ	₹		0=No Comp (No U/L) 1=Checksum Match 2=Checksum Error 3=Match Curr U/L 4=Err Curr U/L	TLM Flag Word 12 (first word)
								0=No Comp (No U/L) 1=Checksum Match 2=Checksum Error	
KSU	CKSUMSTB L	UPLINK CHECKSUM STATUS	TT&C	SPUB	S	Ą		3=Match Curr U/L - 4=Err Curr U/L	TLM Flag Word 20 (first word)
MDA	CMDAVALA /	FLAG INDICAT U/L RCVD AND AWAIT PROC	TT&C	SPUA	S	Power-Up		1=U/L Cmd Recd 0=U/L Cmd Not Recd	

	3012			41	49	2944	2975	29/6	2997	2998	2999	3039	3041	3042	3056	3057	3058	3059	3060	38	SSOH Byte 31 L3 Format	46	2978	2979					-	2977	3013	3051	3051			2979			RDMGMT Flag Word 54 (upper half-first word)	RDMGMT Flag Word 52 (upper half-first word)	RDMGMT Flag Word 62 (upper half-first word)
1=U/L Cmd Recd		1=No Error O=Error	1=No Error O=Error																		0=Even 1=Odd				1=SPU A Active 0=SPU A Inactive	1=SPU B Active 0=SPU B Inactive	1=S-Band 1 Active	0=S-Band 1 Inactive	0=S-Band 2 Inactive					1=Normal 0=Xstrap	1=Xstrap 0=Normal				0=Test Disabled 1=Test Enabled	0=Test Disabled	0=Test Disabled 1=Test Enabled
																			-																		Celsius	Celsius			
Power-I in	HOSS	All Power-Up	All Power-Up	HOSS	HOSS	SSOH	SSCH HOSS	SSOH	All Power-Up	SSOH	SSOH	SSOH	All Power-Up	All Power-Up		All Power-Up	All Power-Up	SSOH	HOSS	SSOH	HOSS	All Power-Up	All Power-Up	SSOH	All Power-Up	All Power-Up	Normai	Thruster	Normai												
U.	S	5	7	S	S	S	တ	S	S	S	S	S	יט מי	S	S	တ	တ	S	တ	S	Ø	S	ဟ	တ	v	v.	,	တ	ဟ	S	S	S	n v	2	占	S	₽	₽	ဟ	ဟ	S
Spil B	2 6	22	E E	BDP-MP	BDP-MP	BDP	80	9	98	8	909	8		8	BDP	BDP	BDP	ВОР	<u>6</u>	BDP-MP	90B	BDP-MP	BDP	BDP	nas	ngo		3	nao	98	BOP	90	BDP-MP	Q	AD.	80	SSS	SSS	SPUA	SPUA	SPUB
17&C	2 SQN	T &C	7.8C	SON	SON	80N	SON	8	8	8	9	8	2 2	SON	NDS	NDS	SON	SON	8	80N	SON	800	SON	SON	11&C	TRC		28T	T&C	80N	SON	SON	2 V	d A	TNP	SON	ADS	ADS	\ \ \ \ \ \	11&C	 T&C
FLAG INDICAT U/L RCVD AND AWAIT PROC	DISABAUTO CMD CHKING	PCE A CMD PARITY ERROR			L3 OP FLAG CMD	COMMAND REGISTER 00	COMMAND REGISTER 1F	COMMAND REGISTER 20	COMMAND REGISTER 35	COMMAND REGISTER 36	COMMAND REGISTER 37	COMMAND REGISTER SF	COMMAND REGISTER 60	COMMAND REGISTER 62	COMMAND REGISTER 70	COMMAND REGISTER 71	COMMAND REGISTER 72	COMMAND REGISTER 73	COMMAND REGISTER 74	CMD RECEIVE COUNTER	BDP COMMAND/UPLOAD MONITOR	XFER MSG FLAG CMD	C-BAND NDM POWER SETTIN	DISABL NPMS DATA C-BAND	CMD LINK CNTRL FROM SPU A	CMD INK CNTRI FROM SPU B		CMD LINK CNTRL FROM UPLINK 1	CMD LINK CNTRL FROM UPLINK 2		BDW WHS CONC MEM SEP	CONCURRENCE ENABLE	CH CONCURRENC WINDOW	MDU CONV A TO CPU A (AND B TO BNORM	MDU CONV B TO CPU A (AND A TO B) XSTRAP	DISABLE SOH DATA C-BAND		CSS -Y TEMP	CSS DATA READY	CSS DATA READY	CSS DATA READY
CMDAVALB	CMDCHECK	CMDERRA	CMDERRB	CMDINTER	CMDL3RO	CMDROOH	CMDR1FH	CMURZOH	CMDR35H	CMDR36H	CMDR37H		CMDR61H	1	[CMDR71H	CMDR72H	CMDR73H	CMDR74H	CMDRECVD	CMDUPMON	CMXFRMSG	CNDMPWR	CNPMDATA	CNTRLSA	CNTRISE		CNTRLU1	CNTRL-U3	COMRELAY	CONCMEM	CONCUR	CONCWIND	CPINEM	CPUXST	CSOHDATA	CSSPYT	CSSMYT	CSSDRA	CSSDRA	
CMDAVALB	1	CMDERRA	CMDERRB	CMDINTER	CMDL3RO	CMDR00H	CMDR1FH	CMDRZOH	CMDR35H	CMDR36H	CMDR37H	CMDRSFH	CMUKBUH	CMDR62H	CMDR70H	CMDR71H	CMDR72H	CMDR73H	CMDR74H	CMDRECVD	CMDUPMON	CMXFRMSG	CNDMPWR	CNPMDATA	CNTRL-SA	an-lating	1	CNTRL-U1	CNTRL-U2	COMRELAY	CONCMEM	CONCUR	CONCWIND	CPLINEM	CPUXST	CSOHDATA	CSS+YT	CSS-YT	CSSDRA	CSSDRA	CSSDRB
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RDWGMT Flag Word 60	RDMGMT Flag Word 52	(lower half-first word)	(lower half-first word)	RDMGMT Flag Word 60	(lower nar-first word)	RDWGMT Flag Word 62 (lower half-first word)	_				=Side Ground Select Flag Word 62 (first word)		Cilist World)	(upper half-first word)	RDMGMT Flag Word 52	(upper half-first word)	(upper half-first word)	RDWGMT Flag Word 60	RDMGMT Flag Word 55	(upper half-second word)	RDMGMT Flag Word 53 (upper half-second word)	RDMGMT Flag Word 63	(upper half-second word)	(upper half-second word)	RDMGMT Flag Word 54	RDMGMT Flag Word 52	(Upper half-first word)	(upper half-first word)	RDWGMT Flag Word 60 (upper half-first word)						0.2959 µA/count (-Y)	0.2959 uA/count (-Y)	0.2959 µA/count (-Y)	0.2959 µA/count (-Y)	0.2959 pt/count (-Y)
0=Test Disabled	0=Disabled	1=Enabled	1=Enabled	0=Disabled	1=Enabled	0=Disabled 1=Enabled	0=Side A 1=Side		0=Side A 1=Side		U=Side A 1=S	0=Side A 1=Side	D Total	1=Test Enabled	0=Test Disabled	1=Test Enabled	1=Test Enabled	0=Test Disabled	0=Test Disabled	1=Test Enabled	0=Test Disabled	0=Test Disabled	1=Test Enabled	0≕ lest Lisabled 1=Test Enabled	0=Test Disabled	0=Test Disabled	0=Test Enabled	1=Test Enabled	0=Test Disabled 1=Test Enabled	v	9	•		8					
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Thorster	New York	Normai	Thruster		Normal	Thruster		Thruster		Normai	Normal		Inruster	Normal		Thurster	Normal	Thrister		Normal	Thurster		Normal	Thruster	Normal		ınuızıer	Normal	Thruster	Normal Thruster	Normal Thruster	Normal	Normal	Thruster	Normal	Thruster	Thruster	Normal	Thruster
U.	0	20	တ		2	ဟ		S		n	ဟ		0	ဟ		S	ဟ	ď		S	Ø		တ	ဟ	U.	,	n	တ	S	ဟ	ဟ	ဟ		S	n u	တ	S	s u	ာဟ
SPUB	V I I I I	SPO A	SPU A	0 1,00	SPUB	SPU B		SPUA		SPUA	SPUB		970	SPUA		SPUA	SPUB	SPI B		SPUA	SPUA		SPUB	SPUB	Spi I A		ALC A	SPUB	SPUB	SPUA	SPUA	SPUB		SPUB	V DIGU	SPUA	SPUA	SPUB	SPUB
1780	-	+	T&C		ر ه	180	-	TRC		၌ =	T&C		8	T&C		282	T&C	TRC		T&C	T&C	┿	2. 1. 1.	T1&C	1 kC		၌ -	TT&C	T&C	SQ4	Ags.	ADS		SS	200	38	ADS	S S	SQ.
CSS DATA READY	COARSE SLIN SENSOR	COARSE SON SENSOR	COARSE SUN SENSOR	O A DORENGO	COARSE SON SENSOR	COARSE SUN SENSOR		CSS EYE SELECT	100	כפס בוב פברבכו	CSS EYE SELECT	FOR 120 BY B 000	COS ETE SELECT	CSS HIGH EYE SUM		CSS HIGH EYE SUM	CSS HIGH EYE SUM	CSS HIGH EVE SUM		CSS LOW EYE OUTPUT	CSS LOW EYE OUTPUT		CSS LOW EYE OUTPUT	CSS LOW EYE OUTPUT	SS I OW EYE SI IM		CSS LOW EYE SUM	CSS LOW EYE SUM	CSS LOW EYE SUM	FILTERED CSS PITCH OUTPUT (1 OF 2)	FILTERED CSS PITCH OUTPUT (2 OF 2)	FILTERED CSS PITCH OUTPUT	FILTERED CSS PITCH OUTPUT	(2 OF 2)	CSS PITCH OUTPUT B (1 OF 2)	CSS PITCH OUTPUT B (1 OF 2)	CSS PITCH OUTPUT B (2 OF 2)	CSS PITCH OUTPUT B (1 OF 2)	CSS PITCH OUTPUT B (1 OF 2)
CSSDRB	CSSENA	ANIBOS	CSSENA	COCENID	COSEND	CSSENB		CSSEYEA	4 3 A 3 A 3 A 3 A 3 A 3 A 3 A 3 A 3 A 3	COSCIEN	CSSEYEB	GEVED	COSCIED	CSSHSUMA		CSSHSUMA	CSSHSUMB	CSSHSUMB		CSSLOUTA	CSSLOUTA		CSSLOUTB	CSSLOUTB	CSSISIMA		CSSLSUMA	CSSLSUMB	CSSLSUMB	CSSPFILA	CSSPFILA	CSSPFILB		CSSPFILB	- 1	- 1	1 1	CSSPITMB	CSSPITMB
CSSDRB	CSSENA	SSEINS	CSSENA	CCCEND	COSCIND	CSSENB		CSSEYEA	A II A I	COSCIEN	CSSEYEB	OPVER	COSCIED	CSSHSUMA		CSSHSUMA	CSSHSUMB	CSSHSUMB		CSSLOUTA	CSSLOUTA		CSSLOUTB	CSSLOUTB	CSSISTIMA		CSSLSUMA	CSSLSUMB	CSSLSUMB	CSSPFILA	CSSPFILA	CSSPFILB		CSSPFILB	CCCDITMA	CSSPITMA	CSSPITMA	CSSPITMB	CSSPITMB
5 1	1	+	4	-	+	4 1		-	7	+	3	•	+-	6		9	9	-		-	0	-	0	0	7	+-	-	7 1	7 1	7 16	7 16	7 16		7 16	7 12	7 12	7 12	7 12	7 12
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6 5 80	6	70 0	7 4 54 1	8	8	7 4 62 1		4 4 52 1	7	7	5 4 62 1	8	3	6 7 54 1		26 6 9	6 7 52 1	5 80		9 22	5 53		6 7	6 5 61	7 52		7c c q	6 7 62 1	6 5 80 1	2 6 52 8	8	8	: :	6	₹ • α	2 A	4 %	3 3	4 62

(0.2959 tuA/count (-Y)	0.2959 μA/count +Y)	0.2959 p.A/count +Y)	0.2959 µA/count +Y)	0.2959 µA/count +Y)	0.2959 µA/count +Y)	U.2959 µA/count + Y)	0.2959 uA/count +Y)						0.2959 µA/count -Y)	0.2959 µA/count -Y)	0.2959 µA/count -Y)	0.2959 µA/count -Y)	0.2959 ttA/count -Y)	0.2959 µA/count -Y)	0.2959 µA/count -Y)	0.2959 µA/count +Y)	0.2959 µA/count +Y)	0.2959 trAcount + Y)	0.2959 tvA/count +Y)	0.2959 μA/count +Y)	0.2959 p.A.count +Y)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits) Word 2 of 2 (second 8 bits)		Word 2 of 2 (second 8 bits)
Thruster uA			Thruster µA	_			indister pro	2		-	Thruster radians	Thruster radians	Normal µA			Normal IIA	-	_				Thruster uA	-		!	Innuster µA	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-In	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up Power-Up	Power-Up	Power-Up
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ADS SPUB	-	-	\dashv	-		AUS SPUB	ADS SPUB	-	 	+	ADS SPUB		ADS SPUA		+	ADS SPUA	+-	┼			+	ADS SPUA	┿	+-		TIRC SPILA	+-	\vdash		TIRC SPUA	+-	-	Н	4	TI&C SPUB	+	+	╀-		1	4	_	-	TI&C SPUA	╄	┦
CSS PITCH OUTPU	Πİ	CSS PITCH OUTP	CSS PITCH OUTPU	CSS PITCH OUTP	CSS PIICHOUIP	CSS PILCHOUR	CSS PITCH OUTPU		FILTERED CSS ROLL OUTPUT A (2 OF 2)	İ	B (1 OF 2)	(2 OF 2)	CSS ROLL OUTPUT	_	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT	PA CSS ROLL OUTPUT A (2 OF 2)	CSS ROLL OUTPUT	CSS ROLL OUTPUT	CSS ROLL OUTPUT A (1 OF	CSS ROLL OUTPUT A (2 OF 2)			CV BUFFER		Τ			Ī	CV BUFFER				i		CV BUFFER	CV BUFFER	CV BUFFER	CV BUFFER		CV BUFFER
WB CSSPITMB	-	\dashv	+	+	-	SSPII PB	-			1	LB CSSRFILB		MA CSSROLMA	\dashv	+	MA CSSROLMA	╁	┼-		-	+	PA CSSROLPA	十	+-		PB CSSROLPB	-			CVITA		 		1	CV128			<u> </u>	;			-	+	CVISA	+	
8 0 7	4 54 4 4 7 12	4 55 8 0 7 12	4 4 7 12	4 53 8 0 7 12	4 62 4 4 / 12	2 8 8 4 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	8 0 7 12	6 52 8 0 7	6 53 8 0 7 16	. 1	1 6 60 8 0 7 16 CSSRFILB	8 0 7 16	ш	55 8 0 7 12	54 4 7 12	1 8 67 4 4 7 12 CSSROLMA	8 8 0 7 12	62 4 4 7 12	Ľ	4 4 7 12	55 8 0 7 12	1 4 53 8 0 7 12 CSSROLPA	62 4 4 7 12	G 8 0 7 12	60 4 4 7 12	A 5 54 8 0 7 16 CV10A	5 55 8 0 7 16	5 62 8 0 7 16	5 8 8 0 7 16	A 6 52 8 0 / 16 CV11A	6 60 8 0 7 16	6 61 8 0 7 16	54 8 0 7 16	6 55 8 0 7 16	A 6 62 8 0 / 16 CV12B	50 0 0 7 16	7 53 8 0 7 16	7 80 8 0 7 16	7 61 8 0 7 16	7 54 8 0 7 16	8 0 7 16	7 62 8 0 7 16	7 8 8 0 7 16	A 8 52 8 0 7 16 CV15A A 8 53 8 0 7 16 CV15A	8 0 2 0	8 61 8 0 7

Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (Second o bits)	Word 1 of 2 (first 8 pits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (tiffst 6 bits)	Word 1 of 2 (first 8 bits)	T				First CVF (first word)	First CVE (first trans)	DIOM SHILL LAND SHILL	Second CVF (first word)	Second CVF (second word)	Second CVF (first word)	Second CVF (second word)	Third CVF (first word)	Third CVF (second word)	Third CVF (first word)	Fourth CVF (first word)
																				-																		0=No CVF Errors Revd	0=No CVF Errors Revd	1=CVF EITORS KCVd											
Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-In	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Un	Power-Up	Power-Up	ī		2 2	7 7	Ā	ΔII	₹ ₹	₹	₹	Al	₹	₹ ₹	A	N N
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SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPU B	SPUA	SPUA	SPU B	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	מומ	2000	Aprido	Spira	Spla	SPUA	SPUA	SPU B	SPUB	SPUA	SPUA	8040	O DIO	SPUA	SPUB	SPUB	SPUA	5	Spira	Alida	SPUB	a lid	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	Splia	SPUA
T&C					_		-	4	_		_	_	<u> </u>	Ш	<u> </u>	-	_	4		-	4	ي ع ا	+	+	4	+-	+-	-			-	+	٥	+	+-	 				2 2	+	+	Ļ	<u>:</u>	_	TT&C		-	282	-	+
CV BUFFER					BUFFER				BUFFER		CV BUFFER										CV BOTTER				CV BUFFER				BUFFER				CV BOLITER					COMMAND VERIFICATION ERROR		NOW ENAIGH				WF	SECOND CVF		VF		THIRD CVF		VF
CV16A	CV16A	CV16B	CV16B	CV1A	CV1A	CV1B	CVIB	CVZA	CVZA	CV2B	CV2B	CV3A	CV3A	CV3B	CV3B	CV4A	CV4A	CV4B	CV4B	CV5A	4 C C C C C C C C C C C C C C C C C C C	CV30	0000	CV6A	CV6B	CV6B	CV7A	CV7A	CV7B	CV7B	8 €	C 00 C	CVOB	S A S A S A S A S A S A S A S A S A S A	V6V5	CV9B	CV9B	CVERRA	99997	CVERAB	CVF1A	CVF1B	CVF1B	CVFZA	CVF2A	CVF2B	CVF2B	CVF3A	CVF3A	CVF3B	CVF4A
CV16A	CV16A	CV16B	CV16B	CVIA	CV1A	CV1B	CV1B	CVZA	CVZA	CV2B	CV2B	CV3A	CV3A	CV3B	CV3B	CV4A	CV4A	CV4B	CV4B	CVSA	A S	CVS B	0.00	CV6A	CV6B	CV6B	CV7A	CV7A	CV7B	CV7B	CV8A	2000	CVOD	Q (2)	CV9A	CV9B	CV9B	CVERRA	0,7000	CVENNE	CVF1A	CVF1B	CVF1B	CVFZA	CVF2A	CVF2B	CVF2B	CVF3A	CVE3B	CVF3B	CVF4A
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0 7	0	0	0	0	0	0 0	0 0	> 1 > 0	> r	0 0	0	0 /	0	0	0 2	0 0	0	0	0) r) 0) 0	- -	0	0	0 7	0	0	0	0 7	0 0	> ^ > C	> 0	0	0	0 7	0 7	2	,	+-	0 4	7 0	0 7	0 /	0 7	0 7	0	0 0	00	00	0 /
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Fourth CVF (second word)	Fourth CVF (first word)	Fourth CVF (second word)	Fifth CVF (first word)	Fifth CVF (second word)	Fifth CVF (first word)	CVF Time Stare	(third word)	CVF Time Stamp (fourth word)	CVF Time Stamp	(third word)	(fourth word)	CVF Time Stamp (first word)	CVF Time Stamp (second word)	CVF Time Stamp (first word)	CVF Time Stamp	TLM Flag Word 13 (second word)	TLM Flag Word 21 (second word)	TLM Flag Word 13 (second word)	TLM Flag Word 21 (second word)	2977						49	3019	49	3019	3022	3023	48	48	48			3024
																0=CVF Buffer Not Full 1=CVF Buffer Full	0=CVF Buffer Not Full 1=CVF Buffer Full	0=No CDU Contention	0=No CDU Contention 1=CDU Contention	Ċ.	0=0#	1=On 0=Off	1=Active O=Inactive	1=Active 0=Inactive											1=COM 0=ATO	1=COM 0=ATO	
																									Celsins												
N N	M	ΙΝ	A	₹.	₹	2	Al	₹		₹	₹	₹	₹	₹	IA	7	₹	ξ	Al	HOSS	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Lin	SSOH	SSOH	SSOH	SSOH	HOSS S	HOSS HOSS	SSOH	SSOH	SSOH	All Power-Up	All Power-Up	SSOH
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SPUA	SPUB	SPU B	SPUA	SPUA	SPUB	9F0 B	SPUA	SPUA		SPUB	SPUB	SPUA	SPU A	SPU B	SPUB	SPUA	SPU B	SPUA	SPU B	B0P	CDN	DGS	SBT	SBT	103	BDP-MP	ВОР	BDP-MP	9	3	BDP-MP	BDP-MP	BDP-MP	BDP-MP	SBT	SBT	80b
TT&C	J SC	2 1 1 8 2	28 L	200) - 	<u>ء</u>	Ω L	T&C	ļ	ည္ဆ ဆ	T&C	TT&C	T&C	Z Z Z	T&C	T &C	T&C	TT&C	TT&C	<u>8</u>	TT&C	T&C	78C	TT&C	SSM	+-		8	8	2 2		+-	-	8	18C	T&C	SON
FOURTH CVF	FOURTH CVF	FOURTH CVF	FIFTH CVF	FIFTH CVF	FIFTH CVF		CVF TIME STAMP LOWER (3 OF 4)	CVF TIME STAMP LOWER (4 OF 4)		CVF IIME SIAMP LOWER (3 OF 4)	CVF TIME STAMP LOWER (4 OF 4)	CVF TIME STAMP UPPER (1 OF 4)	CVF TIME STAMP UPPER (2 OF 4)	CVF TIME STAMP UPPER (1 OF 4)	CVF TIME STAMP UPPER (2 OF 4)		COMMAND VERIFICATION FULL	CDU CMD CONTENTION	CDU CMD CONTENTION	C-BAND XMIT PWR SETTING	DAMPER HEATER A ON/OFF	DAMPER HEATER BON/OFF	S-BAND UPLINK 1 ACTIVE	S-BAND UPLINK 2 ACTIVE	+X PAYLOAD PNL/DC-DC CONV I/F TEMP F	L3 OP FLAG DLYD CMD	DELCMDL3MROEN&INTSEL	L3 OP FLG DYLD CONST	DELCONL3MROEN&INTSEL	2&CNITIMEDELCONSIL3	SEC D.16 DATAENDADDR	DELAYED COMMANDED	DELAYED CONSTELLATION	DELAYED SSOH	S-BAND DOWNLINK 1 ON/OFF	S-BAND DOWNLINK 2 ON/OFF	Z&CNTTIMEDELSSOHL3
CVF4A	CVF4B	CVF4B	CVF5A	CVF3A	CVF5B	20.100	CVTMSTPA	CVTMSTPA	COTTO	CVIMSIPB	CVTMSTPB	CVTMSTPA	CVTMSTPA	CVTMSTPB	CVTMSTPB	CVFULLA	CVFULLB	CVWAITA	CVWAITB	CSMTRPWR	DAMPHTRA	DAMPHTRB	DARCVR1	DARCVR2	DCDCIFT	DCMDL3RO	DCMDMRO	DCONL3RO	DCONSMRO	DCONSISH DCONSISH	DDATAEND	DELCMD	DELCNSTL	DELSSOH	DL1	כום	DLSSOHH
CVF4A	CVF4B	CVF4B	CVF5A	CVF3A	CVF5B	200	CVFLOWA	CVFLOWA		CVFLCWVB	CVFLOWB	CVFTUPA	CVTUPA	CVFTUPB	CVFTUPB	CVFULLA	CVFULLB	CVWAITA	CVWAITB	CXMTRPWR	DAMPHTRA	DAMPHTRB	DARCVR1	DARCVR2	DCDCIFT	DCMDL3RO	DCMDMRO	DCONL3RO	CONSMRO	DCONSISH	DDATAEND	DELCMD	DELCNSTL	DELSSOH	סרו	סוס	DLSSOHH
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3025	3026	3027	49	3019	3001	3019	146	3020	3021	Thruster Flag Word 54 (first word)	Thruster Flag Word 62 (first word)	Thruster Flag Word 54	(DIOM 16 III)	(first word)	Dwell Address (first 4 of 12 bits)	Dwell Address (last 8 of 12 bits)	Ground Select Flag Word 52	+	Ground Select Flag Word 62	+~	(iiist word)	ADS Flag Word	ADS Flag Word	ADS Flag Word	ADS Flag Word	93	164	164			97	42	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)
										(0=-Y 1=+X 2=-X 3=-Z face	0=-Y 1=+X 2=-X 3=-Z face	10年11年11日	0=Odd Half	2=Both Halves			0=Do Not Abort EA Mode	0=Do Not Abort EA Mode	0=Do Not Abort EA Mode	0=Do Not Abort EA Mode	Celsius	0=No Earth Lock	O=No Earth Lock	0=Not in Ectipse	0=Not In Eclipse				1=Not Separated 0=Separated	1=Not Separated 0=Separated					
HOSS	HOSS	SSOH	HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	Thruster	Thruster	Thristor		Thruster	All Power-Up	All Power-Up	Thruster	Normal	Thruster	Thristor	9		Normal	Normal Thruster	Normal Thruster	SSOH	HOSS	SSOH	All Power-Up	All Power-Up	SSOH	SSOH	Power-Up	Power-Up	Power-Up
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BDP	ВОР	BDP	BDP-MP	BDP	8	<u>a</u>	BOP-IP	3 6	J D D	SPUA	SPU B	A LIGS		SPUB	1I	ULL	SPUA	SPUA	SPUB	a ldv	10S	SPUA	SPUB	SPU A	SPU B	BDP-MP	BDP-IP	BDP-IP	TIU	TIU	BDP-MP	BDP-MP	SPUA	SPUA	SPUB
NDS	SON	SON	SON	88	SON	8	8	3	3	TT&C	T&C	TRC	2	TI&C	T&C	T&C	TT&C	T&C	T&C	TIRC	MSS	Z Z) 28 L	T&C	11&C	SON	SON	SON	TT&C	TT&C	80N	8 <u>8</u>	T&C	TT&C	J&C
Z&CNTTIMEDELSSOHL3	Z&CNTTIMEDELCMDL3MRO	Z&CNTTIMEDELCMDL3MRO	L3 OP FLAG DLYD SSOH	DLSSOHL3MROEN&INTSEL			DELAYED SYSTEM TEST	20 ON THINEDELOTOLEOL	CACNI IIMEDELS (S)	- 1	DELTA VELOCITY THRUSTER FACE SELECT	DELTA VELOCITY THRUSTER SELECT	DELTA VELOCITA VELOCITA		~		EARTH ACQUISITION ABORT INDICATOR	EARTH ACQUISITION ABORT INDICATOR	EARTH ACQUISITION ABORT INDICATOR	EARTH ACQUISITION ABORT	EARTH PNL TEMP A	EARTHLOCK	EARTHLOCK	ECLIPSE INDICATOR	ECLIPSE INDICATOR			EE NOTVFYLASTPGWRITE	ELV/SV SEPARATED A	ELV/SV SEPARATED B	XFER MSG FLAG EOM	EOM ERROR COUNTER			SECOND ELEMENT OF ERROR BUFFER
DLSSOHL	DMROH	DMROL	DSSHL3RO	DSSOHMRO	DSISIPAR	DSYSTEST	DSYSISI	Deverer	USTSISIL	DVFACEA	DVFACEB	DVTHRA		DVTHRB	DWELADR	DWELADR	EAABRTA	EAABRTA	EAABRTB	FAARRTR	EAPNLAT	EARTHLKA	EARTHLKB	ECLIPSEA	ECLIPSEB	EDATAEND	EEPRGERR	EEWRTERR	ELVSEPA	ELVSEPB	EMXFRMSG	EOMERROR	ERRBUF1A	ERRBUF1A	ERRBUF1B
DLSSOHL	DMROH	DMROL	DSSHL3RO	DSSOHMRO	DSISIPAR	DSYSIESI	DSYSISI	Deverer	PSISISIF	DVFACEA	DVFACEB	DVTHRA		DVTHRB	DWELADR	DWELADR	EAABRTA	EAABRTA	EAABRTB	FAARRTR	EAPNLAT	EARTHLKA	EARTHLKB	ECLIPSEA	ECLIPSEB	EDATAEND	-	EEWRTERR	ELVSEPA	ELVSEPB	EMXFRMSG	EOMERROR	ERRBUF1A	ERRBUF1A	ERRBUF1B
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Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)								Ground Select Flag Word 52 (first word)	Ground Select Flag Word 54	Ground Select Flag Word 62	(first word)	Ground Select Flag Word 60 (first word)	RDMGMT Flag Word 54 (ripper balf-first word)	RDMGMT Flag Word 52	RDMGMT Flag Word 62	RDMGMT Flag Word 60	(upper nail-lifst word)	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts
									1=Off 0=On		1=Off 9=On	1=0ff 0=0n			1=Off 0=0n	0=No Rad Correction	0=No Rad Correction	0=No Rad Correction	1=Rad Correction	0=No Rad Correction	0=Test Disabled	0=Test Chabled	0=Test Disabled	0=Test Clisabled	I=I est chabled					
					counts	counts	counts	counts		Celsius			volts	Celsius												volts	volts	volts	volts	volts
Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Thruster	- Company	Normai	Normal	Thruster	Normal	Thurston		E SOLITION DE	Normal	Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster
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SPUB	SPUA	SPUA	SPU B	SPU B	SPUA	SPU A	SPU B	SPU B	ESA	ESA	ESA	ESA	ESA	ESA	ESA	SPU A	2	SFUA	SPUB	SPU B	A LIGO				SFU B	SPUA	SPUA	SPUB	SPUB	SPUA
TT&C	T&C	TT&C	TT&C	T&C	TT&C	T&C	T&C	787	ADS :	\$ \&	ADS	ADS	ADS	ADS	ADS	7.8°C	1	၌ -	TI&C	TT&C	7) (2 .	8 6	၌ -	ADS	ADS	ADS	ADS	ADS
1.5		ata İ		FIRST ELEMENT OF ERROR BUFFER	NUM ERR IN ERR BUFF SINCE LAST DUMP	NUM ERR IN ERR BUFF SINCE LAST DUMP	NUM ERR IN ERR BUFF SINCE LAST DUMP	NUM ERR IN ERR BUFF SINCE LAST DUMP	ESA 1 HCI ON/OFF	ESA 1 OKS IN LEGRATOR VOLTAGE ESA 1 THERMAL RING TEMP	ESA 1 STATIC MODE ON/OFF	ESA 2 HCI ON/OFF	ESA 2 ORS INTEGRATOR VOLTAGE	ESA 2 THERMAL RING TEMP	ESA 2 STATIC MODE ON/OFF			ESA KAUIANCE BIAS	ESA RADIANCE BIAS	ESA RADIANCE BIAS	CCA DATA DEADV	ESA DATA BEADY		ESA DATA READT	ESA DATA REAUT ESA E1 DETECTOR OUTPUT	(1 OF 2)	ESA E1 DETECTOR OUTPUT (2 OF 2)	ESA E1 DETECTOR OUTPUT (1 OF 2)	ESA E1 DETECTOR OUTPUT (2 OF 2)	ESA E2 DETECTOR OUTPUT (1 OF 2)
ERRBUF1B	ERRBUFA	ERRBUFA	ERRBUFB	ERRBUFB	ERRNUMA	ERRNUMA	ERRNUMB	ERRNUMB	ESATHCI	ESA10RSV ESA1RNGT	ESA1STAT	ESAZHIC	ESAZORSV	ESA2RNGT	ESAZSTAT	ESABIASA	4 0 4 0 4	ESABIASA	ESABIASB	ESABIASB	AGCAGE	ESAURA	מממאמ	ESAURB	ESAURB	ESAE1A	ESAE1A	ESAE1B	ESAE1B	ESAE2A
ERRBUF1B	ERRBUFA	ERRBUFA	ERRBUFB	ERRBUFB	ERRNUMA	ERRNUMA	ERRNUMB	ERRNUMB	ESA1HCI	ESA1CRSV ESA1RNGT	ESAISTAT	ESACHCI	ESAZORSV	ESA2RNGT	ESA2STAT	FSARIASA		ESABIASA	ESABIASB	ESABIASB	400	ESAURA	ממשלים	ESAURB	ESAURB	ESAE1A	ESAE1A	ESAE1B	ESAE1B	ESAE2A
7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	-	+	-	-	+-	7 8	-	-	+	7	2 1	2			+	-	-	7 13	7 13	7 13	7 13	7 13
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A 8 2	A 7 1	A 7	A 7 2	7	A 2	A 2 1	2	A 2 2	4	A 1 6 5	4	4	-		4	4	-	4	5 4	4 6	,		0 1		9	4 5 5	5	4 5	4	4 7

	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	RDMGMT Flag Word 52 (lower half-first word)
									:								:										0=Disabled 1=Enabled
	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	
Normal	Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal
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	SPUB	SPUB	SPUA	SPUA	SPU B	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPU B	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	8 NAS	SPUA	SPUA	SPUB	SPUB	SPUA
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ESA E2 DETECTOR OUTPUT	(1 OF 2)	ESA E2 DETECTOR OUTPUT (2 OF 2)	ESA E3 DETECTOR OUTPUT (1 OF 2)	ESA E3 DETECTOR OUTPUT	ESA E3 DETECTOR OUTPUT (1 OF 2)	ESA E3 DETECTOR OUTPUT (2 OF 2)	ESA E4 DETECTOR OUTPUT (1 OF 2)	ESA E4 DETECTOR OUTPUT (2 OF 2)	ESA E4 DETECTOR OUTPUT (1 OF 2)	ESA E4 DETECTOR OUTPUT (2 OF 2)	ESA ES DETECTOR OUTPUT (1 OF 2)	ESA ES DETECTOR OUTPUT (2 OF 2)	ESA ES DETECTOR OUTPUT	ESA ES DETECTOR OUTPUT (2 OF 2)	ESA E6 DETECTOR OUTPUT (1 OF 2)	DETECTOR	ESA E6 DETECTOR OUTPUT (1 OF 2)	ESA E6 DETECTOR OUTPUT (2 OF 2)	ESA EZ DETECTOR OUTPUT (1 OF 2)	ESA E7 DETECTOR OUTPUT (2 OF 2)	ESA E7 DETECTOR OUTPUT (1 OF 2)	ESA E7 DETECTOR OUTPUT (2 OF 2)				DETECTOR	EARTH SENSOR ASSEMBLY
	ESAE2B	ESAE2B	ESAE3A	ESAE3A	ESAE3B	ESAE3B	ESAE4A	ESAE4A	ESAE4B	ESAE4B	ESAE5A	ESAESA	FSAESB	ESAE5B	ESAE6A	ESAE6A	ESAE6B	ESAEGB	ESAE7A	ESAE7A	ESAE7B	ESAE7B	ESAE8A	ESAE8A	ESAE8B	EGARAG	ESAENA
	ESAE2B_	ESAE2B	ESAE3A	ESAE3A	ESAE3B	ESAE3B	ESAE4A	ESAE4A	ESAE4B	ESAE4B	ESAE5A	ESAE5A	FSAF5B	ESAE5B	ESAE6A	ESAEGA	ESAE6B	ESAE6B	ESAE7A	ESAE7A	ESAE7B	ESAE7B	ESAE8A	ESAE8A	ESAE8B	GCAERD	ESAENA
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	ESA E2 DETECTOR OUTPUT	7 60 5 3 7 13 ESAE2B ESAE2B (1 OF 2) ADS SPU B S Thruster volts	7 60 5 3 7 13 ESAE2B ESAE2B (1 OF 2) ADS SPU B S Thruster volts 7 61 8 0 7 13 ESAE2B (2 OF 2) ADS SPU B S Thruster volts	7 60 5 3 7 13 ESAE2B ESAE2B (1 OF 2) ADS SPU B S Thruster volts 7 61 8 0 7 13 ESAE2B (2 OF 2) ADS SPU B S Thruster volts 5 54 5 3 7 13 ESAE3A (1 OF 2) ADS SPU A S Thruster volts	7 (60) 5 3 7 13 ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Thruster Volts 7 (61) 8 0 7 13 ESAE2B ESAE2B (1 OF 2) ESA E2 DETECTOR OUTPUT ADS SPU B S Thruster volts 5 54 5 3 7 13 ESAE3A ESAE3A (1 OF 2) ADS SPU A S Thruster volts 5 54 5 13 ESAE3A (1 OF 2) ADS SPU A S Thruster volts 5 54 5 13 ESAE3A (1 OF 2) ADS SPU A S Thruster volts	7 60 5 3 7 13 ESAE2B ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Thruster Thruster volts 7 61 8 0 7 13 ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Thruster volts 5 54 5 3 7 13 ESAE3A (1 OF 2) Normal Normal 5 55 8 0 7 13 ESAE3A (2 OF 2) ADS SPU A S Thruster volts 5 55 8 0 7 13 ESAE3A (2 OF 2) Normal Normal 6 55 5 3 7 13 ESAE3A (2 OF 2) Normal Normal 6 55 5 5 5 9 10 Normal Normal 7 13 ESAE3B (1 OF 2) Normal Normal Normal Normal	7 60 5 3 7 13 ESAE2B ESAE2B (1 OF 2) ESAE2B (1 OF 2) ESAE2B (1 OF 2) SPU B S Thruster volts 7 61 8 0 7 13 ESAE2B (1 OF 2) COF 2) Normal Normal volts 5 54 5 3 7 13 ESAE3B (1 OF 2) Normal Normal Normal 5 55 8 0 7 13 ESAE3A ESAE3A ESAE3 DETECTOR OUTPUT ADS SPU A S Thruster volts 5 55 8 0 7 13 ESAE3A (2 OF 2) ADS SPU A S Thruster volts 5 55 5 3 7 13 ESAE3B ESAE3B COF 2) ADS SPU B S Thruster volts 5 55 5 3 7 13 ESAE3B	7 60 5 3 7 13 ESAE2B ESAE2B (1 OF 2) ESAE2B (1 OF 2) COT 2) SPU B S Thruster volts 7 61 8 0 7 13 ESAE2B (1 OF 2) ESAE2 DETECTOR OUTPUT ADS SPU B S Thruster volts 5 54 53 7 13 ESAE3A (1 OF 2) Normal Normal Normal 5 54 53 7 13 ESAE3A (1 OF 2) Normal Normal 5 56 5 3 7 13 ESAE3B ESAE3B <td< th=""><th>7 60 5 3 7 13 ESAE2B ESAE2B ESAE2B (1 OF 2) Normal Normal volts 7 61 8 7 13 ESAE2B ESAE2B (1 OF 2) Normal volts Normal 5 54 5 3 7 13 ESAE3B ESAE3B (2 OF 2) Normal volts 5 54 5 3 7 13 ESAE3A ESAE3A (1 OF 2) Normal volts 5 56 5 3 7 13 ESAE3A ESAE3A (2 OF 2) Normal volts 5 56 5 3 7 13 ESAE3B ESAE3B ESAE3B COF 2) Normal Normal 5 56 5 3 7 13 ESAE3B ESAE3B ESAE3B COF 2) Normal Normal 7 54 5 7 13 ESAE4A ESAE4A</th><th>7 80 5 3 7 13 ESAE2B ESAE2B (1 OF 2) Normal Normal volts 7 61 8 0 7 13 ESAE2B ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Thuster volts 5 54 5 3 7 13 ESAE3A ESAE3A (1 OF 2) Thuster volts 5 55 5 3 7 13 ESAE3A ESAE3B ESAE3B CO F 2) Thuster volts 5 55 5 3 7 13 ESAE3B ESAE3B CO F 2) Thuster volts 5 65 5 3 7 13 ESAE3B ESAE3B CO F 2) Thuster volts 5 65 5 3 7 13 ESAE3B ESAE3</th><th>7 50 5 3 7 13 ESAE2B ESAE2B (OF 2) ESAE2B (OF 2) SPU B SPU B</th><th>7 60 7 13 ESAE2B ESAE3B E</th><th>7 8 5 7 13 ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B COF 2) COF 2) SPUB S Thruster volts Normal volts SPUB S Thruster Volts SPUB</th><th>7 68 5 7 13 ESAE2B ESAE2B TESAE2B TOF 2) Thruster volts Normal 7 61 8 0 7 13 ESAE2B ESAE2B COF 2) ESAE2B COF 2) Thruster volts Normal volts Normal volts Normal volts SPU A SPU A</th><th>7 60 5 3 7 13 ESAE2B ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Normal volts SPU B S Thuster Volts S Thuster Volts SPU B S Thuster SPU B S Thuster SPU B SPU B S Thuster ADS SPU B S Thuster SPU B SPU B SPU B S<</th><th>7 68 5 7 13 ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ECAE2B ESAE2B ESAE2B ECAE2B ESAE2B ESAE2B ECAE2B ESAE2B ECAE3B ESAE3B ESAE3B</th><th> 1 1 1 1 1 1 1 1 1 1</th><th> 1</th><th> 1</th><th> 1</th><th> 1</th><th> 1 1 1 1 1 1 1 1 1 1</th><th> 1 1 1 1 1 1 1 1 1 1</th><th> 7 50 5 7 13 ESAEZB h><th> 1</th><th> 7 50 6 7 71 ESALEDE ES</th><th> 1 1 1 1 1 1 1 1 1 1</th></td<>	7 60 5 3 7 13 ESAE2B ESAE2B ESAE2B (1 OF 2) Normal Normal volts 7 61 8 7 13 ESAE2B ESAE2B (1 OF 2) Normal volts Normal 5 54 5 3 7 13 ESAE3B ESAE3B (2 OF 2) Normal volts 5 54 5 3 7 13 ESAE3A ESAE3A (1 OF 2) Normal volts 5 56 5 3 7 13 ESAE3A ESAE3A (2 OF 2) Normal volts 5 56 5 3 7 13 ESAE3B ESAE3B ESAE3B COF 2) Normal Normal 5 56 5 3 7 13 ESAE3B ESAE3B ESAE3B COF 2) Normal Normal 7 54 5 7 13 ESAE4A ESAE4A	7 80 5 3 7 13 ESAE2B ESAE2B (1 OF 2) Normal Normal volts 7 61 8 0 7 13 ESAE2B ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Thuster volts 5 54 5 3 7 13 ESAE3A ESAE3A (1 OF 2) Thuster volts 5 55 5 3 7 13 ESAE3A ESAE3B ESAE3B CO F 2) Thuster volts 5 55 5 3 7 13 ESAE3B ESAE3B CO F 2) Thuster volts 5 65 5 3 7 13 ESAE3B ESAE3B CO F 2) Thuster volts 5 65 5 3 7 13 ESAE3B ESAE3	7 50 5 3 7 13 ESAE2B ESAE2B (OF 2) ESAE2B (OF 2) SPU B SPU B	7 60 7 13 ESAE2B ESAE3B E	7 8 5 7 13 ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B COF 2) COF 2) SPUB S Thruster volts Normal volts SPUB S Thruster Volts SPUB	7 68 5 7 13 ESAE2B ESAE2B TESAE2B TOF 2) Thruster volts Normal 7 61 8 0 7 13 ESAE2B ESAE2B COF 2) ESAE2B COF 2) Thruster volts Normal volts Normal volts Normal volts SPU A SPU A	7 60 5 3 7 13 ESAE2B ESAE2B ESAE2 DETECTOR OUTPUT ADS SPU B S Normal volts SPU B S Thuster Volts S Thuster Volts SPU B S Thuster SPU B S Thuster SPU B SPU B S Thuster ADS SPU B S Thuster SPU B SPU B SPU B S<	7 68 5 7 13 ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ESAE2B ECAE2B ESAE2B ESAE2B ECAE2B ESAE2B ESAE2B ECAE2B ESAE2B ECAE3B ESAE3B ESAE3B	1 1 1 1 1 1 1 1 1 1	1	1	1	1	1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1	7 50 5 7 13 ESAEZB 1	7 50 6 7 71 ESALEDE ES	1 1 1 1 1 1 1 1 1 1	

RDMGMT Flag Word 54	(lower half-first word)	RDMGMT Flag Word 60 (lower half-first word)	RDMGMT Flag Word 62 (lower half-first word)	RDMGMT Flag Word 54 (upper half-first word)	RDMGMT Flag Word 52 (upper half-first word)	RDMGMT Flag Word 62 (upper half-first word)	RDMGMT Flag Word 60 (upper half-first word)																	Segmented rai curve to volte	Segmented cal curve to volts	Segmented cal clinye to volts	Segmented cal curve to volts	Segmented cal curve to volts
0=Disabled	1=Enabled	0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled	0=Test Disabled 1=Test Enabled	0=Test Disabled				:																	
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	EARTH SENSOR ASSEMBLY	EARTH SENSOR ASSEMBLY	EARTH SENSOR ASSEMBLY	ESA EARTH LOCK LOST	FILTERED ESA PITCH OUTPUT (1 OF 2)	FILTERED ESA PITCH OUTPUT (2 OF 2)	FILTERED ESA PITCH OUTPUT (1 OF 2)	FILTERED ESA PITCH OUTPUT (2 OF 2)	FILTERED ESA PITCH OUTPUT (1 OF 2)	FILTERED ESA PITCH OUTPUT (2 OF 2)	FILTERED ESA PITCH OUTPUT (1 OF 2)	FILTERED ESA PITCH OUTPUT (2 OF 2)		FILTERED ESA ROLL OUTPUT (2 OF 2)	FILTERED ESA ROLL OUTPUT (1 OF 2)	FILIERED ESA ROLL OUTPUT (2 OF 2)	FILTERED ESA ROLL OUTPUT (1 OF 2)		FILTERED ESA ROLL OUTPUT (1 OF 2)	FILTERED ESA ROLL OUTPUT	ESA S1 DETECTOR OUTPUT (1	ESA S1 DETECTOR OUTPUT (2 OF 2)	OUTPUT	ST DETECTOR	ESA S2 DETECTOR OUTPUT (1 OF 2)			
	ESAENA	ESAENB	ESAENB	ESALOCKA	ESALOCKA	ESALOCKB	ESALOCKB	ESAPITA	ESAPITA	ESAPITA	ESAPITA	ESAPITB	ESAPITB	ESAPITB	ESAPITB	ESAROLA	ESAROLA	ESAROLA	ESAROLA	ESAROLB	ESAROLB	ESAROLB				ESAS1B		
	ESAENA	ESAENB	ESAENB	ESALOCKA	ESALOCKA	ESALOCKB	ESALOCKB	ESAPITA	ESAPITA	ESAPITA	ESAPITA	ESAPITB	ESAPITB	ESAPITB	ESAPITB	ESAROLA	ESAROLA	ESAROLA	ESAROLA	ESAROLB	ESAROLB	ESAROLB	ESAROLB	ESASIA	ESAS1A	ESAS1B	ESAS1B	ESAS2A
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volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	voits	volts	volts	volts	volts	volts	volts	voits	volts	volts	volts	volts	volts	volts	volts	o volts	
Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Segmented cal curve to volts	Mode Flag Word
																											0=Null No Earth 1=Acquisition Process 2=Normal Process
volts	volts	volts	vofts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	volts	
Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal
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ESA S2 DETECTOR OUTPUT OF 2)	ESA S2 DETECTOR OUTPUT OF 2)	ESA S2 DETECTOR OUTPUT OF 2)	33 DETECTOR		ESA S3 DETECTOR OUTPUT OF 2)	ESA S3 DETECTOR OUTPUT OF 2)	ESA S4 DETECTOR OUTPUT OF 2)	ESA S4 DETECTOR OUTPUT OF 2)	ESA S4 DETECTOR OUTPUT OF 2)	ESA S4 DETECTOR OUTPUT OF 2)	ESA S5 DETECTOR OUTPUT OF 2)	ESA S5 DETECTOR OUTPUT OF 2)		ESA S5 DETECTOR OUTPUT OF 2)		ESA S6 DETECTOR OUTPUT OF 2)	ESA S6 DETECTOR OUTPUT OF 2)	ESA S6 DETECTOR OUTPUT OF 2)	ESA S7 DETECTOR OUTPUT OF 2)		37 DETECTOR		ESA S8 DETECTOR OUTPUT OF 2)	ESA S8 DETECTOR OUTPUT OF 2)	ESA S8 DETECTOR OUTPUT OF 2)	ESA S8 DETECTOR OUTPUT OF 2)	ESA SUBMODE
ESAS2A	ESAS2B	ESAS2B	ESAS3A	ESAS3A	ESAS3B	ESAS3B	ESAS4A	ESAS4A	ESAS4B	ESAS4B	ESAS5A	ESAS5A	ESAS5B	ESAS5B	ESAS6A	ESAS6A	ESASGB	ESASGB	ESAS7A	ESAS7A	ESAS7B	ESAS7B	ESAS8A	ESAS8A	ESAS8B	ESAS8B	ESASUBMA
ESAS2A	ESAS2B	ESAS2B	ESAS3A	ESAS3A	ESAS3B	ESAS3B	ESAS4A	ESAS4A	ESAS4B	ESAS4B	ESAS5A	ESAS5A	ESAS5B	ESAS5B	ESAS6A	ESAS6A	ESASGB	ESASGB	ESAS7A	ESAS7A	ESAS7B	ESAS7B	ESAS8A	ESAS8A	ESAS8B	ESAS8B	ESASUBMA
13	13	13	5	13	13	13	13	13	13	13	13	13	13	13	13	13	5	. 13	13	13	5	5	13	5	13	13	, 2
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Mode Flag Word	Mode Elay More	Mode Flag Word						Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 hits)	Word 1 of 2 (first 8 hits)	Word 2 of 2 (second 8 hits)	49	3066		49	88	3010	3053													Not displayed, used for SPINRT	
0=Null No Earth 1=Acquisition Process 2=Normal Process	0=Null No Earth 1=Acquisition Process 2=Normal Process	0=Null No Earth 1=Acquisition Process 2=Normal Process	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled O=Enabled	1=Disabled 0=Enabled							1=Disabled 0=Enabled								1=0n 0=0f					1=On 0=Off		1=0n 0=0ff	1=0n 0=0f	1=CEP 0=No CEP	
								counts	counts	counts	counts								volts	Volts	volts		volts	volts	Volts	NO P		volts				volts
Thrister	le El	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Power-Up	Power-Up	Power-Up	Power-Up	HOSS	HOSS	All Power-Up	HOSS	HOSS	HOSS	HOSS	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up
o.	0	ဟ	占	占	占	占	占	တ	ဟ	ဟ	တ	S	S	겁	S	S	S	S	₹	₹₹	AH	占	₹	₹	₹ ₹	₹	占	₹	占	占	겁	₹
SPUA	SPUB	SPUB	REA	REA	REA	REA	REA	SPUA	SPUA	SPUB	SPUB	BDP-MP	ВОР	REA	BDP-MP	BDP-MP	8	BOP	RAFS	RAFS	RAFS	RAFS	RAFS	RAFS	DAFC	RAFS	RAFS	RAFS	CAFS	CAFS	FSS	FSS
18°C	T&C	18C	RCS	RCS	RCS	వ్	RCS	TI&C	T&C	T&C	T&C	NDS	SON	RCS	8 2	SON	88	SON	d S	Z Z	TNP	TNP	TNP	d L	ב אב מאב	d	TNP	TNP	T. P.	TNP	ADS	ADS PBS
ESA SUBMODE	ESA SUBMODE	ESA SUBMODE	REA EVEN 0.2 LB POWER ENABLED	REA EVEN 0.2 LB X ENABLED	REA EVEN 0.2 LB Y ENABLED	REA EVEN 5.0 LB POWER ENABLED	REA EVEN 5.0 LB Z ENABLED	NUM OF GLOBAL EVENTS DUR BOOT	NUM OF GLOBAL EVENTS DUR BOOT		NUM OF GLOBAL EVENTS DUR BOOT	L3 OP FLAG EV_1	CLEAR EVMEM&RSTPOINT	REA EVEN CATBED HEATER ENABLED	L3 OP FLAG EV_SCEM STORF ALL DATA	SEC F,16 DATAENDADDR	PARALLEL FIFO RESET	QFSMODE=1, FREQ SETTING	FREG STD1 RB CAVITY OVEN	FREQ STD1 RB DC LIGHT	FREQ STD1 RB LAMP OVEN	RAFS 1 28 VDC ON/OFF	FREQ STD1 VCXO CNTRL COLT	FREG SIDZ RB CAVIIY OVEN	FRED STD2 RR DC1 IGHT	FREQ STD2 RB LAMP OVEN	RAFS 2 28 VDC ON/OFF	FREQ STD2 VCXO CNTRL VOLT	CAFS HEATER 28 VDC ON/OFF	CAFS 28 VDC ON/OFF	FSS 1 CEP STATUS	FSS 1 FINE COSINE VOLTAGE
ESASUBMA	ESASUBMB	ESASUBMB	EVENZPWR	EVEN 2X	EVEN2Y	EVENSPWR	EVENSZ	EVENTNA	EVENTNA	EVENTNB	EVENTNB	EVIL3RO	EVMEMPNT	EVNCBHTR	EVSCL3RO EVTSTORE	FDATAEND	FIFORST	FREGSET	FS1CAVO	FS1LITE	FS1LMPO		\Box	FSZCAVO			1	FS2VCXOV	FS3HTR	FS3PWR	1	FSS1COSV
ESASUBMA	ESASUBMB	ESASUBMB	EVEN2PWR	EVEN2X	EVEN2Y	EVENSPWR	EVENSZ	EVENTNA	EVENTNA	EVENTNB	EVENTNB	EVIL3RO	EVMEMPNT	EVNCBHTR	EVSCL3RO EVTSTORE	FDATAEND	FIFORST	FREGSET	FS1CAVO	FS1LITE	FS1LMPO	FS1PWR	FS1VCXOV	FS2CAVO	FSZLITE	FSZLMPO	FS2PWR	FS2VCXOV	FS3HTR	FS3PWR	FSS1CEP	FSS1COSV
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Gray Code equivalent value	1=On	5		1=CEP 0=No CEP		Gray Code equivalent value	1=0n 0=0f			1=Normal 0=Xstrap	1=Normal D=Xetran																					- C	O-Curbut											
		volts	volts		volts			volts	volts										affort	SIOA MOIES	Alloy	volts	volts	volts	SIION I	VOIIS			amps															
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ADS	υ V	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	TNP	d N.	SON	SON	82	88	8	8	8	3 2	3 2	2	S S	NDS	902	3 5	32	808	SON	SQ.	3 2	2 2	2	3 2	808	SON	NDS	SON	S2 N	8	8	2 2	38	80	80N
FSS 1 COARSE SUN ANGLE GRAY CODE	ESS.1 28VDC ONVOEE	FSS1 FINE REF BIAS VOLTAGE		FSS 2 CEP STATUS	FSS 2 FINE COSINE VOLTAGE	FSS 2 COARSE SUN ANGLE GRAY CODE	FSS-2 28 VDC ON/OFF	FSS 2 FINE REF VOLTAGE	FSS 2 FINE SINE VOLTAGE		MDU CONV B TO VCXO/FSU A (AND A TO B) XSTRAP	BDD DATA DISABLE	BDP DATA DISABLE	BDW DATA DISABLE	BDW PARITY FLAG	BDX DATA DISABLE	BDY DATA DISABLE	DIG -5.25 VDC SWITCH	EN GUR EEPROM REFRES	GDR + 28 VDC	GDR DIGITAL + 5 25 VDC		GDR RF +7 VDC	GDR DIGITAL -10 VDC	GUN DIGITAL -3.23 VUC	DIG ARIES PWRSETTING	ARIES STATE 1	NPMS BDY BYTES/EPOCHCNT	GDR CURRENT	COMMAND ERROR COUNT	RESEI GUR SEI COMMANUS	Oli ATAG GGG GGG	SERIAL DATA ERR CNT	DIGITAL PWR SUPPLY TEMP	GDR EEPROM REFRESH	GDR EOM ERROR FLAG	RST GDR POINTERS & FLGS	DISABLE GDR FUNCTIONS	GIM RESET ACKNOW-GDR	GIM RESET REQ-GDR	ENABLE GUR GIM ERRICHK	GDR CHANNEL GIM RESET	GDR PROCESSOR INIT	GDR PROCESSORINITSEL
FSS1CRSE	FCC1DA/B	FSS1REFV	FSS1SINV	FSSZCEP	FSS2COSV	FSS2CRSE	FSS2PWR	FSS2REFV	FSS2SINV	FSUNRM	FSHXST	GBDDATA	GBDPDATA	GBDWDATA	GBDWPAR	GBDXDATA	GBDYDATA	GDM5.25V	CDEERFEN	GDRP2RV	GNRP525V	GDRP5V	GDRP7V	GDRM10V	SUNIOS V	GDRAPWR	GDRASTAT	GDRBDYC	GDRC	GDRCMDER	GDRCONFR	CDDDATA	GDRDATER	GDRDPST	GDREERF	GDREOMER	GDRFLRST	GDRFUNC	GDRGIMAC	GDRGIMRQ	GDRGMECK	GDRGMRST		GDRITYPE
FSS1CRSE	FCC1DA/ID	FSS1REFV	FSS1SINV	FSS2CEP	FSS2COSV	FSS2CRSE	FSS2PWR	FSS2REFV	FSS2SINV	FSUNRM	FSUXST	GBDDATA	GBDPDATA	GBDWDATA	GBDWPAR	GBDXDATA	GBDYDATA	GD-5.25V	GUEERFEN CDP+10/	GDR+10V	GUR+5.25	GDR+5V	GDR+7V	GDR-10V	SDR-3.23	GDRAPWR	GDRASTAT	GDRBDYC	GDRC	GDRCMDER	GURCONFR	ATAGGG	GURDATER	GDRDPST	GDREERF	GDREOMER	GDRFLRST	GDRFUNC	GDRGIMAC	GDRGIMRO	GDRGMECK	GDRGMRST	GDRINIT	GDRITYPE
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37.4	374	374	374	371	2980	383	147	147	174	SSOH Byte 3444	SSCH Byte 3445	35	150	2988	2980	7987	377	378	379	380	2984	374	374	374	369	370	2993	7667														211	211				
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SON	SQN	88	800	SQN	SON	8	8	8	900	2 2	3 2	88	SON	SON	2 2	3 2	88	808	8	8	8	S .	88	8	2 2	3 2	2 2	78T	S S	TI&C	TT&C	7 2 2	2 C	ي ا ا	2 C C C	T&C	TT&C	18C	200	178C	TI&C	80N	88	T&C	T&C	ļ	TI&C
L4 EED ARM	L4 DEPLOYED	L4 EED ENABLE	L4 STOWED	DIG NUC DETMONPWRSET	DISABLE GDR MRO MSGS	OP NOT PERFORMED CNT	GDR PARITY ENABLE	GUR OUD/EVEN PARITY	CDP POWER STIRE X 7 VINC	GOR POWER SUPPLY A / VDC	IP GDR GIM ERROR FLG	RF POWER SUPPLY TEMP	GDR SOH RECEIVAL CNT	GDR SELECTION	SEND ODE SOH MSGS	+	DIGITAL STATE 1	DIGITAL STATE 2	DIGITAL STATE 3	DIGITAL STATE 4	ENABLE GDR SYSTEM TEST	SYNTH LOCK 1	SYNIH LOCK 2		BOX LEMPERATORE	OAC GOOD	ENABLE GDR UPLOAD	+X+Y GEN TEMP A	+X+Y GED TEMP B	-X+Y GED TEMP A	-X+Y GED TEMP B	GLOBAL EVENT COUNTER (1 OF 2)	GLOBAL EVENT COUNTER (2 OF 2)	GLOBAL EVENT COUNTER (1 OF 2)	GLOBAL EVENT COUNTER (1 OF 2)	GLOBAL EVENT COUNTER (2 OF 2)	GLOBAL EVENT COUNTER (1 OF 2)	GLOBAL EVENT COUNTER (2 OF 2)	GLOBAL EVENT COUNTER (2 OF 2)	GLOBAL EVENT COUNTER (1 OF 2)	GLOBAL EVENT COUNTER (2 OF 2)	GIM PARITY	GIM PARITY ENABLE	GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)	GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)
GDRL4ARM	GDRL4DEP	GDRL4ENA	GDRL4STO	GDRMPWR	GDRMRO	GURCHAR	GURFAR	CORPAROL	SURPROIN VCAPORAN	GDRPSB7V	GDRRECER	GDRRFPST	GDRSHRCV	GDRSLCT	GDRSOHSD	GDRSTAT	GDRSTAT1	GDRSTAT2	GDRSTAT3	GDRSTAT4	GURSISI	GDRSYLK1	GURSYLKZ	GURSYLK3	GURTENIE	0 0 000	GDRUPLEN	GFDPX1T	GEDPX2T	GEDMX1T	GEDMX2T	GEDCNTA	GEDCNIA					GEDCNIB		GEDCNTB	GEDCNTB	GIMPAR	GIMPAKEN	GNDCMCTA	GNDCMCTA	GNDCMCTA	GNDCMCTA
GDRL4ARM	GDRL4DEP	GDRL4ENA	GDRL4STO	GDRMPWR	GDRIMRO	SURCENE CONCORDED	CDDDARAR	GURPARUE	GURPAATV	GDRPSB7V	GDRRECER	GDRRFPST	GDRSHRCV	GDRSLCT	GDRSOHSD	GDRSTAT	GDRSTAT1	GDRSTAT2	GDRSTAT3	GURSTA14	GURSISI	GURSYLKI	GURSTLAZ	GURSYLKS	GNRTBANE	ח ופו ופרב	GDRUPLEN	GED+X1T	GED+X2T	GED-X1T	GED-X2T	GEDCNIA	GEDCNIA	GEDCNIA	GEDCNTA	GEDCNTA	GEDCNTB	GELICATE	GEDCNTB	GEDCNTB	GEDCNTB	GIMPAR	GIMPAKEN	GNDCMCTA	GNDCMCTA	GNDCMCTA	+
NA NA NA 5	NA NA NA 7	NA: NA NA 4	NA NA NA 6 NA	NA NA O	NA NA NA S	NA NA NA NA O NA 8	NA NA NA NA	NA NA NA 7	7 24 8 0	8 24 8 0 7	NA'NA NA 7 NA	NA NA NA 0	NA NA NA	NA NA NA NA 1	NA NA NA A	NA NA NA NA 7 NA 1	NA NA NA NA O NA 8	NA NA NA O NA	NA NA NA O	NA NA NA	¥ :		7 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6	NA NA NA NA S	NA NA NA O NA NA O	NA NA NA A NA	NA NA 4	2 8 58 8 0 7 8	58 8 0 7	3.58 8 0 7	4 58 8 0 7	7 14 8 0 /	2 2 2 2 0 7 16	8 8 8 0 7 7	4 54 8 0 7	4 55 8 0 7	7 22 8 0 7	3 8 63 8 0 7 16	8 8 0 7	5 4 62 8 0 7 8	<u>4</u> 8	∑	<u>-</u>	A 5 14 8 0 7 16	A 5 15 8 0 7 16	8 8 52 8 0 7 16	1

								Mode Flag Word					۰	23 (second word)	2984	2985	3064	3051	3047	3047	345	325	359	291	306	278	283
								0=Off 1=RN 2=SOH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	0=Off 1=RN 2=SOH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	0=Off 1=RN 2=SOH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	0=Off 1=RN 2=SOH 3=SHES 4=EAH 5=SK 6=SNP 7=EHYS	O=No Cmds Rcvd (No U/L) 1=At Least One Cmd Rcvd (Have U/L)	O=No Cmds Rcvd (No U/L) 1=At Least One Cmd	RCVG (Have U/L)													
counts	sunos	counts	sjunoo	counts	sjunoo	ş ili	counts																				
Thruster	Thruster	Early Orbit	Early Orbit	Normal	Normal	Thrister	Thruster	Normal	Thruster	Normal	Thruster	Power-Up		HOSS HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	HOSS	SSOH
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SPUA	SPUA	SPUB	SPU B	SPU B	SPU B	SPUB	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	alido	BDP-IP	BDP	80b	3 6	9	ВОР	BDP	\$ \$ \$ \$	BDW	BDW	BDW		MOM MOM	BDW
78,0	TT&C	Tr&C	787	TRC	T&C	18C	T&C	17&C	7.8°C	TT&C	T&C	TT&C	787	SS	NDS	808	2 2	80 80 80 80 80 80 80 80 80 80 80 80 80 8	SQN	8 8	3 8	SS	SON	SON	8 8	38	SS .
GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)	GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)	GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)	GROUND CMD ACCEPT COUNT (1 OF 2)	GROUND CMD ACCEPT COUNT (2 OF 2)	GNDMODEA GROUND COMMANDED ADS MODE	GROUND COMMANDED ADS MODE	GNDMODEB GROUND COMMANDED ADS MODE	GROUND COMMANDED ADS MODE	FLAG INDIC AT LEAST ONE GND CMD RCVD	FLAG INDIC AT LEAST ONE GND		GDR SYSTEM TEST EXECUTE	GDR DISCRETE SYS TEST	DONTSNDHIBAND B DATA	THREE CH CONCURRENCE	HI BAND CHANNEL SEL	HIBANDFALSEALARMRATE	HIGH BAND FREQ STEP	LACC - HIGH BAND CH1	HIBANDCH1AUXDELCORR CTI	CENTERFREQ-HIBANDCH2	DELAY CORRECT-HIBANDCH1		A/D VALUE-HIBAND CH1
GNDCMCTA	GNDCMCTA	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDMODEA	GNDMODEA	GNDMODEB	GNDMODEB	GRDCONTA	GROCONTR	1		GSTSTZEX	HBBBFDAT	1		HBFARTH				T	HBHCDC		HBHCGCAL
GNDCMCTA	GNDCMCTA	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDCMCTB	GNDMODEA	GNDMODEA	GNDMODEB	GNDMODEB	GRDCONTA	GROCONTR	GRPXFER	GSTST1EX	GSTSTZEX	HBBBFDAT	HBCONCUR	HBFARCH	HBFARTH	HBFREGST	HBHCACMD	HBHCADC	HBHCCF	HBHCFTC	HBHCGAIN	HBHCGCAL
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HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	SSCH	FO.00	HOS S	1000	HOSS	HOSS	HOSS	HOS	HOUS	SSOH	SSOH	SSOH	HOSS	All Power-Up		All Power-Up	HOSS	HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	1	Thrister in I		T.	1.	-		Thruster	T
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NUB VIOLE	RDD/X	MOR	BDW	BDW	ВОР	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	BDW	ا ا	BDW BDW	200	200	200	200	7 Z	\ \C		BOW	BDW	BDW	FSA		ESA	200	000	909	BDP	BDP-IP	BDP-IP	BDD/X	80P-IP	SPUA	SPUB	Spila	Allda	SPUA	SPU B	SPUB	SPUA
NPS N	+	+	900	1	_		_	88	4	_	_	4			SS		-	-		800	4	+	3 2	+	+	+	_	1	+	-		NDS	ADS	 -	ADS	┿	+	NDS	NDS	\vdash	88	+	88		+	+-	Ans	+	+++	ADS Social	
MID A/D VAL HIBNIDCH1		=	SSET	SSET			CORRE CTI		IBANDCH3				MID A/D VAL-HIBNDCH3				HIGH BAND CH 3 THRESSET		-	CTI		DELAY CORRECT. HIBANDCH2	FICV HIBAND CHZ:HILO	GAIN SEI HIBAND CHZ			BOW FIIGH BAND ON Z	THOUSE THE COURT OF THE COURT	HIGH BANDON 2 THRESSET	EN HIGH BAND CHAN 2	HI BAND CHAN SELECT	AUTO HI BAND OFFSET	ESA 1 HC! HIGH!! OW RATE		ESA 2 HCI HIGH/LOW RATE	EVENI HEADER ERA CIVI	HARDASIC CADERREPORT	HARDEEPROMFAILREPORT	HARD MEM ERR REPORTS		BDX/D EV CUM DMP COUNT	_	_		IMPULSE DEMAND PITCH (2 OF 2)	INTO 11 SE DENAMAN DITCH (2 OF 2)	IMPOUSE DEMAND BOLL (1 OF 2)	IMPULSE DEMAND NOCE (1 %) 2/	IMPULSE DEMAND ROLL (1 OF 2)	IMPULSE DEMAND ROLL (2 OF 2)	IMPULSE DEMAND YAW (1 OF 2)
UDDUCA A A D	HEHCMM	HEHCROWN	HBHCTH	HBHCTHOF	HBHCTRIG	HBLCACMD	HBLCADC	HBLCCF	HBLCDC	HBLCFTC	HBLCGAIN	HBLCGCAL	HBLCMAD	HBLCNM	HBLCRCMD	нвгстн	HBLCTHOF	HBLCTRIG	HBMCACMD	HBMCADC	HBMCCF	HBMCDC	HBMCFIC	HBMCGAIN	HEMCGCAL	HEWCMAD	HEWCNW.		HEMCTHOE	HEATTER	HBNOISCH	HBNOISTH	немерате	5	HCI2RATE	TOKEKON I	HRDASCSM	HRDFESM	HRDMEMSM	116KDMPP	IBDDUMP	IDLELOOP	nı		MPPITA			MPROLA	IMPROLB	IMPROLB	IMPYAWA
CONTOUR	_	1	4_	HBHCTHOF	HBHCTRIG	HBLCACMD					HBLCGAIN		HBLCMAD	HBLCNM	HBLCRCMD	HBLCTH	HBLCTHOF	HBLCTRIG	HBMCACMD			!	_	_			HUNGUNG	4	HEMCIH	Cigrowan	HBNOISCH	BHNOISTH	UCHEATE	1	-+		HEADER	HRDFFSM	HRDMEMSM	116KDMPP	IBDDOWNP		=		MPPITA	\perp		MPROLA MPROLA			IMPYAWA IMPYAWA
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		O=No Interrupt Error Rcvd TLM (Error) Flag Word 52 1=Interrupt Error Rcvd (first word)	cvd TLM (Error) Flag Word 52 (first word)	O=No Interrupt Error Rcvd TLM (Error) Flag Word 60 1=Interrupt Error Rcvd (first word)	O=No Interrupt Error Rcvd TLM (Error) Flag Word 60 1=Interrupt Error Rcvd (first word)	3060	254			3008	2988	2988	138	3008	3000	3000	<u>~~</u>	2993	2992	3036	3008	159	150	150	89	3008	3036	9	9	3036	148	3008	185	3036	142	3008	2993	2992	146	159	180
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IMPULSE DEMAND YAW (1 OF 2)	IMPULSE DEMAND YAW (2 OF 2)	INTERRUPT ERROR INDICATOR	INTERRUPT ERROR INDICATOR	INTERRUPT ERROR INDICATOR	INTERRIPT ERROR INDICATOR	INTEGRATION PERIOD	BDY-P INTERSTATBT:UNDIN	FLAG INDIC INVALID U/L STATUS	FLAG INDIC INVALID U/L STATUS	DISABLE IP A/D INTER	INCREMENTING PATTERN	MARCHING RAM TEST	BDX/D EVLD DISABL FLG1	ENIP BDWGIM ERCHKING	ENIP BDXGIM ERCHKING	ENIP BDYGIMERCHKING	CMD HISTORY POINTER	IP DOMP REGISTED IN DEFINES	ENBDP IP EEPROM REFR	IP EV&ERRQUEUECNTRST	ENIP GDRGIM ERCHKING	WHS EVLD DISABL FLG1	WHX E LD DISABL FLG1	INTRPROCINIT&SWAPSEL	WLS EVLD DISABL FLG!	NICA EVED DISABLE I COI	RESET IP POINT&FLAGS	IP RAM SWAPPED	IP ROM SWAP	IP SET COMMAND RESET	IP SOH XFER COUNTER	SELECT DSOH FOR IP	IP SOH REQUEST	IP STACK FOIL IER	MOTONPITCH EVOMPCNT	INHIP HRDWRTIMOUTINT		ENABLE BDP IP UPLOAD	UPLOAD ALLOW	YD EVLD DISABLE FLG1	YLT EVLD DISABL FLG2
	IMPYAWB	INTERRA	INTERRA	INTERRB	INTERRA	Т	INTROERR	INVSTATA	INVSTATB	IPADINT	IPATRN	IPATTST	IPBDEVLD	PIBDWECK	PIBDXECK	IPBDYECK	IPCMHSTP	IPDUMP	IPEERFEN	IPEQCRST	IPGDRECK	IPHSEVLD	IPHXEVLD	PINIT	IPLSEVLD	IPMESINT	IPPFLRST	IPRAMSWP	IPROMSWP	IPSCMRST	IPSHXFR	HOSOH	IPSOHREQ	IPSIACAF	PTCHOMP	IPTOINT	IPUPLD	IPUPLEN	IPUPLOAD	IPYDEVLD	IPYLEVLD
IMPYAWB	IMPYAWB	INTERRA	INTERRA	INTERRB	INTERR	INTPER	INTROERR	INVSTATA	INVSTATB	IPADINT	IPATRN	IPATTST	IPBDEVLD	IPBDWECK	IPBDXECK	IPBDYECK	IPCMHSTP	IPDOMP	IPEERFEN	IPEQCRST	IPGDRECK	IPHSEVLD	IPHXEVLD	IPINIT	PLSEVLD	IPLAEVLD	IPPEI RST	IPRAMSWP	IPROMSWP	IPSCMRST	IPSHXFR	HOSOH	IPSOHREQ	PSIACRE	IPTCHOMP	INCLUSION	IPUPLD	IPUPLEN	IPUPLOAD	IPYDEVLD	IPYLEVLD
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82	88	8	SQN	TNP	TNP	TNP	2	N ON O	dNF	dNL	TNP	SON	స్ట	స్ట	RCS	బ్ద	స్ట	స్ట	NDS	808	808	8 <u>8</u>	dNF	dNT DN	A.	d d	T P	dNT	TA D	d N	d N	TNP
YMP EVLD DISABL FLG2	FLG2	YS EVLD DISABLE FLG!	YT EVLD DISABLE FLG1	CIDU A RCVR AGC VOLTAGE	CTDU A RCVR TO RCVR ANT CTDU A RCVR CONV VOLTAGE	CTDU A RCVR 28VDC ON/OFF	CLOS BACAN AGO VOLIAGE	CTDU B RCVR CONV VOI TAGE	CTDU B RCVR 28 VDC ONIOEE	CTDU A RCVR ON/OFF	CTDU B RCVR ON/OFF	MOTION ROLL EVDMPCNT	ISO LATCH VALVE PWR 182 ARM	ISO LATCH VALVE PWR 1&2 ENAB	ISOLATN LATCH VALVE 1 CLOSE	ISOLATN LATCH VALVE 2 CLOSE	ISOLATN LATCH VALVE 1 OPEN	ISOLATN LATCH VALVE 2 OPEN	WH A EV CUM DMP CNT	WHS B EV CUM DMP CNT	WL A EV CUM DMP CNT	WLS B EV CUM DMP CNT	CTDU A XMTR TO XMTR ANT	CTDU A XMTR CONV VOLTAGE MON	CTDU A XMIT 28 VDC ON/OFF	CTDU A XMTR RF PWR OUT	CTDU B XMTR TO XMTR ANT	CTDU B XMTR CONV VOLTAGE MON	CTDU B XMTR 28 VDC ON/OFF	CIDU B XMTR RF PWR OUT	CTDU A XMTR ON/OFF	CTDU B XMTR ON/OFF
IPYPEVLD	PYREVLD	PYSEVLD	IPY IEVLD	IRCVAAGC	IRCVAANT IRCVACV	IRDVAPWR IRCVBAGC		IRCVBANT	IRCVBPWR	IRCVRA	IRCVRB	IROLLDMP	ISO12ARM	ISO12PWR	ISOCLS1	ISOCLS2	ISOOPN1	ISOOPN2	_	╅	IWLSADMP	IWLSBDMP	IXMTAANT	IXMTACV		IXMTAREP	IXMTBANT	IXMTBCV		IXMIBREP		
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SQN NDS	SON	SON	╁	NDS	ADS	ADS	ADS.	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	1 %C	TT&C	T&C	T8C	TI&C	TT&C	TT&C	TRC	TNP	TNP	TNP	TNP	dNT	TNP	TNP
YD EV CUM DUMP COUNT	YF EV CUM DUMP COUNT	YF TMPBUFF I/P POINT	YF TMPBUFFO/P POINT	YF TEMP BUFF QUE CNT	DELTA-V JET SECONDS TIMER (1 OF 2)	JET SECON	DELTA-V JET SECONDS TIMER (1 OF 2)	DELTA-V JET SECONDS TIMER (2 OF 2)	DELTA-V JET SECONDS ACHIEVED (1 OF 2)	DELTA-V JET SECONDS ACHIEVED (2 OF 2)	DELTA-V JET SECONDS ACHIEVED (1 OF 2)	DELTA-V JET SECONDS ACHIEVED (2 OF 2)	DELTA-V JET SECONDS DURATION (1 OF 2)	DELTA-V JET SECONDS DURATION (2 OF 2)	DELTA-V JET SECONDS DURATION (1 OF 2)	DELTAV JET SECONDS DURATION (2 OF 2) BASE PNI IK-BOX IF TEMP A		KG-46-1 CONV +5VDC OUT	KG-46 (2) ON/OFF	KG-46-2 CONV +5VDC OUT	VCC WORD 3 AUTHENTICATE BIT	VCC WORD 3 BUSY BIT	VCC WORD 3 AUTHENTICATE BIT	VCC WORD 3 BUSY BIT		L11/L2 CONV B 28 VDC ON/OFF	L11/L2 CONV A STATUS ON/STBY	L11/L2 CONV B STATUS ON/STBY	I 1 HPA A STATUS	L1 HPA A INTERNAL TEMP	L1 HPA B STATUS
IYDDUMP	IYFDUMP	IYFTBIP		1	JETIMERA (JETIMERA (JETIMERB		JETSECAA (JETSECAB		JETSECDA	JETSECDA	i		T	5V		KG2CV5V	KIR1AUTH	KIR1B	KIR2AUTH		L12CAPWR	112CBPWR	L12CVA	L12CVB	1 1HPAA	LIHPAAT	L1HPAB
IYDDUMP	IYFDUMP	IYFTBIP	IYFTBOP	IYFTBQUE	JETIMERA	JETIMERA	JETIMERB	JETIMERB	JETSECAA	JETSECAA	JETSECAB	JETSECAB	JETSECDA	JETSECDA	JETSECDB	JETSECDB	N C	KG1CV5V	KG2	KG2CV5V	KIR1AUTH	KIR1B	KIRZAUTH	KIR2B	L12CAPWR	112CBPWR	L12CVA	12CVB	LIHDAA	LIHPAAT	L1HPAB
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Celsius	Celsius			Celsius		wafts		watts		watts					Celsius		Celsius	Celsius				watts		watts		watts						
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TNP	MSS	TNP	TNP	MSS	TNP	TNP	dNT	TNP	TNP PNF	TNP	TNP	TNP	TNP	dNL	TNP	TNP	dN1	MSS	TNP	dNF	d N	dNT	TNP	ďΝΤ	TNP	TNP	TNP	TNP			200	TNP P
L1 HPA B INTERNAL TEMP	+X PAYLOAD PNUL1 HPA I/F TEMP C	L1/L2 CONV A TO L1 HPA A (AND B TO B) NORM	L1/L2 CONV B TO L1 HPA A (AND A TO B) NORM	+X PAYLOAD PNL/L2259 IPA I/F TEMP D	L1/L2 CONV A TO L1 IPA A (AND B TO B) NORM	L1 MOD/IPA RF PWR OUT	L1/L2 CONV B TO L1 MOD IPA A (AND A TO B) XSTRAP	L1 HPA RF PWR OUT:L1 TOTAL	L1/L2 CONV A TO L TO B) NORM	- 1	L1/L2 CONV B TO L1 SYN A (AND A TO B) XSTRAP	L1/L2 CONV A L1 XMIT ON/OFF	L1/L2 CONV B L1 XMIT STATUS	L2 HPA A STATUS	L2 HPA A INTERNAL TEMP	L2 HPA B STATUS	L2 HPA B INTERNAL TEMP	+X PAYLOAD PNUL2260 HPA I/F TEMP B	L1/L2 CONV A TO L2 HPA A (AND B TO B) NORM	L1/L2 CONV B TO L2 HPA A (AND A TO B) XSTRAP	L1/L2 CONV A TO L2 IPA A (AND B	L2 MÓD/IPA RF PWR OUT	L1/L2 CONV B TO L2 MOD IPA A (AND A TO B) XSTRAP	L2 HPA RF PWR OUT:L2 TOTAL	L1/L2 CONV A TO L2 SYN A (AND B TO B) NORM	L2 SYNTHESIZER RF PWR OUT	L1/L2 CONV B TO L2 SYN A (AND A TO B) XSTRAP	L1/L2 CONV A L2 XMIT STATUS	L1/L2 CONV B L2 XMIT STATUS	L3 BDX EVENT COUNTER	L'3 BUFF FULL FLAG FIRST BYTE OF INCONT	L3 CONV A STATUS ON/STBY
L1HPABT	L1HPAIFT	L1HPANRM	L1HPAXT	L1PAIFT	L1IPANRM	L11PARFT	L1IPAXST	LIRFP	LISYNNRM	SLSYNRFP	LISYNXST	L1XMTCVA	L1XMTCVB	LZHPAA	LZHPAAT	L2HPAB	LZHPABT	L2HPAIFT	LZHPANRM	LZHPAXST	LZIPANRM	L2IPARFP	LZIPAXST	L2RFP	LZSYNNRM	L2SYNRFP	L2SYNXST	L2XMTCVA	L2XMTCVB	L3BDXEVT	L3COUNT	L3CVA
L1HPABT	L1HPAIFT	L1HPANRM	L1HPAXST	L1IPAIFT	L1IPANRM	L1IPARFP	L1IPAXST	L1RFP	L1SYNNRM	L1SYNRFP	L1SYNXST	L1XMTCVA	L1XMTCVB	L2HPAA	LZHPAAT	LZHPAB	L2HPABT	L2HPAIFT	LZHPANRM	L2HPAXST	LZIPANRM	LZIPARFP	L2IPAXST	L2RFP	LZSYNNRM	L2SYNRFP	L2SYNXST	L2XMTCVA	L2XMTCVB	L3BDXEVT	L3COUNT	L3CVA
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1=On	1=Standby 0=On							1=Connected 0=Not Connected		1=Connected 0=Not Connected			1=Norma 0=Xstrap	1=Xstrap 0=Normal				1=Normal 0=Xstrap		1=Xstrap 0=Normal	:												1									
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All Power-Up	All Power-Up	All Power-Up	SSOH	SSOH	SSOH	SSOH	SSOH	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	SSOH	SSOH	SSOH	All Power-Up	All Power-Up	All Power-Up	HOSS	HOSS HOSS	SSOH	SSOH	SSOH	SSOH	HOSS	HOSS	SSOH	HOSS	HOSS	500	HOSS	HOSS HOSS	SSOH	SSOH	HOSS	HOSS	SSOH	HOSSOH	All Power-Up	SSOH
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TNP	TNP	TNP	80N	SON	88	NDS	SON	J. P.	TNP	Z.	d N	MSS	TNP	d N L	SON	SON	NDS	d NT	TNP	TA	SON	22 22	SON	SON	SON	SON	2 2	88	SON	SON	8	2 2	3 2	3 2	38	SON	SON	SON	8	8 2	S P	NDS
L3 CONV A 28 VDC ON/OFF	L3 CONV B STATUS ON/STBY	L3 CONV B 28 VDC ON/OFF	L3 EV_I MAX SECTION	L3 EV INIT O/P POINT	L3 EV INITIATED O/P SEC	INH L3 FIFO INTERRUP	L3 FULL, RM IN NON L3	L3 HPA A STATUS	L3 HPA A INTERNAL TEMP	1	L3 HPA B INTERNAL TEMP +X PAYLOAD PNL/L2261 HPA I/F	TEMP A	L3 CONV A TO L3 HPA A (AND B TO B) NORM	L3 CONV A TO L3 HPA B (AND B TO A) XSTRAP	L3 INPUT POINTER	L3 INPUT SECTION	5	L3 CONV A TO L3 MOD IPA A (AND B TO B) NORM	L3 MOD/IPA RF PWR OUT	L3 CONV A TO L3 MOD IPA B (AND B TO A) XSTRAP	L3RDOTSEC2&3-IPUP32K	L3RDOTSEC4&5-MPLO32K	L3RDOUTSEC889-PAGE 1	L3RDOUTSECA&B-PAGE 2	L3RDOUTSECC&D-PAGE 3	L3RDOUTSECE&F-PAGE 4	L3 MEM KEADOUI POIN!	13 NAV BLK INS FRED	L3 FEEDME FLAG	L3 NEXT SECT, ENTRY 1	L3 NEXT SECT, ENTRY 2	L3 NEXT SECT, ENTRY 3	LA NEXT SECT ENTRY 4	LONEAL SECTIONING S	L3 NEXT SECT, ENTRY 7	L3 NEXT SECT, ENTRY 8	L3 NEXT SECT, ENTRY 9	L3 NEXT I/P POINTER	L3 NEXT O/P POINTER	L3 OUTPUT POINTER	13 HPA RF PWR OUT 13 TOTAL	
L3CVAPWR	L3CVB	L3CVBPWR				L3FIFOIN	L3FULL	L3HPAA		ГЗНРАВ	L3HPABT	L3HPAIFT	L3HPANRM	L3PHAXST	L3INPTP	L3INSEC	L3INTER	L3IPANRM	L3IPARFP	L3IPAXST	L3MRO23	L3MRO45	13MRO89	L3MROAB	L3MROCD	L3MROEF	LAMRODEO	I 3NAVINS	L3NOFULL	}	- 1		LONGENA		L3NSEN7	L3NSEN8	L3NSEN9	L3NSINP	L3NSOUTP	L3OUTPTP	13RFP	L3STAGE2
L3CVAPWR	L3CVB	L3CVBPWR	L3EVIMAX	L3EVNTOP	L3EVOSEC	L3FIFOIN	L3FULL	L3HPAA	L3HPAAT	L3HPAB	L3HPABT	L3HPAIFT	L3HPANRM	L3HPAXST	L3INPTP	L3INSEC	L3INTER	L3IPANRM	L3IPARFP	L3IPAXST	L3MRO23	L3MRO45	1 3MROR9	L3MROAB	L3MROCD	L3MROEF	LAMKOOP	I 3NAVINS	L3NOFULL	L3NSEN1	L3NSEN2	L3NSEN3	LONGENA	CNUCENC	L3NSEN7	L3NSEN8	L3NSEN9	L3NSINP	L3NSOUTP	L3OUTPTP	13RFP	L3STAGE2
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	1=Normal	0=Xstrap	1=Xstrap	0=Normal							1=Enabled 0=Disabled	1≂Enabled 0=Disabled																														0=Not Exectued	1=Executed	0=Not Exectued 1=Executed	0=Not Exectued	1=Executed
Celsius		watts												:															:																	
All Power-Up		All Power-Up		All Power-Up	HOSO S	1000	500	HOSS HOUS	1000	HOSSOH	All Power-Up	All Power-Up	SSOH	HOSS	SSOH	1000	HOSS HOSS	HS S	HOSS.	HOSS	HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	HOSS	HOSS	HOSS	SSOH	SSOH	SSOH	HOSS CH	HOSS	HOU	HOSS	HOU	HOSS	SSOH	HOSS	SSOH	Normal	Thruster	Normal Thruster	Normal	Thruster
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+X PAYLOAD PNUL2261 SYNTH I/F TEMP A	L3 CONV A TO L3 SYN A (AND B TO	B) NORM L3 SYNTHESIZER RF PWR OUT	L3 CONV A TO L3 SYN B (AND B TO	A) XSTRAP	L'S TURN-ON COND ME I	LO LONNICIO INCIDENTE	13 WHO B BLIEF EV ONT	13 WI A RIFF EV CNT	13 WIS BRIFF EVENT	ABORT L3 TRANSFER	L3 CONV A L3 XMT STATUS		L3 YD EVENT COUNTER	L3 YF EVENT COUNTER	TURNOFFI OBAND A BUFF	CONTRACTOR OF FOT	LOW BAIND CHAN SELECT	1 ACC - LOW BAND CH1	CENTERERED I OBANDCH1	DELAY CORRECT. I OBANDCH1	FTCV LOBAND CHI:HILO	GAIN SET LOBAND CH1	A/D VALUE-LOBAND CH1	MID A/D VAL-LOBNDCH1	BDW LOW BAND CH 1	LRCC - LOW BAND CH1	LOW BAND CH 1 THRESSET	COV BAND CH I INKESSE!	LACC - LOW BAND CH2	CENTERFREQ-LOBANDCH2	DELAY CORRECT- LOBANDCH2	FTCV LOBAND CH2:HILO	GAIN SE I LOBAND CHZ	AU VALUE-LOBAND CHZ	BUNITORIO VALLOCINO	I BCC - I OW BAND CH 2	I OW BANDOH 2 THRESSET	I OW BAND CH 2 THRESSET	EN LOW BAND CHAN 2	LOW BAND CHAN SELECT	AUTO LOW BAND OFFSET	1	LOAD SHED SET 1 EXECUTED	LOAD SHED SET 1 EXECUTED		LDSH2EXA LOAD SHED SET 2 EXECUTED
L3SYNIFT		L3SYNNRM L3SYNRFP			LSICCOND	T	LSVVHABE 34/HBBE	13MI ARE	1 3WI BBF	L3XFER	4		1		LBABUFF	LEBERDAI	Ī	1	-T-	T	LBHCFTC		Π.	LBHCMAD		۵	T	- PUCTON	LBMCACMD	1	LBMCDC	LBMCFTC	1	LEMCGCAL	1	6		PMCTHOF	IBMCTRIG	BNOISCH	Т	1	LDSH1EXA	LDSH1EXB		LDSH2EXA
L3SYNIFT		L3SYNNRM L3SYNRFP		L3SYNXST	LSTONDET	PONDICT.	LSWHADE	1 3MI ARE	1 3WI RRF	L3XFER	L3XMTCVA	L3XMTCVB	L3YDEVT	L3YFEVT	LBABUFF	LEBELDAI	LEFARCH		TOTAL TOTAL	BUCD	LBHCFTC	LBHCGAIN	LBHCGCAL	LBHCMAD	LBHCNM	LBHCRCMD	LBHCTH		LBMCACMD	LBMCCF	LBMCDC	LBMCFTC	LBMCGAIN	LEMCGCAL	- DANCING	- PACECIAIN	- BACTU	PANCTHOE	BMCTRIG	BNOISCH	LBNOISTH		LDSH1EXA	LDSH1EXB	-	LDSH2EXA
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Power Flag Word	Power Flag Word	Power Flag Word																			79067	3067	163											
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			counts	counts	counts	counts	counts	counts	counts	counts	counts	counts	counts	counts	Celsius	Celsius Celsius	Celsius		Celsius		Celsius		,	counts	spuns Sounds	counts	counts	counts	counts	counts	Sunds	counts	counts	Souns
Normal Thruster	Normal Thruster	Normal Thruster	Early Orbit	Early Orbit	Normal	Normai	Thruster	Thruster	Early Orbit	Early Orbit	Normal	Normal	Thruster	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	HOSS	HOSS	Power-up	Power-up	Power-up	Early Orbit	Normal	Normal	Thruster	Farly Oxbit	Early Orbit	Normal	Normal
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LOAD SHED SET 2 EXECUTED	LOAD SHED SET 3 EXECUTED				LOW LEVEL EVENT COUNTER (1 OF 2)				VEL EVENT	VEL EVENT	LOW LEVEL EVENT COUNTER (1 OF 2)			LOW LEVEL EVENT COUNTER	RCS LINE TEMP A	RCS LINE TEMP B	RCS LINE TEMP D	LLED A ON/OFF	LLEDATEMP	LLED B ON/OFF	LLED B TEMP	LOAD PROGRAM & WAIT	LAST SENSORDIRECTOMD	LAST VALID CHECKSUM (1 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (1 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (1 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (2 OF 2)	LAST VALID CHECKSUM (1 OF 2)	LAST VALID CHECKSOW! (4 C) 47
LDSH2EXB	LDSH3EXA	LDSH3EXB	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LINAT	LINBT	LINDT	LLEDAPWR		LLEDBPWR	LLEDBT	PAVAIT	LSDCMD	LVCKSMPA	LVCKSMPB	LVCKSMPB	LVCKSUMA	LVCKSUMA	LVCKSUMA	LVCKSUMA	LVCKSUMA	LVCKSUMB	LVCKSUMB	LVCROUMD
LDSH2EXB	LDSH3EXA	LDSH3EXB	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTA	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LEDCNTB	LINAT	LINBT	LINDT	LLEDAPWR	LLEDAT	LLEDBPWR	LLEDBT	L PACIT	LSDCMD		LVCKSMPB		L.	LVCKSUMA	_		LVCKSUMA			LVCKSUMB
1-9	7	7 1	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	+	7 8	7 8	7	7 8	4	7 8	- F	- 8 Y Y	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	7 16	116
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		193	71	Word 1 of 2 (first 8 bits)- 1750a fault reg format	Word 2 of 2 (second 8 bits)-	Word 1 of 2 (first 8 bits)-	Word 2 of 2 (second 8 bits)-	000 = MAF 1 through	111 = MAF 8	3044	3044	3045	28							3 E					Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)	Word 1 of 2 (first 8 bits)	Word 2 of 2 (second 8 bits)		2080	2990	2991	3066	3062	2988	000 = MIF 1 through	111 = MIF 8	155	8	
								Binary equivalent-1 of									1=Enabled	pelq	1=C=0	1=On 0=Off	1=Enabled 0=Disabled	1=Enabled 0=Disabled	1=On 0=Standby	1=On 0=Standbv				MOLI Men Noe 0.127	0=SRAM	1=PKOM						Binary equivalent-1 of	decimal values 1 to 8			
counts	counts										:			volts	volts	volts	SIOA																						counts	counts
Thruster	Thruster	SSOH	SSOH	Power-Up	Power-Un	Dater In	Double	do-lawor	All Power-Up	SSOH	HOSS	HOSS	HOSS	All Power-Up	All Power-Up	All Power-Up	do-lawo i liu	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Power-Up	Power-Up	Power-Up	All Power-Up		All Power-Up	HOSS	SSOH	SSOH	SSOH	SSOH HOS		All Power-Up	SSOH HOSS	Early Orbit	Early Orbit
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SPUB	SPUB	BDP-IP	BDP-MP	SPUA	SPUA	a lidy	a la	200	₽	BOP	908 908	900	BDP-MP	Σ	NE NE		3	20 5	20	MDC	CDU	DG5	MDU	MDU	SPUA	SPUA	SPUB	MDIS		80P	BDP	ВОР	ВОР	вор	BDP BDP-MP		TIC.	80P-IP 80P-IP	SPUA	SPUA
TI&C	T18C	8	<u>80</u>	TT&C	TIRC	TT&C) Z	3	ည္ရ <u>င</u> ္	8	8 8	88	SQN SQN	J.	A.	d N		78C	ည္ခ ဗ	TI&C	TT&C	T&T	TNP	TNP	T&C	ည္ဆင္	S S S S S S S S S S S S S S S S S S S	JAP C	Ç	SON	SON	SON	NDS	SON	S S	+-	_	8 8	-	\dashv
LAST VALID CHECKSUM (1 OF 2)	LAST VALID CHECKSUM (2 OF 2)	YF IMPFUBLASTADDRUSE		CONTENTS OF FAULT REGIOF LAST MACH ERR	CONTENTS OF FAULT REG OF LAST MACH ERR	CONTENTS OF FAULT REG OF LAST MACH ERR	CONTENTS OF FAULT REG OF LAST MACH ERR		MASTER FRAME COUNTER	HIGH BAND CH SELECT	MAN HIBAND I HRESHVAL LOW BAND CHAN SEI FOT	MAN LOBAND THRESHVAL	BDX/D EVENT DUMP COUNT	MDU A VOLTAGE MON 1	MDU A VOLTAGE MON 2	MDU A VOLTAGE MON 1		MDU BYPASS MODE ENA/DISA	MICO A 20 VIC ON/OFF	MDU CONV B 28 VDC ON/OFF	CDU A MDU CLK ENADISA	CDU B MDU CLK ENA/DISA	MDU CONV A STATUS ON/STBY	MDU CONV B STATUS ON/STBY	LAST MDU INPUT DATA READ	LAST MDU INPUT DATA READ	LAST MDU INPUT DATA READ	MDU MESSAGE NUMBER	ACM CINIT ACENODY CONTRACTION	MEM LOAD ADDR(8MSB)	MEM LOAD ADDR(8 LSB)	MEMORY LOAD DATA	DISABLE MEMORYPARITY	MEM PARITYERR REPORT	MEMORY SELECTIONBITS INT ERR FLG(MES S-D)		MINOR FRAME COUNTER	MP+IP CMD ERR CUMCNI MP+IP CMD OPNOT CNT	MEMORY LOAD COUNTER (1 OF 2)	MEMORY LOAD COUNTER (2 OF 2)
LVCKSUMB	LVCKSUMB	LYFADDR	M16KDMPP	MACHERRA	MACHERRA	MACHERRB	MACHERRB	_		MANHECH	MANLBCH	MANLBTH	МВООИМР	MDUAV1	MDUAV2	MDUBY	$\overline{}$	MIDUBYPAS		MDUCBPWR	MDUCLKA	MDUCLKB		MDUCVB			MDUDALAB					_		5	MEMSICI			MIPCMONF		
		_	16 M16KDMPP	16 MACHERRA	16 MACHERRA	16 MACHERRB	16 MACHERRB		3 MAFRIMONT	4		6 MANLBTH		_	1	8 MDUBV2	+	MDUBYPAS	YAAL COOM	1 MDUCBPWR	1 MDUCLKA	1 MDUCLKB	1 MDUCVA	1 MDUCVB	-		16 MUUUAIAB		Tation	8 MEMLDH	_		1 MEMPAR	4	MEMSICI MFSINTER	-	_	MIPCMONE	MLOADCTA	MLOADCTA
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					ADS Flag Word	ADS Flag Word	ADS Flag Word	ADS Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	Mode Flag Word	h Mode Flag Word	211	2969	217	3013	2000	2969	- Se	45	47	47
					0=Thrusters 1=Torquers	0=Thrusters 1=Torquers	0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Mode Did Not Converge 1=Mode Converged	0=Do Not Allow Autonomous Mode Switch 1=Allow Autonomous Mode Switch	0=Do Not Allow Autonomous Mode Switch 1=Allow Autonomous Mode Switch	0=Do Not Allow Autonomous Mode Switch 1=Allow Autonomous Mode Switch	O=Do Not Allow Autonomous Mode Switch 1=Allow Autonomous Mode Switch													
counts	Counts	counts	counts	counts												· · · · · · · · · · · · · · · · · · ·										
Normal	Farty Orbit	Early Orbit	Normal	Normal	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal	Thruster	Normal	Thruster	Normal	Thruster	Normal	Thruster	HOSS	HOSS	HOSS	HOSS	HOSS CH	TOSS OF	HOSS	HOSS	SSOH	SSOH
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SPU A	S D D	SPUB	SPUB	SPUB	SPU A	SPU B	SPU A	SPU B	SPUA	SPUA	SPUB	SPUB	SPU A	SPUA	SPU B	SPUB	BDY	BDY	ADA	BOP	g 2	200	ADD-MP	BDP-MP	BDP-MP	BDP-MP
7 T & C	+-	+-	1	TT&C	TT&C	11&C	T1&C	T & C	17&C	TT&C	71&C	TI&C	TL&C	T&C	T&C	S E	SON	NDS	NDS	8	802	82 2	2 2	32	SON	88
MEMORY LOAD COUNTER (1 OF 2)	+	+-	NTER (1 OF 2)		INLOADING	MGMT UNLOADING	A MGMT UNLOADING	A MGMT UNLOADING	ADS MODE CONVERGENCE INDICATOR	ADS MODE CONVERGENCE INDICATOR	ADS MODE CONVERGENCE INDICATOR	ADS MODE CONVERGENCE INDICATOR	MODSWCHA AUTONOMOUS ADS MODE SWITCH	MODSWCHA AUTONOMOUS ADS MODE SWITCH	AUTONOMOUS ADS MODE SWITCH		MOTION INTERRUP	HIGH/LOW SAMPLE RATE	HIGH/LOW RATE	BDPSTORCNTRLFORMOTDT	DISABMOTIONMEMOVRWRT	DISABLOVERWRITMOTION	SAVE MOTION	EVID DISABLE FLOOR	MP DUMP PAGE NUMBER	MP DUMP
MLOADCTA	_	MICACCIB		MLOADCTB		1	-	_	MODCNVA	MODCNVA	MODCNVB	MODCNVB	MODSWCHA	MODSWCHA	MODSWCHB	aHUWbdCW	MOINTMSK	MOSAMPRI	MOSRATE	MOSTORE	MOTMOVRT	MOTOVRT	MOTSAVE	MPCMHSIP	MPDMPPG	MPDUMP
MLOADCTA	MLCALCIA	MICAUCIB	MLOADCTB	MLOADCTB		+			MODCNVA	MODCNVA	MODCNVB	MODCNVB	MODSWCHA		MODSWCHB	anJohandan	MODSVOID	MOSAMPRT	MOSRATE	MOSTORE	MOTMOVRT	MOTOVRT		MPCMHSIP	MPDMPPG	MPDUMP
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BDP-MP	9	90P	BDP-IP	90B	BDP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	8	8	BDP-MP	BDP-MP	90	BDP-IP	BDP-IP	BDP-MP	BDP-MP	80 B	ВОР	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	DG	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BDP-MP	ชีบห-พิษ เ	BDP-MP	BDP-MP	806	BDP-MP	BDP-MP	BDP-MP	BDP-MP	BOP-MP	100 100 100 100 100 100 100 100 100 100	מטיישר	BDP-MP
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MPDXEVLD EV LD DISABLE FLG1:BDX		MPEERFEN ENBOP MP EEPROM REFR		MPEQCRST STORE-ALL RESET		MPHSEVLD EV LD DISABLE FLG1:WHS	۵	\dashv	MPLSEVLD EV LD DISABLE FLG1:WLS		DISABMPMASFRMS		-	MP ROM SWAP	T MP SET CMDS RES	\neg	MP SOH REQUEST	MP STACK POINTE	П	UPLOAD BDP MP	MPUPLEN ENABLE BDP MP UPLOAD		MPYDEVLD EV LD DISABLE FLG1:YD		MPYPEVLD EV LD DISABLE FLG2:YMP	MPYREVLD EV LD DISABLE FLG2:YMR		MPYTEVLD EV LD DISABLE FLG1:YT	MROLL MOTION ROLL COUNTER	MROLLDMP MOTION ROLL EV CNT	MSGMODE SERIAL MESSAGE MODE ON/OFF	i	_	MWHSBDMP WHS B EVENT DUMP CNT	-	_		MYFDUMP YF EVENT DUMP COUNT	MYFTBIP YF TMP BUF I/P POINT	MYFTBOP YF TMP BUF O/P POINT			NL3BDEVT NON-L3 BX EV/BDD CNT		NL3INSEC NON-L3 INPUT SECTION	NL3LIGHT NON-L3 LIGHTNING EV CNT	DISABNONL3MEMC	ヿ	NONL3 NEXT SEC	NONL3 NEXT SECT	NONL3 NEXT I/P P	\neg	NL3WHBBF NON-L3 WHS B BUF CN I	NL3WLABF NON-L3 WL A BUF CN I	IL3WLBBF NON-L3 WLS B BUF CNT
A NA NA NA 3 NA 1 MPDXEVLD MI	NA NA NA NA 3 NA 1 MPEERF N	NA NA NA NA 3 NA 1 MPEERFEN ME		NA NA NA NA 6 NA 1 MPECCRST ME		NA NA NA NA 1 MPHSEVLD M	NA NA NA 6 NA 1 MPHXEVLD	NA NA NA 8 MPITCH	NA NA NA 5 NA 1 MPLSEVLD	NA NA NA 7 NA 1 MPLXEVLD	NA NA NA 5 NA 1 MPMFSINT	NA NA NA 7 NA 1 MPPFLRST	NA NA NA 4 NA 1 MPRAMSWP	_	NA NA NA 4 NA 1 MPSCRMRST	NA 4 MPSHRCV	5 NA 1 MPSOHREQ	ᆛ	П		_	NA NA NA NA 0 NA 1 MPUPLOAD	NA NA NA NA 2 NA 1 MPYDEVLD MI	NA NA NA NA 2 NA 1 MPYLEVLD M	NA NA NA NA O NA 1 MPYPEVLD MI	NA 1 NA 1 MPYREVLD		NA NA NA NA 1 NA 1 MPYTEVLD M	NA NA NA O NA 8 MROLL	NA NA NA NA NA 0 NA 8 MROLLDMP MI	A A 43 1 6 6 1 MSGMODE M	NA NA NA 6 NA 1 MTSTL3RO		NA NA NA NA O NA 8 MWHSBOMP M	-	0 NA 8 MWLSBDMP	NA'NA NA 0 NA 8 MYDDUMP			0 NA 16 MYFTBOP	NA NA NA 0 NA 8 MYFTBQUE		NA:NA NA 0 NA 8 NL3BDEVT		NA NA NA NA 4 NA 4 NL3INSEC N	NA NA NA NA O NA 8 NL3LIGHT N	NA NA NA 2 NA 1 NL3MOVRT	NA NA NA 4 NA 4 NL3NSEN1	_	NA 4 NA 4 NL3NSEN3	0 NA 8 NL3NSINP	NA NA NA O NA 8 NL3WHABF	NA NA NA O NA 8 NL3WHBBF	O NA 8 NL3WLABE	NA NA NA NA O NA 8 NLOWLBBF N

18	16	3063	ADS Flag Word	ADS Flag Word	3050	221	221	211	29/0 211									47															!		2971
			0=Not in Noon/Midnight Region 1=In Noon/Midnight Region	O=Not in Noon/Midnight Region Noon/Midnight Region						1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled D=Fnabled	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled 0=Enabled	1=Disabled 0=Enabled				1=No Overcurrent	0=Overcurrent			1=No Overcurrent	0=Overcurrent				The state of the s					
									!										ΨΨ	volts	Celsius		μĄ	siov .	Ceisius		amps	amps	amps		In-IDI-sec	in-lbf-sec	in-lbf-sec	in-lbf-sec	
HOSS	SSOH	SSOH	Normal Thruster	Normal Thruster	SSOH	SSOH	SSOH	SSOH	SSOH	All Power-Up	All Power-Up	All Power-Up	All Dower-I in	All Power-Up	All Power-Up	All Power-Up	All Power-Up	SSOH	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Normal	Normal	Thruster	Normal Thruster	Normal Thruster	SSOH
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\vdash	_	SON	17&C		SON	SS .	8	SON	2 2 2 2 2 2 2	87	S S	స్ట	ű	3 2	SS	5,0	<i>y</i> .		TT&C	TT&C	7 & C	TT&C	TL&C	18C) - -	TT&C	EPS	3	2 N	3	ADS	ADS	ADS	ADS	NDS
NON-L3 YD EV COUNTER		QFS=3, NOISE THRESH LEVEL	NOON-MIDNIGHT INDICATOR	NOON-MIDNIGHT INDICATOR	NOISE MONCHHI/LOBAND	NPMS DATA STORE	NPMS BAND PASS GAIN SEL		NPMS DATA TESTINTERRUPT NPMS RANGE	OCU A ENABLED/DISABLED	OCU B ENABLED/DISABLED	REA ODD 0.2 LBF POWER ENABLED	DEA ODD 0.21 BE Y ENIAB! ED	REA ODD 0.2 LBF Y ENABLED	REA ODD 501 BF POWER ENABLED	PEA ODD 5 0 1 BF 7 ENABLED	REA ODD CATBED HEATER	PAGE DISABLE	PCE A C/S CAL MON	PCE A CONV +5VDC OUT	PCE A CONV TEMP	PCE A DPC OVERCURR FAULT	PCE B C/S CAL MON	PCE B CONV +5VDC OUT	PCE B CONV TEMP	PCE B DPC OVERCURR FAULT	BUS CURR TO PCE HI-PWR (T1)	BUS CURR TO PCE HI-PWR (T2)	BUSS CURR TO PCE LO-PWR		PITCH MOMENTUM ERROR (1 OF 2)	PITCH MOMENTUM ERROR (2 OF 2)	. –	DITCH MOMENTI IM ERROR (2 OF 2)	DISABLE PITCH MSGS
\Box		NOISETH	NOONMIDA	NOONMIDB	NOSMONCH I	NPMSDATA I		J	NPMSRNT	 		Œ	1		Q		CONTROLLED	PAGEDIS	i	 _	PCEACVT	PCEAOVRC	PCEBCAL	PCEBCV5V	PCEBCVI	PCEBOVRC	PCECURH1	PCECURH2	PCECURLO	7	PITCHMEA	PITCHMEA	PITCHMEB	PITCHMEB	PITCHMST
NL3YDEVT	NL3YFEVT	NOISETH	NOONMIDA	NOONMIDB	-	NPMSDATA	NPMSGAIN	NPMSIMSK	NPMSINT	OCUA	OCUB	ODDPAWR) and o	YAJUU	ODDSDAVB		COCCELTE	PAGEDIS	PCEACAL	PCEACVSV	PCEACVT	PCEAOVRC	PCEBCAL	PCEBCV5V	PCEBCVT	PCEBOVRC	PCECURH1	PCECURH2	PCECURLO	FEET.	PITCHMEA	PITCHMEA			
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217	SSOH Byte 3418	207	2967																	Thruster Flag Word 54 (first word)	Thruster Flag Word 62 (first word)	2958	2969	Word 1 of 2 (first 8 bits) format dep on port read	Word 2 of 2 (second 8 bits) fmt dep on port read	Word 1 of 2 (first 8 bits) format dep on port read	Word 2 of 2 (second 8 bits)	3066	47	264		
																				0=Primary 1=Backup	0=Primary 1=Backup											1=Enabled 0=Disabled
=	Celsius			radians	radians	radians	radians	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec						!						Celsius	
HOSS	All Power-Up	SSOH	SSOH	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Thruster	Thruster	Thruster	Thruster	Normal	Normal	Normal	Normal	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Thruster	Thruster	HOSS	SSOH	Power-Up	Power-Up	Power-Up	Power-lin	HOSS	HOSS	HOSS	All Power-Up	All Power-Up
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₽Q	ВОУ	BDY	908	SPUA	SPUA	SPUB	SPU B	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPU B	BOP	8	SPUA	SPUA	SPUB	a lav	80P	BDP-MP	BDD/X	25 Z	MTC S
SON	<u>8</u>	80N	828	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	18C	7.8C	NDS	88	TT&C	TT&C	TI&C	1180	SON	SQN	808 808	MSS	§ §
PITCH POWER ENABLE	PITCH ACCELEROMETER TEMP	PITCH TRIGGER COUNT	PITCH TRIGGER	PITCH ATTITUDE ERROR (1 OF 2)		PITCH ATTITUDE ERROR (1 OF 2)	PITCH ATTITUDE ERROR (2 OF 2)	PITCH ATTITUDE INTEG ERROR (1 OF 2)	PITCH ATTITUDE INTEG ERROR (2 OF 2)	PITCH ATTITUDE INTEG ERROR (1 OF 2)	PITCH ATTITUDE INTEG ERROR (2 OF 2)		PITCH ATTITUDE INTEG ERROR (2 OF 2)	PITCH ATTITUDE INTEG ERROR (1 OF 2)	PITCH ATTITUDE INTEG ERROR (2 OF 2)	PITCH ATTITUDE RATE ERROR	NTTITUDE R	PITCH ATTITUDE RATE ERROR	PITCH ATTITUDE RATE ERROR	THRUST CNTRL PITS MATRIX SELECT	THRUST CNTRL PITS MATRIX	PENUMBRA (8 MSB)			RESULTS OF PORT READ COMMAND	RESULTS OF PORT READ	RESULTS OF PORT READ	RUN PROCESSOR DIAG	MP/IP CONTROL	≊	BASE PNUPRU I/F TEMP C	PTC FORWARD COIL ENABLED
PITCHPWR		PITCHTC		PITERRA		PITERRB	PITERRB	PITINTA	PITINTA	PITINTB	PITINTB	PITINTNA	PITINTNA	PITINTNB	PITINTNB	PITRATEA	PITRATEA	PITRATEB	PITRATEB	PITSSELA	PITSSFIR	PNMBRAH	PNMBRAL	PORTRDA	PORTRDA	PORTRUB	adataca	PROCDIAG	PROCNTRL	PROMCKSM	PRUIFT	PTCFWD
PITCHPWR	PITCHT	PITCHTC	PITCHTRG	PITERRA	PITERRA	PITERRB	PITERRB	PITINTA	PITINTA	PITINTB	PITINTB	PITINTNA	PITINTNA	PITINTNB	PITINTNB	PITRATEA	PITRATEA	PITRATEB	PITRATEB	PITSSELA	PITSSEIB	PNMBRAH	PNMBRAL	PORTRDA	PORTRDA	BUBTRUB	d de la company	PROCDIAG	PROCNTRL	PROMCKSM	PRUIFT	PTCFWD
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			2967	2970	217	2967	217								216	216	2969	3062	210	017														RDMGMT Flag Word 54 (upper half-first word)	RDMGMT Flag Word 52	(upper half-first word) RDMGMT Flag Word 62	(upper half-first word)	RDMGMT Flag Word 60 (upper half-first word)
1=0# Pon	1=Off	Ę.						1=Enabled 0=Disabled	1=Off 0=On	1=Qf Q-0	1=Forward 0=Reverse	1=Enabled 0=Disabled	1=0ff 0=0=	1=0ff								1=On	0=Off	1=0 0=0 0=0=0			1≂Disabled 0=Enabled	 			1=Disabled 0=Enabled	1=Q#	3	0=REDMAN Disabled 1=REDMAN Enabled	0=REDMAN Disabled	1=REDWAN Enabled 0=RFDWAN Disabled	1=REDMAN Enabled	0=REDMAN Disabled 1=REDMAN Enabled
						_													Celsius	1	Ceisius	Clima			Celsius	쯢			Celsius	₽ B			Celsius					
All Power-Up		All Power-Up	SSOH	HOSS	SSOH	HOSS	SSOH	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	SSOH	HOSS	SSOH	SSOH	All Power-Up	- Day	All Davier-Up	do 1500 1 10	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Dougs I'm	All Power-Up	Normal		Thruster	Normal	Thruster
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MTC		MTC	90	BDP	₽Q	BDP	₽Q	ΔIC	MTC	MTC	MTC	MTC	ΔI	MTC	BOY	BDY	вор	вор	173	Ž	3	2	RAP	RAP	RAP	SBT	SBT	SBT	SBT	SBT	SBT	1 50	SBT	Alida		SPUA	SPUB	SPUB
ADS		ADS	SON	<u>88</u>	SON	88	SON	ADS	SQV	ADS	ADS	ADS	ADS	ADS	SQN	NDS	SON	SON	MSS	3	SSN	}	RAP	RAP	RAP	ည္ဆင္	TT&C	TRC	17&T	TI&C	T&C	7.6	18 18 1			2 2 1 1	TIC	TT&C
SPIJ A PTC FWD ON/OFF		SPU B PTC FWD ON/OFF	PITCH COUNT CODE	PITCH POWER	PITCH SYSTEM TEST	PITCH TRIGGER LEVEL	PITCH TRIGGER ENABLE	PTC REVERSE COIL ENABLED		SPU B PTC REV ON/OFF	PTC SPR POLARITY	PTC SPR COIL ENABLED	SPILA PTC SPR ONOFF	SPII R PTC SPR ONOFF	PULSE AMP BITS: PORT 39	PULSE WIDTH BITS:PORT39	PITCH-SLOW COINCIDEN	QFS MODE	-X PAYLOAD PNL/RAFS I/F TEMP C		EARTH PNURAPI/F TEMPC	KAP KF COLPUL POWER	RAP 28 VDC ON/OFF	DAD STATIS ON/OFF	RAP TEMP	S-BAND RCVR 1 SIGNAL STR	S-BAND RCVR 1 PRN ENABLE	S. BAND BCV/R 1 SOUELCH	S-BAND RCVR 1 TEMP	S-BAND RCVR 2 SIGNAL STR			S-BAND ROVE 2 SUBELCH S-BAND ROVE 2 TEMP	E IGNATIVOMO		ROMGMT ENABLE INDICATOR	RDMGMT ENABLE INDICATOR	
PTCFWDA	Т	PTCFWDB	1	PTCHPWR	PTCHSTST	PTCHIL	(2)	1	-		Π.	PTCSPR	PTCSPRA	DTCSPRB	PUISEAMP	PULSEWID	PYSLCOIN	QFSMODE	RAFSIFT	RAMPPEAK	RAPIFT	KAPPKFP	RAPPWR	DADCTC	RAPT	RCVR1AGC	RCVR1PRN	100,000	RCVR1T	RCVR2AGC	RCVR2PRN		RCVR25QL RCVR2T	AND TO TO	Chicinical	RDIMGMENA	RDMGMENB	RDMGMENB
PTCEMINA		PTCFWDB	PTCHCNT	PTCHPWR	PTCHSTST	PTCHTL	PTCHTRIG	PTCREV	PRCREVA	PRCREVR	PTCSPPOL	PTCSPR	DTCCDRA	DICCORR	PILISEAMP	PULSEWID	PYSLCOIN	QFSMODE	RAFSIFT	RAMPPEAK	RAPIFT	RAPPREP	RAPPWR	OFOCIAC	_	RCVR1AGC	┼—	+	BCVR13GL	12	+		RCVR2SQL RCVR2T	-		RDMGMENA	RDMGMENB	
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Thruster	Thriefor	Thruster																									
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SPUA	A Lids	SPUB	SPU B	SPUA	SPUA	SPU B	SPUB	SPUA	SPU A	SPU B	SPU B	SPU A	SPU A	SPU B	SPU B	SPU A	SPUA	SPU B	SPU B	SPU A	SPU A	SPU B	SPUB	SPUA	SPUA	SPU B	SPU B
ADS	A CA	ADS .	A SQ	ADS																							
REA 1 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 1 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 1 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 1 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 2 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 2 PULSÉWIDTH ATTITUDE PAIR (2 OF 2)	REA 2 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 2 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 3 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 3 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 3 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 3 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 4 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 4 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 4 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 4 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 5 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 5 PULSÉWIDTH ATTITUDE PAIR (2 OF 2)	REA 5 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 5 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 6 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 6 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 6 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 6 PULSÉWIDTH ATTITUDE PAIR (2 OF 2)	REA 7 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 7 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA Ž PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 7 PULSEWIDTH ATTITUDE PAIR (2 OF 2)
REA1PWA	REATEWA	REATPWB	REA1PWB	REA2PWA	REA2PWA	REA2PWB	REA2PWB	REASPWA	REA3PWA	REA3PWB	REA3PWB	REAAPWA	REA4PWA	REAMPWB	REAMPWB	REASPWA	REASPWA	REASPWB	REASPWB	REAGPWA	REAGPWA	REAGPWB	REAGPWB	REA7PWA	REA7PWA	REA7PWB	REA7PWB
16 REATPWA	16 REATEWA	1	16 REA1PWB	16 REA2PWA	16 REA2PWA	16 REA2PWB	16 REA2PWB	16 REA3PWA	16 REA3PWA	16 REA3PWB	16 REA3PWB	16 REA4PWA	16 REA4PWA	16 REA4PWB	16 REAMPWB	16 REASPWA		16 REASPWB	16 REASPWB	16 REAGPWA	16 REAGPWA	<u> </u>		16 REA7PWA	16 REA7PWA	<u> </u>	
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				41			167	3063	2970	RDMGMT Flag Word 52 (lower half-first word)	RDMGMT Flag Word 54	RDMGMT Flag Word 60 (lower half-first word)	RDMGMT Flag Word 62 (lower half-first word)																		
					1=Reload S/W Occurred 0=Reload S/W Failed	1=Reload S/W Occurred 0=Reload S/W Failed				0=Disabled 1=Enabled	0=Disabled	0=Disabled	0=Disabled 1=Enabled	1=On 0=Off	1=High !0=Low		1=On 0=Off	1=High 0=Low													
seconds	seconds	seconds	seconds													Celsius			Celsius	radians	radians	radians	radians	radians	radians	radians	geiber	counts	counts	counts	counts
Thruster	Thruster	Thruster	Thruster	SSOH	Power-Up	Power-Up	SSOH	SSOH	SSOH	Normal	Thrister	Normal	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Early Orbit	Early Orbit	Normal Thruster	Normal Thruster	Early Orbit	Early Orbit	Normal	Normal	Early Orbit	Early Orbit	Early Orbit	Normal
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ADS	ADS	ADS	Q	SON	180) 	SON	SON	SON	TI&C	T&C	11&C	TI&C	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	O C	SQS	ADS	ADS	ADS
	REA 8 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	REA 8 PULSEWIDTH ATTITUDE PAIR (1 OF 2)	REA 8 PULSEWIDTH ATTITUDE PAIR (2 OF 2)	INTER(PARA FIFO REC)	FLAG INDIC RELOAD OF FLIGHT S/W OCCUR	FLAG INDIC RELOAD OF FLIGHT SWY OCCUR	RESET FIFOS&16 EOMS	QFS=2OR3,MINRETUNE TIME	ROLL POWER		RATE MEASURING ASSEMBLY ENABLE	RATE MEASURING ASSEMBLY ENABLE	RATE MEASURING ASSEMBLY ENABLE	RMA PITCH 1 28VDC ON/OFF	RMA PITCH 1 RATE RANGE HI/LO	RMA PITCH-1 TEMP	RMA PITCH 2 28VDC ON/OFF	RMA PITCH 2 RATE RANGE HI/LO	RMA PITCH-2 TEMP	FILTERED RMA PITCH OUTPUT (1 OF 2)	(2 OF 2)	FILTERED RMA PITCH OUTPUT (1 OF 2)	FILTERED RMA PITCH OUTPUT (2 OF 2)	FILTERED RIMA PITCH OUTPUT (1 OF 2)	FILTERED RMA PITCH OUTPUT (2 OF 2)	FILTERED RMA PITCH OUTPUT (1 OF 2)	FILTERED RMA PITCH OUTPUT	RMA PITCH OUTPUT (1 OF 4)	RMA PITCH OUTPUT (2 OF 4)	RMA PITCH OUTPUT (3 OF 4)	RMA PITCH OUTPUT (1 OF 4)
REASPWA	REA8PWA	REASPWB	REASPWB	RECINTER	RELOADA	RELOADB	RESETREQ	RETUNE	RLLPWR	RMAENA	RMAENA	RMAENB	RMAENB	RMAP1PWR	RMAP1RAT	RMAPIT	RMAP2PWR	RMAP2RAT	RMAP2T	RMAPFILA	RMAPFILA	RMAPFILA	RMAPFILA	RMAPFILB	RMAPFILB	RMAPFILB	OMADE!! D	RMAPITA	RMAPITA	RMAPITA	RMAPITA
REABPWA	REABPWA	REABPWB	REA8PWB	RECINTER	RELOADA	RELOADB	RESETREQ	RETUNE	RLLPWR	RMAENA	RMAENA	RMAENB	RMAENB	RMAP1PWR	RMAP1RAT	RMAP1T	RMAP2PWR	RMAP2RAT	RMAP2T	RMAPFILA	RMAPFILA	RMAPFILA	RMAPFILA	RMAPFILB	RMAPFILB	RMAPFILB	a iiaaviia	RMAPITA	RMAPITA	RMAPITA	RMAPITA
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Normal	Normal Thruster	Normal	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	¥	₹	₹	₹	Farty Orbit	Early Orbit	Early Orbit	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Normal Thruster	Normal Thruster
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RMA PITCH OUTPUT (2 OF 4)	RMA PITCH OUTPUT (3 OF 4)	RMA PITCH OUTPUT (4 OF 4)	RMA PITCH OUTPUT (1 OF 4)	RMA PITCH OUTPUT (2 OF 4)	KMA PIICHOUIPUT (3 OF 4)	KMA PIICH OUTPUT (4 OF 4)	RMA PITCH OUTPUT (1 OF 4)	RMA PITCH OUTPUT (2 OF 4)	RMA PITCH OUTPUT (3 OF 4)	RMA PITCH OUTPUT (4 OF 4)	RMA ROLL 1 28 VDC ON/OFF	RMA ROLL 1 RATE RANGE HI/LO	RMA ROLL-1 TEMP	RMA ROLL 2 28 VDC ON/OFF	RMA ROLL 2 RATE RANGE HI/LO	RMA ROLL-2 TEMP	FILTERED RMA ROLL OUTPUT (1 OF 2)	FILTERED RMA ROLL OUTPUT (2 OF 2)	FILTERED RMA ROLL OUTPUT (1 OF 2)	FILTERED RMA ROLL OUTPUT (2 OF 2)	RMA ROLL OUTPUT (2 OF 4)	RMA ROLL OUTPUT (3 OF 4)	RMA ROLL OUTPUT (4 OF 4)	RMA ROLL OUTPUT (1 OF 4)	RMA ROLL OUTPUT (2 OF 4)	RMA ROLL OUTPUT (3 OF 4)	RMA ROLL OUTPUT (4 OF 4)			-	RMA ROLL OUTPUT (4 OF 4)	RMA ROLL OUTPUT (1 OF 4)	RMA ROLL OUTPUT (2 OF 4)
RMAPITA	RMAPITA	RMAPITA	RMAPITB	RMAPITB	KMAPILB	KMAPILB	RMAPITB	RMAPITB	RMAPITB	RMAPITB	RMAR1PWR	RMAR1RAT	RMAR1T	RMAR2PWR	RMAR2RAT	RMAR2T	RMARFILA	RMARFILA	RMARFILB	RMARFILB	RMAROLA	RMAROLB	RMAROLB	RMAROLB	RMAROLB	RMAROLB	RMAROLB						
RMAPITA	RMAPITA	RMAPITA	RMAPITB	KMAPIIB	KMAPIB	KWAPIIB	RMAPITB	RMAPITB	RMAPITB	RMAPITB	RMAR1PWR	RMAR1RAT	RMAR1T	RMAR2PWR	RMAR2RAT	RMAR2T	RMARFILA	RMARFILA	RMARFILB	RMARFILB PMAPOLA	RMAROLA	RMAROLB	RMAROLB	RMAROLB	RMAROLB	RMAROLB	RMAROLB						
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																							ADS G SWOOD	Tag Wood				RDMGMT Flag Word 54 (upper half-first word)	RDMGMT Flag Word 52 (upper half-first word)	RDMGMT Flag Word 62 (upper half-first word)
		1=0 0=0#	1=High 0=Low		1=On 0=Off	1=High 0=Low																0=Bias Est Not Enabled	0=Bias Est Not Enabled					0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled
counts	counts			Celsius			Celsius	counts	counts	counts	counts	counts	counts	counts	counts	counts	counts	counts	siuno	sinos .	counts	SILINA		radiane	radians	radians	radians			
Normal Thruster	Normal Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Early Orbit	Early Orbit	Early Orbit	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Early Orbit	Early Orbit	Early Orbit	Normal Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal Thruster	Normal	Thruster	Normal
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SPUB	SPUB	RMA	RMA	RMA	RMA	RMA	RMA	SPUA	SPUA	SPUA	SPU A	SPUA	SPU A	SPUA	SPUB	SPUB	SPUB		0 0		SPU S	SPUA	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB
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RMA ROLL OUTPUT (3 OF 4)	RMA ROLL OUTPUT (4 OF 4)	RMA YAW 1 28VDC ON/OFF	RMA YAW 1 RATE RANGE HI/LO	RMA YAW-1 TEMP	RMA YAW 2 28VDC ON/OFF	RMA YAW 2 RATE RANGE HI/LO			RMA YAW OULPUT (2 OF 4)	RMA YAW OUTPUT (4 OF 4)	RMA YAW OUTPUT (1 OF 4)	RMA YAW OUTPUT (2 OF 4)	RMA YAW OUTPUT (3 OF 4)	RMA YAW OUTPUT (4 OF 4)	RMA YAW OUTPUT (1 OF 4)	RMA YAW OUTPUT (2 OF 4)			RMA VAW OUTDUT COE A		RMA YAW OUTPUT (4 OF 4)		RMA YAW BIAS UPDATE	FILTERED RMA YAW OUTPUT	FILTERED RMA YAW OUTPUT (2 OF 2)	FILTERED RMA YAW OUTPUT (1 OF 2)	FILTERED RMA YAW OUTPUT (2 OF 2)	RMA ZERO RATE	RMA ZERO RATE	RMA ZERO RATE
RMAROLB	RMAROLB	RMAY1PWR	RMAY1RAT	RMAY1T	RMAYZPWR	RMAY2RAT	RMAY2T	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWB	RMAYAWB	RMAYAWB	DAMAYANA D	PMAYAWB		RMAYAWB	RMAYBIAA	RMAYBIAB	RMAYFILA	RMAYFILA	RMAYFILB	RMAYFILB	RMAZRTA	RMAZRTA	RMAZRTB
RMAROLB	RMAROLB	RMAY1PWR	RMAY1RAT	RMAY1T	RMAYZPWR	RMAY2RAT	RMAY2T	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWA	RMAYAWB	RMAYAWB	RMAYAWB	DAAAVAIA/D	RMAYAWB	DAIAVAIAID	RMAYAWB	RMAYBIAA	RMAYBIAB	RMAYFILA	RMAYFILA	RMAYFILB	RMAYFILB	RMAZRTA	RMAZRTA	RMAZRTB
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RDMGMT Flag Word 60 (upper half-first word)	2979	2979	29/9	6/67					2968													2971	217					217	SSOH Byte 3419	209	2968 2968	217	3067	2969	164	\$ 2
0=Test Disabled 1=Test Enabled					rad/sec	rad/sec	rad/sec	rad/sec		radians	radians	radians	radians	rad/sec	rad/sec	rad/sec	ad/sec	in-lbf-sec	in-lbf-sec	in-lbf-sec	in-lbf-sec			rad/sec	rad/sec	rad/sec	rad/sec		Celsius							
Thruster	SSOH	SSOH	SSOH	HOSS	_	Normal rac	Normal rac		SSOH				Normal Thruster rac	Thruster	Thruster ra	Thruster		Normal Thruster in-I				SSOH	SSOH					\vdash	ತಿ	SSOH	SSOH HOSS	HOSS HOSS	SSOH	SSOH	SSOH	SSOH
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RMA ZERO RATE	DISABLE RMI INTERLEAVER	DISABLE RMI OUTPUT	DISABLE RMI SCRAMBLER	ROLL ATTITUDE INTEG ERROR	(1 OF 2) ROLL ATTITUDE INTEG ERROR		ROLL ATTITUDE INTEG ERROR (1 OF 2)	ROLL ATTITUDE INTEG ERROR (2 OF 2)	ROLL COUNT CODE	ROLL ATTITUDE ERROR (1 OF 2)	ROLL ATTITUDE ERROR (2 OF 2)	ROLL ATTITUDE ERROR (1 OF 2)	ROLL ATTITUDE ERROR (2 OF 2)	ROLL ATTITUDE INTEG ERROR (1 OF 2)	(2 OF 2)	KOLL AT ITT UDE INTEG ERROR (1 OF 2)	ROLL ATTITUDE INTEG ERROR (2 OF 2)	ROLL MOMENTUM ERROR (1 OF 2)	ROLL MOMENTUM ERROR (2 OF 2)	ROLL MOMENTUM ERROR (1 OF 2)		DISABLE ROLL MSGS	ROLL POWER ENABLE	(1 OF 2)	ROLL ALLITUDE RALE ERROR (2 OF 2)		ROLL ATTITUDE RATE ERROR	ROLL SYSTEM TEST	ROLL ACCELEROMETER TEMP	ROLL TRIGGER COUNT	ROLL TRIGGER LEVEL	ROLL IRIGGER ENABLE	RUN PROGEROMBASEADDR	ROLL-PITCH COINCIDEN	INTR RST 0-3	RST 5.5 SERIAL COM
		+	_			ROLINTNA (ROLINTNB		ROLLCNT	ROLLERRA	ROLLERRA	ROLLERRB	ROLLERRB	ROLLINTA	ROLLINTA	ROLLINTB (ROLLINTB	ROLLMEA	ROLLMEA	ROLLMEB	i	П	ROLLPWR	ROLLRATA	ROLLRATA	ROLLRATB (ROLLRATB	1	1		1	Т	RPRASE			RST55INT
RMAZRTB	RMINTER	RMIOUTP	RMISCRAM	KMIISIPA	ROLININA	ROLINTNA	ROLINTNB	ROLINTNB	ROLLCNT	ROLLERRA	ROLLERRA	ROLLERRB	ROLLERRB	ROLLINTA	ROLLINTA	ROLLINTB	ROLLINTB	ROLLMEA	ROLLMEA	ROLLMEB	ROLLMEB	ROLLMSG	ROLLPWR	ROLLRATA	ROLLRATA	ROLLRATB	ROLLRATB	ROLLSTST	ROLLT	ROLLTC	ROLLTL	ROLLING POLLING	ROLLIKIG	RPCOIN	RST03INT	RST47INI RST55INT
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254	164	20.	LSB=5 rpm	LSB=5 rpm	LSB=5 rpm	LSB-5 rpm														1.0	md: c=85.	LSB=5 rpm	LSB=5 ram											
			counts	counts	counts	counts	Celsius	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	mA	jql-ui	in-lbf	jq-ui	in-lbf	counts	counts	counts	Celsius	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	mA M	in-lbf
HOSS	HOSS	HOSS	Normal	Normal	Normal	Normal	All Power-Up	Normal	Normal	Thruster	Thruster	Normai	Normal	Thruster	Thruster	All Power-Up	Normal	Normal	Normal	Normal	Normal	Normal	Normal	All Power-Up	Normal	Normal	Thruster	Thruster	Normal	Normal	Thruster	Thruster	All Power-Up	Normal
S	S	S	S	S	S	S	8	တ	ဟ	ဟ	တ	ဟ	S	တ	တ	ΑH	တ	တ	ဟ	တ	S	တ ပ	S	₽	တ	S	S	S	S	တ	ဟ	S	₹	တ
BDY	BDP-IP	BDP-IP	SPUA	SPUA	SPU B	SPUB	₩.	SPUA	SPUA	SPUA	SPU A	SPUB	SPU B	SPUB	SPUB	RWA	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPLIB	RWA	SPUA	SPUA	SPUA	SPUA	SPUB	SPUB	SPU B	SPUB	RWA	SPUA
NDS	\vdash	\dashv	-	{	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	S S S	ADS	ADS	ADS	SQS SQS	ADS	ADS	ADS	ADS	ADS	ADS	ADS
BDY-P INTERSTATBT:NOSRQ	RST6.5 MFS/FIFO FILL	RST 7.5	RWA 1 TACH OUTPUT (1 OF 2)	RWA 1 TACH OUTPUT (2 OF 2)	RWA 1 TACH OUTPUT (1 OF 2)	RWA 1 TACH OUTPUT (2 OF 2)	RWA 1 BEARING TEMP	(1 OF 2)	FILTERED RWA 1 TACH OUTPUT (2 OF 2)	FILTERED RWA 1 TACH OUTPUT (1 OF 2)	FILTERED RWA 1 TACH OUTPUT (2 OF 2)	FILTERED RWA 1 TACH OUTPUT (1 OF 2)	FILTERED RWA 1 TACH OUTPUT (2 OF 2)	ED RWA 1 TA	FILTERED RWA 1 TACH OUTPUT (2 OF 2)	RWA 1 MOTOR CURRENT	RWA TORQUE COMMAND 1 (1 OF 2)	RWA TORQUE COMMAND 1 (2 OF 2)	RWA TORQUE COMMAND 1 (1 OF 2)	RWA TORQUE COMMAND 1 (1 OF 2)	RWA 2 TACH OUTPUT (1 OF 2)	RWA 2 TACH OUTPUT (2 OF 2)	RVVA 2 TACH OUTPUT (1 OF 2)	RWA 2 BEARING TEMP	FILTERED RWA 2 TACH OUTPUT (1 OF 2)	FILTERED RWA 2 TACH OUTPUT (2 OF 2)	FILTERED RWA 2 TACH OUTPUT (1 OF 2)	FILTERED RWA 2 TACH OUTPUT (2 OF 2)	FILTERED RWA 2 TACH OUTPUT (1 OF 2)	FILTERED RWA 2 TACH OUTPUT (2 OF 2)	FILTERED RWA 2 TACH OUTPUT (1 OF 2)	FILTERED RWA 2 TACH OUTPUT	RWA 2 MOTOR CURRENT	RWA TORQUE COMMAND 2 (1 OF 2)
RSTESERR E			. [- 1	ŀ	- 1	RWA1BT	RWA1FILA (RWA1FILA (RWA1FILA (RWA1FILB (RWA1FILB		RWA1FILB	~	RWAITCA	RWA1TCA	RWA1TCB	В			KWAZB	1.	RWAZFILA	RWAZFILA		RWA2FILA		RWA2FILB	RWAZFILB	DIA/A2EII B	RWA2MCUR	RWA2TCA
RSTESERR	RST65INT	RST75INT	RWA1A	RWA1A	RWA1B	RWA1B	RWA1BT	RWAIFILA	RWA1FILA	RWA1FILA	RWA1FILA	RWA1FILB	RWA1FILB	RWA1FILB	RWA1FILB	RWA1MCUR	RWA1TCA	RWAITCA	RWA1TCB	RWA1TCB	RWAZA	RWA2A	KWA2B	RWA2BT	RWA2FILA	RWAZFILA	RWAZFILA	RWA2FILA	RWAZFILB	RWAZFILB				RWA2TCA
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			LSB=5 rpm	LSB=5 rpm	LSB=5 rpm	LSB=5 rpm														LSB=5 rpm	LSB=5 rpm	LSB=5 rom									
jq-uj	jq-ui	in-lbf	counts	counts	counts	counts	Ceisius	rad/sec	radicar	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	ΨΨ	jq-ui	jq-ui	jq-ui	in-lbf	counts	counts	counts	Celsius	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	radisec	rad/sec	rad/sec
Normal	Normal	Normal	Normal	Normal	Normal	Normal	All Power-Up	Normal	Thnister	Thruster	Normal	Normal	Thruster	Thruster	All Power-Up	Normal	Normal	Normal	Normal	Normal	Normal	Normal	All Power-Up	Normal	Normal	Thrister	Thruster	Normal	Normal	Thruster	Thruster
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SPUA	SPUB	SPUB	SPU A	SPUA	SPUB	מלק מ	AVVA A LIGA	SPUA	SPUA	SPUA	SPUB	SPUB	SPUB	SPUB	RWA	SPUA	SPUA	SPUB	SPUB	SPUA	SPLIA	SPUB	RWA	SPUA	SPUA	SPUA	SPUA	SPU B	SPUB	SPU B	SPUB
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RWA TORQUE COMMAND 2 (2 OF 2)	RWA TORQUE COMMAND 2 (1 OF 2)	RWA TORQUE COMMAND 2 (2 OF 2)	RWA 3 TACH OUTPUT (1 OF 2)	RWA 3 TACH OUTPUT (2 OF 2)	RWAS IACH CUIPUI (1 OF 2)	PV/A 3 READING TEMP	FILTERED RWA 3 TACH OUTPUT	FILTERED RWA3 TACH OUTPUT (2 OF 2)	FILTERED RWA 3 TACH OUTPUT	ļ —	—	FILTERED RWA 3 TACH OUTPUT (2 OF 2)	 	FILTERED RWA 3 TACH OUTPUT (2 OF 2)	RWA 3 MOTOR CURRENT	RWA TORQUE COMMAND 3 (1 OF 2)	RWA TORQUE COMMAND 3 (2 OF 2)	RWA TORQUE COMMAND 3 (1 OF 2)	RWA TORQUE COMMAND 3 (2 OF 2)	BMA 4 TACH OUTPUT (1 OF 2)	RWA 4 TACH OUTPUT (1 OF 2)	RWA 4 TACH OUTPUT (2 OF 2)	RWA 4 BEARING TEMP	_	⊢	FILTERED RWA 4 TACH OUTPUT (1 OF 2)	FILTERED RWA 4 TACH OUTPUT (2 OF 2)	FILTERED RWA 4 TACH OUTPUT (1 OF 2)	FILTERED RWA 4 TACH OUTPUT	ı⊢	FILTERED RWA 4 TACH OUTPUT (2 OF 2)
RWA2TCA	RWA2TCB	RWA2TCB	RWA3A	RWA3A	RVVA3B PIV/A3B	RIMARET	RWA3FILA	RWA3FILA	RWA3FILA		RWA3FILB	RWA3FILB	RWA3FILB	RWA3FILB	RWA3MCUR	RWA3TCA	RWA3TCA	RWA3TCB	m	RWA4A	ļ		RWA4BT	RWA4FILA	RWA4FILA	RWA4FILA		RWA4FILB		RWA4FILB	RWA4FILB
RWA2TCA	RWA2TCB	12			RVVA3B	_	L		RWA3FILA	RWA3FILA	RWA3FILB	RWA3FILB	RWA3FILB	RWA3FILB	RWA3MCUR	RWA3TCA	RWA3TCA	RWA3TCB	RWA3TCB	RWA4A	\perp		RWA4BT	RWA4FILA	RWA4FILA	RWA4FILA	RWA4FILA	RWA4FILB	RWA4FILB	RWA4FILB	RWA4FILB
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				**************************************	Ground Select Flag Word 52 (first word)	Ground Select Flag Word 54 (first word)	Ground Select Flag Word 62 (first word)	Ground Select Flag Word 60 (first word)	RDMGMT Flag Word 53 (lower half-second word)	RDMGMT Flag Word 55 (lower half-second word)	RDMGMT Flag Word 61 (lower half-second word)	RDMGMT Flag Word 63 (lower half-second word)	RDMGMT Flag Word 54 (upper half-first word)	RDMGMT Flag Word 52 (upper half-first word)	RDMGMT Flag Word 62 (upper half-first word)	RDMGMT Flag Word 60 (upper half-first word)			ADS Flag Word	ADS Flag Word	ADS Flag Word	ADS Flag Word	ADS Flag Word
					0=RWA1 1=RWA2 2=RWA3 3=RWA4 4=None	0=RWA 1 1=RWA 2 2=RWA 3 3=RWA 4 4=None	- ო	0=RWA1 1=RWA2 2=RWA3 3=RWA4 4=None	0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	1=0n 0=0f	1=0n 0=0f	0=RWA Not Power Limited 1=RWA Power Limited	O=RVVA Not Power Limited 1=RVVA Power Limited	0=RWA Not Speed Limited 1=RWA Speed Limited	0=RWA Not Speed Limited 1=RWA Speed Limited	0=RWA Not Torque Limited 1=RWA Torque Limited
ΨΨ	in-lbf	in-lbf	in-lbf	in-lbf																			
All Power-Up	Normal	Normal	Normal	Normal	Thruster	Normal	Normal	Thruster	Normal	Thruster	Normal	Thruster	Normal	Thruster	Normal	Thruster	All Power-Up	All Power-Up	Normai Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster
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RWA	SPUA	SPU A	SPU B	SPU B	SPUA	SPU A	SPU B	SPU B	SPUA	SPU A	SPU B	SPU B	SPUA	SPUA	SPU B	SPU B	RWA	RWA	SPUA	SPU B	SPU A	SPU B	SPUA
ADS	ADS	ADS	ADS	ADS		TI&C	T&C	17&C	T&C	ļ	2% T	T&C	T&C	T&C		ļ	ADS	SQ.	2% 1	T&C	ТВС	TT&C	TT&C
RWA4MCUR RWA4MCUR RWA 4 MOTOR CURRENT	RWA TORQUE COMMAND 4 (1 OF 2)	RWA TORQUE COMMAND 4 (2 OF 2)	RWA TORQUE COMMAND 4 (1 OF 2)	RWA TORQUE COMMAND 4 (2 OF 2)	 	RWA DISABLED INDICATOR	RWA DISABLED INDICATOR	RWA DISABLED INDICATOR	REACTION WHEEL ASSEMBLY	REACTION WHEEL ASSEMBLY	REACTION WHEEL ASSEMBLY	REACTION WHEEL ASSEMBLY	RWA RATE ERROR	RWA RATE ERROR	RWA RATE ERROR	RWA RATE ERROR	RWA HEATER A ON/OFF	RWA HEATER A ON/OFF	RWAPWI MA RWA POWER LIMIT INDICATOR	RWA POWER LIMIT INDICATOR	RWA SPEED LIMIT IN	RWASPLMB RWA SPEED LIMIT INDICATOR	RWATQLMA RWA TORQUE LIMIT INDICATOR
RWA4MCUR	RWA4TCA	RWA4TCA	RWA4TCB	RWA4TCB	RWADISA	RWADISA	RWADISB	RWADISB	RWAENA	RWAENA	RWAENB	RWAENB	RWAERRA	RWAFRRA	RWAERRB	RWAERRB	RWAHTRA	RWAHTRB	RWAPWIMA	RWAPWLMB	RWASPLMA	RWASPLMB	RWATQLMA
RWA4MCUR	RWA4TCA	RWA4TCA	RWA4TCB	RWA4TCB	RWADISA	RWADISA	RWADISB	RWADISB	RWAENA	RWAENA	RWAENB	RWAENB	RWAERRA	RWAFRRA	RWAFRR	RWAERRB	RWAHTRA	RWAHTRB		RWAPWLMB		RWASPLMB	RWATQLMA
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	ADS Flag Word																			2969	S/A Step Status Word					RDMGMT Flag Word 55 (upper half-second word)	RDMGMT Flag Word 53	RDMGMT Flag Word 63	RDMGMT Flag Word 61 (upper half-second word)			
0=RWA Not Torque	1=RWA Torque Limited									1=Enabled	0=Disabled	1=0ff	1=0# 음으	1=Enabled 0=Disabled	1=0# P=0n	1=Off G-On	1=Forward 0=Reverse	1=Enabled 0=Disabled	1=Off	1=Off 0=0n	2=+Y Fwd 3=+Y Rev 0-1,4-7=Spare	2=+Y Fwd 3=+Y Rev 0-1.4-7=Spare	4=-Y Fwd 5=-Y Rev 0-3.6-7=Spare	4=-Y Fwd 5=-Y Rev 0-3,6-7=Spare	1=Armed 0=Disarmed	1=Armed 0=Disarmed	1=Off 0=On	1=Off O=On	0≕Test Disabled 1=Test Enabled	0=Test Disabled	0=Test Disabled	0=Test Disabled 1≔Test Enabled
		volts	Celsius	volts	Celsius	volts	Celsius	volts	Celsius	2																						
Normal	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	do-lawo I IIV	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up SSOH	₹	₹	₹	Æ	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Normal	Thruster	Normal	Thruster
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	SPUB	RWE	RWE	RWE	RWE	RWE	YWE.	א א ז	ATO TO	>	MTC	MTC	MTC	MTC	MTC	MTC	MTC	MTC	MTC	MTC	SPUA	SPU B	SPU A	SPU B	S/A	S/A	SAD	SAD	SPU A	SPU A	SPUB	SPU B
	TI&C	ADS:	ADS:	8	ADS:	800	3	3	ADS	3	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	ADS	TRC	7% T	28 T	TT&C	EPS	<u>В</u>	8	EPS	TT&C	TT&C	TT&C	TT&C
	RWA TORQUE LIMI	RIVE 1 CC-DC CONV +5VDC OUI	DIAME 2 PO PO CONT. FLASS CITE	RIVE 2 DC-DC CONV +5VDC OUT	DIVIE 2 DC DC CONV. EVIDO CUIT	DIVES DC-DC CONV +5VDC COI	RIVE 3 LEIVIE BIAVE 4 DC DC CONIV 15 VDC OI IT	RIVE 4 TEMP	RYC COIL CURRENT		RYC FORWARD COIL ENABLE	SPU A RYC FWD ON	SPU B RYC FWD ON	RYC REVERSE COIL ENABLED	SPU A RYC REV ON	SPU B RYC REV ON	RYC SPR POLARITY	RYC SPR COIL ENABLED	SPU A RYC SPR ON	SPU B RYC SPR ON ROLL-SLOW COINCIDENC	+Y S/A STEP STATUS	+Y S/A STEP STATUS	-Y S/A STEP STATUS	+Y S/A STEP STATUS	OCU A PYROS (S/A) ARMED	OCU B PYROS (S/A) ARMED	SAD A ON/ B OFF	SAD B ON/ A OFF	SADPOT DEADBAND	SADPOT DEADBAND	SADPOT DEADBAND	SADPOT DEADBAND
	RWATQLMB PWF1CVEV	DIAMETER	-12		1		>	RWE4T	RYCCUR		RYCFWD	RYCFWDA	RYCFWDB	RYCREV	RYCREVA	RYCREVB	RYCSPPOL	RYCSPR	RYCSPRA	RYCSPRB	SAPCMDA	SA+CMDB	SAMCMDA	SAMCMDB	SAARMA	SAARMB	SADA	SADB	SADDBNDA	SADDBNDA	SADDBNDB	SADDBNDB
	RWATOLMB RWF1CVSV	DIVIE 1T	DIVIES CIVERY	DIAMEST	BIMERCIASI	RIVEST	RWF4CV5V	RWE4T	RYCCUR		RYCFWD	RYCFWDA	RYCFWDB	RYCREV	RYCREVA	RYCREVB	RYCSPPOL	RYCSPR	RYCSPRA	RYCSPRB RYSLCOIN	SA+CMDA	SA+CMDB	SA-CMDA	SA-CMDB	SAARMA	SAARMB	SADA	SADB	SADDBNDA	SADDBNDA	SADDBNDB	SADDBNDB
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		RDMGMT Flag Word 55 (upper half-second word)	RDMGMT Flag Word 53	(upper half-second word)	RUMGMI Flag Word 63 (upper half-second word)	RDMGMT Flag Word 61	(upper half-second word)	Ground Select Flag Word 52 (first word)		Ground Select Flag Word 54 (first word)	Ground Select Flag Word 62	(III) wold)	Ground Select Flag Word 60	(Sign Sill)	395	441	397	419	420	416	417	396	407 1.4E	385	TLM (Error) Flag Word 53 (second word)	TLM (Error) Flag Word 53 (second word)	TLM (Error) Flag Word 61	TLM (Error) Flag Word 61	(second Word)	2995	197	SSOH Byte 3409	SSOH Byte 3411	SSOH Byte 3410
1=Forward 0=Reverse	1=Forward 0=Reverse	0=Test Disabled 1=Test Enabled	0=Test Disabled	1=Test Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled	1=Test Enabled	O=S/A Slew During SK if Prev SNP Disabled 1=S/A Slew During SK if Prev SNP Enabled	0=S/A Slew During SK if Prev SNP Disabled	1=S/A Slew During SK if Prev SNP Enabled	O=S/A Slew During SK if Prev SNP Disabled 1=S/A Slew During SK if Drev SND Emakked	0=S/A Slew During SK if	Prev SNP Disabled 1=S/A Slew During SK if Prev SNP FreeHod												Binary equivalent of values 0-255	Binary equivalent of values 0-255	Binary equivalent of	Binary equivalent of	Values U-200					
									ļ.					Celsius			!															volts	É	volts
All Power-Up	All Power-Up	Normal		Thruster	Normal		Thruster	Thuster	1	Normal	S CONTRACTOR		Thoseter	All Power-Up	HOSS	SSOH	E E	SSOH	HOSS HOSS HOSS HOSS HOSS HOSS HOSS HOSS	HOSS	SSOH	SSOH	HOSS	HOSS	Early Orbit	Normal	Farty Orbit	Normal	HOSSOH	SSOH	HOSS	All Power-Up	SSOH CO	All Power-Up
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SAD	SAD	SPUA		SPUA	SPUB		SPU B	SPUA	:	SPUA	allas	5	a lido	TCS	90B	BDW	5 2 2 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	BDD/X	BDD/X	BDD/X	BDD/X	BG B	BDP-IP	9	SPUA	SPUA	SPU B		SPO B	BDP	BDP-IP	<u>à</u>	2	BDY
EPS	8.	18C		ည _ _	T18C		TI&C	T&C		TT&C	TRC	3		MSS	SS SS	8	2 S	SON	8	38	SON	8	2 2	88	18°C	D\$L	T&C	(2 S	+-	NDS	8	32	SON
SAD A STEP DIRECTION FWD/REV	SAD B STEP DIRECTION FWD/REV	SADPOT POSITION RESET	Thomas Moltinoa Todaka	SAUPUL PUSHION RESEL	SADPOT POSITION RESET		SADPOT POSITION RESET	SKP SNP SOLAR ARRAY SLEW ENA/DIS		SKP SNP SOLAR ARRAY SLEW ENA/DIS	SKP SNP SOLAR ARRAY SLEW FNAMPIS		SKP SNP SOLAR ARRAY SLEW FNA/DIS	BASE PNL S-BAND ANT TEMP D	BDP TEMPERATURE	BDW TEMP SENSOR #5	BDX S1 SINGLES COUNT	BDX S2 SINGLES COUNT	BDX SA SINGLES COUNT	BDX TEMPERATURE 2	BDX TRIGGER COUNT	BDP CURRENT	OPTICAL DETECTOR EMP	ZTIME	SINGLE BIT ERROR ROLLOVER COUNTER	SINGLE BIT ERROR ROLLOVER COUNTER	SINGLE BIT ERROR ROLLOVER	SINGLE BIT ERROR ROLLOVER	S-BAND DMP O/P POINT	S-BAND DUMP ADDRESS	S-BAND DUMP POINTER	SEGMENT I BIAS VOLTAGE	SEGMENT PEEDBACK	SEGMENT J BIAS VOLTAGE
SADIRCTA	SADIRCTB	SADRSETA		SAURSEIA	SADRSETB		SADRSETB	SASLWENA		SASLWENA	NA NA NA NA NA NA NA NA NA NA NA NA NA N	COCCANCIAC	SASIWENB	SBANTT	SBDPT	SBDWT	SBDXC SBDXSC1	SBDXSC2	SBDXSC3	SBDXT	SBDXTC	SBDYC	SBUYI	SBHDZWDS	SBITERRA	SBITERRA	SBITERRB		SOMPOP	SDUMPADR	SDUMPP	SEGIBV	SEGIPMR	SEGJBV
SADIRCTA	SADIRCTB	SADRSETA	ATHORN	SAURSEIA	SADRSETB		SADRSETB	SASLWENA		SASLWENA	MAN MAN	CASCATCING	SASIWENB	SBANTT	SBDPT	SBDWT	SBDXC SBDXSC1	SBDXSC2	SBDXSC3	SBDXT	SBDXTC	SBDYC	SBUYI	SBHDZWDS	SBITERRA	SBITERRA	SBITERRB		SOMPOP	SDUMPADR	SDUMPP	SEGIBV	SEGIPMR	SEGJBV
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				0=Not Separated 1=Separated	0=Not Separated 1=Separated	0=Not Separated 1=Separated	0=Not Separated	1=Separated									-											0=No Signal	0=No Signal	1=Signal Present	0=Do Not Abort SK 1=Abort SK	0=Do Not Abort SK	1=Abort SK													
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All Power-Up	SSOH	SSOH	SSOH	Normal Thruster	Normal Thruster	Normal	Normal	Thruster	HOSSOH	HOSS HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	ESSON FOSSON	D 200	HOSS	HOSS	SSOH	HOSS	SSOH	SSOH	All Power-Up	All Power-Up	All Power-Up	SSOH		All Power-Up	All Power-Up	Normal	Normal	Thruster	LOSS TOU	HOSS	SSOH	SSOH	SSOH	SSOH	HOSS HOSS	1000	HOSS	SSOH	HOSS	SSOH	SSOH
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SEGMENT J FEEDBACK	SEGMENT J POWER	DISABLE I SEGMENTPWR	J SEGMENT PWRDISABLE	SEPARATION SIDE A FLAG		BFIAG		SEPARATION SIDE B FLAG	PROPER SEQ CHECK ON	SOFIASTIC CMUERKEFORI	SOFTEEPROMPAILMEPORTS	RF (ARIES) POWER	RF COM RELAY (CF	RF HIGH PWR AMP	\neg	RF NDT MON (NDM)	-	FLIRGCI-HIBNDCH1,2,3	AVONORENAL DIBANDOLI	EAL A BACHTHIBANDCH3	AVONOISEVALHIBANDCH3	FAI AI ARMCNTHIBANDCH2	AVGNOISEVALHIBANDCH2	SHUNT DRIVE VOLTAGE #1 (T1)	SHUNT DRIVE VOLTAGE #1 (T2)	SHUNT DRIVE VOLTAGE #2 (T1)	SHUNT DRIVE VOLTAGE #2 (12)	V EN INSO I ENO	S-BAND RCVR 1 SIGNAL PRESENT	S-BAND RCVR 2 SIGNAL PRESENT	STATIONKEEPING ABORT	STATIONKEEPING ABORT	INDICATOR	FALTRGCNT-LOBNIXCH1,2	FALALAKMON I LOBANDON I	FAI AI ARMONTI OBANDCH2	AVGNOISEVALI OBANDCH2	SLOPE (7 MSB)	SLOPE (8 LSB)			_	SOLAR YSLOW FB COMPRATE	SOL DAY	-	
SEGIFB	SECJEWR	SEGMENTI	SEGMENTJ	CEDCIDAA	SEPSIDAB	GEDGIDBA	עמטויי ביי	SEPSIDBB	SEOCK	SFTASCSM	SFIEESM	SCDARPWR	SGDCRPWR	SGDHPAAT	SGDHPABT	SGDNDPWR	SCDTXPWR	SHBFTC	SHEET CLASS	CHETCA	SCIDIO SC	SHEWCEAC	SHBMCN	SHDV1T1	SHDV1T2	SHDV2T1	SHDV2T2	DOMNATATIO	SIGPRE1	SIGPRE2	ATOMANO	SNABKIA	SKABRTB	SLBFTC	SLBHCFAC	SLBHCN	SECONOL SO	SLOPEH	SLOPEL	SLOPESGN	SMSGRERR	SOAMODE	SOAUMOFS	SOLDAY	SOLDSPAN	SOLENC
REI CER	SEGJPWR	SEGMENTI	SEGMENTJ	CEDCIDAA	SEDGIDAR	CED CID BA	Vanishas Vanishas	SEPSIDBB	SEQCK	SFTASCSM	SFIEESM	SCDARPWR	SGDCRPWR	SGDHPAAT	SGDHPABT	SGDNDPWR	တ်	_	0	SHEHCN	1	U		_	1	_	-	SHA-KWO	SIGPRE1	SIGPRE2	-	SKABKIA			S	SLEHCN	1	1		-	-		SOAUMOFS	-	O	+
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SOLARINHENDTIME-8MSB		B			R INHIBIT DISABLE		SOLAR INHIBIT PERIOD	SOL RSRS=PENUMBRA'2		ARINHSTRTTIM-8MSB		R			X1X1		SPARE 00 AH DWELL REGION	SPARE 00 AH NON-DWELL REGION	SPARE 00 AP DWELL REGION	SPARE 00 AP NON-DWELL REGION	SPARE 00 DL DWELL REGION	SPARE 00 DL NON-DWELL REGION	SPARE 01 AH DWELL REGION	SPARE 01 AH NON-DWELL REGION	SPARE 01 AP DWELL REGION	SPARE 01 AP NON-DWELL REGION	SPARE 01 DL DWELL REGION	SPARE 01 DL NON-DWELL REGION	SPARE 02 AH DWELL REGION	SPARE UZ ARI NOIN-DWELL REGION	SPARE 02 AP NON-DWELL REGION	SPARE 02 DL DWELL REGION	SPARE 02 DL NON-DWELL REGION	SPARE 03 AH DWELL REGION	SPARE 03 AH NON-DWELL REGION	SPARE 03 AP DON-DWELL REGION	SPARE 03 DL DWELL REGION	SPARE 03 DL NON-DWELL REGION	SPARE 04 AH DWELL REGION	SPAKE 04 AH NON-DWELL REGION	SPARE 04 AP NON-DWELL REGION	SPARE 04 DL DWELL REGION	SPARE 04 DL NON-DWELL REGION	SPARE 05 AH DWELL REGION	SPARE OF AH NON-DWELL REGION	SPARE US AP NON-UVELL REGION	SPARE OF DI NON-DIVIELI REGION	SPARE 06 AH DWELL REGION	SPARE 06 AH NON-DWELL REGION	SPARE 06 AP NON-DWELL REGION	SPARE US DI DIVELL REGION	SPARE 06 DL NON-DWELL REGION
SOLETH	SOLETL	SOLETM	SOLINCA	SOLINCB	SOLINHIB	SOLINHST	SOLINPER	SOLPEN2	SOLSPAN	SOLSTH	SOISTI	SOLSTM	SOI IMB2	SOLX1	SOI X1X1	SOLY	SPOOAHDW	SPOOAHND	SPOOAPDW	SPOOAPND	SPOODLDW	SPOODLND	SP01AHDW	SP01AHND	SP01APDW	SP01APND	SPOIDLDW	SPO1DLND	SPOZAHDW	SPUZAHND	SPOZAPNO	SPOZDLDW	SPO2DLND	SPOBAHDW	SPO3AHND	SPURAPUW	SPOOLDW	SPO3DLND	SP04AHDW	SPOAAHNU	SPOAAPND	SPOADLDW	SPOADLND	SPOSAHDW	SPOSAHND	OF CAPACION OF CAP	SPOSOLDWY	SPOSAHDW	SPOGAHND	SPO6APND	SPOBULUM	SPOEDLND
SOLETH	SOLETL	SOLETM	SOLINCA	SOLINCB	SOLINHIB	SOLINHST	SOLINPER	SOLPEN2	-	H	SOISTI	MINION	SOLUMB?	SOLXI	NO XIX1	. :	SPOOAHDW	╁╴	-	╀	+	├-		SPOTAHND	SP01APDW 8			+	_	SPUZAHNU		-	Н	Н	-	SPUSAPDW	+	+	-	SPOAAHNU	+	1.	╀	-	SPOSAHND	+	SPABULDAY	SPOSAHDW	SPOGAHND		SPOGULUW	SPOEDLND
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All Power-Up	All Power-Up	All Power-Up	¥	All	All Power-Up	All Power-Up	₹	₹	All Power-Up	All Power-Up	A	₽	ΙΚ	¥	7	A	₹ ₹	2	₽	ΑII	F	Farty Orbit		Early Orbit	Early Orbit	Early Orbit	Early Orbit		Early Orbit	Early Orbit	Early Orbit	SSOH	Early Orbit		Early Orbit	Early Orbit		Eany Orbit	Early Orbit	Early Orbit	Early Orbit
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	SPARE 07 AH NON-DWELL REGION	SPARE 07 AP NON-DWELL REGION	SPARE 07 DL DWELL REGION	SPARE 08 AH DWELL REGION	SPARE 08 AH NON-DWELL REGION	SPARE 08 AP NON-DWELL REGION	SPARE 08 DL DWELL REGION	SPARE OF AH DIAMELL REGION	SPARE 09 AH NON-DIVIELL REGION	SPARE 09 AP NON-DWELL REGION	SPARE 09 DL DWELL REGION	SPARE 09 DL NON-DWELL REGION	SPARE 10 DL NON-DWELL REGION	SPARE 11 DL NON-DWELL REGION	SPARE 12 DL NON-DWELL REGION	SPARE 14 DI NON DIVISITI DECION	SPARE 15 DL NON-DWELL REGION		DWELL	18 DL NON-	SPARE 19 DL NON-DWELL REGION	SPM SPIN PERIOD (1 OF 4)		SPM SPIN PERIOD (2 OF 4)	SPM SPIN PERIOD (3 OF 4)	SPM SPIN PERIOD (4 OF 4)	SPM SPIN PERIOD (1 OF 4)		OFM OPIN PERIOD (2 OF 4)	SPM SPIN PERIOD (3 OF 4)	SPM SPIN PERIOD (4 OF 4)	~ :	SPM CEP TO FIRST PULSE DELAY (1 OF 4)	SPM CEP TO FIRST PULSE DELAY	SPM CEP TO FIRST PHI SE DELAY		SPM CEP TO FIRST PULSE DELAY	SPM CEP TO FIRST PULSE DELAY			SPM CEP TO FIRST PULSE DELAY (3 OF 4)
SP07AHDW	SP07AHND	SP07APND	SP07ULDW SP07ULDW	SP08AHDW	SP08AHND	SP08APND	SPORDLOW	SPORHIN	SP09AHND	SP09APND	SPOODLDW	SPO9DLND	SP10DLND	SPIDEND	SP13DIND	SP14DI ND	SP15DLND	SP16DLND	SP17DLND	SP18DLND	SP190LND	SPINPERA		SPINPERA	SPINPERA	SPINPERA	SPINPERB	CDINIDED	פרווארבולם	SPINPERB	SPINPERB	SPITCHTC	SPMDLAYA	SPIAN AVA		SPMDLAYA	SPMDIAYA	T	SPMDLAYB	SPMDLAYB	SPMDLAYB
7 8	- 1	× 0×	2	7 8	7 8	2 0	3 1 SPORDINO	7 8	7 8	7 8	4	4 0	1 1 SPIODEND	2	1 6	4	0	-	2 1 8	7	4 - SPISOLNO	7 32 SPINPERA	- {	/ 32 SPINPERA	7 32 SPINPERA	7 32 SPINPERA	7 32 SPINPERB	7 % SPINIDEBR	3	7 32 SPINPERB	33	NA 8 SPITCHTC	7 32 SPMDLAYA	7 30 SPMDIAVA	3	7 32 SPMDLAYA	7 32 SPMDLAYA		7 32 SPMDLAYB	7 32 SPMDLAYB	7 32 SPMDLAYB
7 31 8	o o	3 7 6	v &	8 31 8	28	3, 0, 0	8 11 -	1 30 8	2 32 8	6 57 8	2 31 1	8 4		1 0	2 41 1	2 41 1	· ·	2 42 1	42 1	A 2 42 1 3	74	1 8 52 8 0		2 2 3	1 8 54 8	1 8 55 8 0	1 8 60 8	2 2 3 C		1 8 62 8 0	8 8	NA NA NA O	8 8 52 8 0	8 23	3	8 8 54 8 0	8 8		8 8 90 8 0	8 8 61 8 0	8 8 62 8 0

Should be AF: 16-bit fixed w/scale factor																																			
	1=Enabled 0=Disabled	1=Enabled 0=Disabled									1=Off 1=Coarse Pri 2=Coarse Even	3=Coarse Odd	4=Fine Pri	5=Fine Even	1=Off 1=Coarse Pri		3=Coarse Odd	4=Fine Pri	6=Fine Odd	1=CPU B in Control 0=CPU A in Control	1=CPU Normal	0=CPU Swap		1=0#	0-0-	1=0ff 0=0n	1=Off OFO	1=Normal Memory	1=CPU B Selected 0=CPU A Selected	1=CPU A in Control 0=CPU B in Control	1=CPU Normal	O-CFU SWap		1=0# 0=0	1=Off 0=On
		:	counts	Action 5	counts	1	Spreade	seconds	seconds	seconds													volts	Ceisius								y volta	Celsius		
Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	E adv. Cakit	Farty Orbit	Early Orbit	Early Orbit	Early Orbit		,		Farly Orbit					Early Orbit	All Power-Up		Ali Power-Up	All Power-Up	do-Jawei-Ob	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up		All Power-Up	All Power-Up	All Power-Up	All Power-Up
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SPUB	SPU A	SPU B	SPUA	SPUA	SPUB	<u>a</u>	SPUA	SPUA	SPUB	SPUB		,		SPUA					SPUB	SPU		SPU	Ods Ids	٠ <u>٠</u>	GED	GED	SPU	SPU	SPU	SPU	1100	SPU	SPU	GED	GED
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SPM CEP TO FIRST PULSE DELAY (4 OF 4)	SPM RUN FLAG		SPM PULSE PAIRS REMAINING (1 OF 2)	SPM PULSE PAIRS REMAINING (2 OF 2)	SPM PULSE PAIRS REMAINING (1 OF 2)	SPM PULSE PAIRS REMAINING (1 OF 2)		2 OF 2)	SPM PULSEWIDTH (1 OF 2)	2 OF 2)				SPM THRUSTER SELECTION					SPM THRUSTER SELECTION	SPU A IN CONTROL		SPU A CPU NORM / SWAP	SPU A CONV TEMP		SPU A GED 1 ON/OFF	SPU A GED 2 ON/OFF	SPU A I/O PWR ON/OFF	SPU A MEMORY NORMAL		SPU B IN CONTROL	04			SPU B GED 1 ON/OFF	SPU B GED 2 ON/OFF
SPMDLAYB	SPMENA	SPMENB	SPMPAIRA	SPMPAIRA	SPMPAIRB	SPMPAIRB	SPMPWA		SPMPWB		-			SPMSLCTA					SPMSLCTB	SPUACONT			SPUACVT		SPUAGED1	SPUAGED2	SPUAIOP	SPUAMEM	SPUASEL	SPUBCONT	Idoalido	T	,	SPUBGED1	SPUBGED2
SPMDLAYB	SPMENA	SPMENB	SPMPAIRA	SPMPAIRA	SPMPAIRB	SPMPAIRB	SPMPWA	SPMPWA	SPMPWB	OV INI O				SPMSLCTA			•		SPMSLCTB	SPUACONT		SPUACPU	SPUACVT		SPUAGED1	SPUAGED2	SPUAIOP	SPUAMEM	SPUASEL	SPUBCONT	SPUBCPU	SPUBCV5V	SPUBCVT	SPUBGED1	SPUBGED2
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天	1=Normal Memory 0=Swap Memory	1=CPU B Selected 0=CPU A Selected														0=Test Disabled RDMGMT Flag Word 52 1=Test Enabled (lower half-first word)	0=Test Disabled RDMGMT Flag Word 54 1=Test Enabled (lower half-first word)		0=Test Disabled RDMGMT Flag Word 62 1=Test Enabled (lower half-first word)	r-Up 2=Early 3=Normal ter 0 and 5-7	r-Up 2=Early 3=Normal ter 0 and 5-7	r-Up 2=Early 3=Normal ter 0 and 5-7	r-Up 2=Early 3=Normal ter 0 and 5-7		403
10 10 10 10 10	1=h 0=S	- 0 - 0									_				Celsius	0=T=1	0=T=1	0=T=1	0=T 1=T	1=Powe Orbit 4=Thrus Unused	1=Powe Orbit 4=Thrus	1=Powe Orbit 4=Thrus Unused	1=Powe Orbit 4=Thrus		
All Power-Up	All Power-Up	All Power-Up	Early Orbit	Early Orbit	Normal	Normal		:	Early Orbit	Early Orbit	Normal	Normal	Thruster	Thruster	٥	Normal	Thruster	Normal	Thruster	₹	₹	Power-Up	Power-Up	HOSS	SSOH
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TT&C	TT&C	TRC	7 % C	78°C	17&C	T&C	7.8C	T&C	2 L	T&C	TT&C	TRC	TT&C	TRC	MSS	TT&C	T&C	TT&C	T&C	T&C	T&C	T&C		↓_	SON
SPU B I/O PWR ON/OFF	SPU B MEMORY NORMAL	SPU B SELECT	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	SPU-CDU CMD ACCEPT COUNT (1 OF 2)	SPU-CDU CMD ACCEPT COUNT (2 OF 2)	+X BUS PNL/SPU I/F TEMP A	SPU I/O CONTROL	SPU I/O CONTROL	SPU I/O CONTROL	SPU I/O CONTROL	SPUMODE	SPUMODE	SPU MODE	SPUMODE	ROLL TRIGGER COUNT	I SEGMENT BIAS
SPUBIOP	SPUBMEM	SPUBSEL	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUIFT	SPUIOCLA	SPUIOCLA	SPUIOCLB	SPUIOCLB	SPUMODEA	SPUMODEB	SPUMODPA	~		SSEGIBV
SPUBIOP	SPUBMEM	SPUBSEL	SSPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTA	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUCMCTB	SPUCMCTB	S	SPUIFT	SPUIOCLA	SPUIOCLA	SPUIOCLB	SPUICCLB	SPUMODEA	SPUMODEB	SPUMODPA	SPUMODPB	SROLLTC	SSEGIBV
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NA 2		STSTPFAK	STSTPFAK	BDY SYSTSTSETRMPPEAK	800	BDP	S	SSOH	29	2973
NA NA S	<u>.</u>	STSTPWID	STSTPWID	BDY SYSTSTSETPULSWID	82	BDP	S	HOSS	29	2973
N A	NA 4	STSTSBIT	STSTSBIT	SYS TEST SERIES BITS	88	BDP	ဟ	SSOH	298	2985
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NA NA NA 4	-	STXFRMSG	STXFRMSG	XFER MSG FLAG STATUS	82	BDP-MP	တ	SSOH	46	
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7	-	CI INI KA	VI IVII K	NI S	T&T	Allds	U.	Normal	O=No Sun Lock	ADS Flag Word
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-		SUNLKB	SUNLKB	SUNLOCK	TT&C	SPUB	S	Thruster		ADS Flag Word
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13 2 5	2	SVSOHA	SVSOHA	REDUNDANCY MGMT SV STATE OF HEALTH	T & C	SPU A	ဟ	₹		TLM Flag Word 13 (second word)
	+			REDUNDANCY MGMT SV STATE OF		ļ		,	1=Yellow	TLM Flag Word 21 (second
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NAN		1		BDP IP WLS B BUFEVCT	SON	909	S	HOSS	333	33
0 X				SOFTWARE VERSION	SON	BDD/X	S	SSOH	26	2ස
A A		SXFRERR	SXFRERR	BDY SERIAL XFER ERROR	NDS	ACB	S	HOSS	254	2
NA NA O		SYFSTFB	SYFSTFB	YFAST FEEDBACK	SON	ВΩУ	S	HOSS	402	200
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o ≨		SYFSTN	SYFSTN	YFAST S7 NOISE	8	À R	S	SSOH	401	10
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NA NA O	∞	4	STESTIC	THAS I RIGGEN COOK!	3 5	1	טופ	All Dough In	2	Symc Word 1 (EA Hex)
-	7 24	4	SYNCWRD	ILM SYNC WORD (1 OF 3)	١	_	0	All Parise I is	000	VIIIC Wold I (FA Nex)
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A WAN O	NA 24	SYNCWRU	O INCORRE	VSI OW I TNING! NTRGCNT	88	Ţ	ာတ	HOSS	41	413
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₹	+-	SYSTEST	SYSTEST	TIM/NXTX1 EPOCSYSTST	SON	BDP	S	SSOH	29	2984
NA NA NA 7	NA 1	SYSTST21	SYSTST21	SYS TEST 2-1 (SPIKE)	8	<u>}</u>	S	SSOH	21	215
		SYSTST22	SYSTST22	SYS TEST 2-2 (SQUARE)	8 2		တ	HOSS	21	215
NA NA NA NA 5	- ≶	SYSTST24	SYSTS124	SYS IESI 2-4 (KAMP)	3	AC.	n	1000	171	CI

MAIN 1 NATE SYSTEME SYSTEME SYSTEME NATE N	215	215	215	3015	Thruster Flag Word 54 (first word)	Thruster Flag Word 62 (first word)	TLM Flag Word 13 (second word)	TLM Flag Word 21 (second word)	M Poc 6 201 W/M	ADS Flag Word	2952	2953	2954	2965	3030	3031	3032	3033	3034	3035			Last 2 bits of TIU serial cmd echo (unallocated)	(pampaumin) auga			RDMGMT Flag Word 52	RDMGMT Flag Word 54	RDMGMT Flag Word 60	RDMGMT Flag Word 62	RDMGMT Flag Word 55	RDMGMT Flag Word 53 (upper half-second word)	RDMGMT Flag Word 63 (upper half-second word)
MANNIA MAI 19/15/15/15/16 5/5/15/15/16 5/5/15/16 19/5/15/16 5/5/					0=Odd Half 1=Even Half 2=Both Halves	0=Odd Half 1=Even Half 2=Both Halves	0=Thrusters Off 1=Thrusters On	0=Thrusters Off 1=Thrusters On	0=PW < Max Pulsewidth (PID Enabled) 1=PW > Max Pulsewidth	0=PW < Max Pulsewidth (PID Enabled) 1=PW > Max Pulsewidth (PID Disabled)	7										1=Disabled 0=Enabled	1=Disabled 0=Enabled	Binary value (TIU CMD echo bits 18.17)				0=Disabled	0=Disabled	0=Disabled	0=Disabled	0=Test Disabled	0=Test Disabled	0=Test Disabled 1=Test Enabled
WANNIN W. W. SYSTSTER SYSTSTER SYSTEM SYSTE										·														volts	Celsius	Volts							
MANIAN N. M. 1 SYSTSTER SYSTEER SYSTEER SWSTEER SWSTEEN N. SWSTEER S	SSOH	SSOH	SSOH	SSOH	Thruster	Thruster	₹	₹	Normal	Normal	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	SSCH SCH	SSOH	Power-Up	Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Normal	Thrietor	Normal	Thruster	Normal	Thruster	Normal
MAN NA MA 1 SYSTSTER SYSTEET 2 & MODION NDS MAN NA MA 1 SYSTSTEN SYSTEET 2 & MODION NDS MAN NA 1 MA 1 FESTMEM TESTMEM TESTMEM THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 FESTMEM TESTMEM THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 FESTMEM THROSEN THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 THROWA THROWA THRUSTERS ON THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 THROWA THROWA THRUSTERS ON THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 THROWA THROWA THRUSTERS ON THRUST CATTLA BORT THRUSTERS ON THRUST CATTLA BORT THRUSTER MAN NA 1 MA 1 THROWA THROWA THRUSTERS ON THRUST CATTLA BORT THRUSTERS ON THRUST CATTLA BORT THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA BORD THRUST CATTLA	S	တ	ဟ	တ	တ	v	ဟ	ဟ	ď	y v	S	S	S	တ	ဟ	S	တ	S	n c	n	S	ဟ	ဟ	₹	₽	₹₽	ဟ	U	o o	S	v	· v	S
MAN NA MA 1 NA 1 SYSTSTEP SYSTSTEP SYSTEPT 24 (MOTION) NEW NATE MAY NATE	BDY	BD√	AGB	80P	SPUA	SPUB	SPUA	SPU B	Allas	SPUB	BDP	вор	вор	909	BDP	вор	80b	80b	2 2	200	SPUA	SPUB	2	TIU	£	22	SPUA	Alida	SPUB	SPUB	SPUA	SPUA	SPUB
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NA NA NA NA 1 SYSTSTEN SYSTSTEN NA NA NA 1 SYSTSTEN SYSTSTEN SYSTSTEN NA NA NA 1 SYSTSTEN SYSTS	SYS TEST 2-8 (MOTION)	SYSTEM TEST ENABLE	SYSTEM TEST EXECUTE	ENABLE TEST MEMORY	THRUST CNTRL ABORT THRUSTER SELECT	THRUST CNTRL ABORT THRUSTER SELECT	THRUSTERS ON	THRUSTERS ON	THRUSTER PULSEWIDTH LIMIT	THRUSTER PULSEWIDTH LIMIT	SOLARINHCNSTNT-@0HI	SOLARINHCNSTNTS-@0LO	SOLARINHCNSTNT-@1HI	SOLARINHCNSTNTS-@1LO	TIME INTERVAL 1 HI 8	TIME INTERVAL 1 LO 8	TIME INTERVAL 2 HI 8	IIME INTERVAL 2 LO 8	THE INTERVAL STILLS	TIME IN LEKVAL 3 LO 8	DISABLED	FLAG INDIC IF 5 MIN BOOT TIMER IS DISABLED	TIU SERIAL CMD ECHO BITS 18/17	TIU A CONV +5VDC OUT	TIU A CONV TEMP	TIU B CONV TEMP			TELEMETRY INFORMATION UNIT	TELEMETRY INFORMATION UNIT	ŧ.	TIU FRAME COUNT	TIU FRAME COUNT
NAM	SYSTST28	SYSTSTEN	SYSTSTEX	TESTMEM	THRABRTA	THRABRTB	THRONA				TIMEOH	TIMEOL	TIME1H	TIME1L	TIMINT1H	TIMINT1L	TIMINT2H	I IMIN I ZL	TIMINISH	I IMIN I SE	TIMRDISA	TIMRDISB											TIUFCNTB
N	SYSTST28	SYSTSTEN	SYSTSTEX	TESTMEM	THRABRTA	THRABRTB	THRONA	THRONB	THRPWLMA	THRPWLMB	TIMEOH	TIMEOL	TIME1H	TIME1L	TIMINT1H	TIMINT1L	TIMINT2H	I IMINI 2L	TELLINITO	I IMIIN I OF	TIMRDISA	TIMRDISB	TIU1718	TIUACVSV	TIUACVT	TIUBCVT	TIUENA	THIENA	TIUENB	TIUENB	TIUFCNTA	TIUFCNTA	TIUFCNTB
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(upper half-second word)	RDMGMT Flag Word 55 (upper half-second word)	RDMGMT Flag Word 53	(upper nair-second word) RDMGMT Flag Word 63	(upper half-second word)	RDMGMT Flag Word 61 (upper half-second word)	ROMGMT Flag Word 55	(upper half-second word)	RDMGMT Flag Word 53	RDMGMT Flag Word 63	(upper half-second word)	RDMGMT Flag Word 61 (upper half-second word)									at First word (8 bits) of TIU	serial cmd echo		First unra (8 hits) of Till	serial cmd echo	First word (8 bits) of TIU	Senal cmd ecno	2			-	3066										169		
0=Test Disabled 1=Test Enabled	0=Test Disabled	0=Test Disabled	1= i est Enabled 0=Test Disabled	1=Test Enabled	0=Test Disabled 1=Test Enabled	O=Test Disabled	1=Test Enabled	0=Test Disabled	0=Test Disabled	1=Test Enabled	0=Test Disabled 1=Test Enabled									1=Format 2 0=Format	-		O=Normal 1=Dumn		1=500 bps	sda control																	
												volts	volts	volts	Volts	volts	volts	volts	Æ	₽ P		volts	Volts				Celsius	Celsius	psia	psia	jq-ui	i-bf	jq-ui	jq-ui	jq-u	<u>6</u>	i ja	in-15	jq-ui	i-b	2	seconds	seconds
Thruster	Normal	F	i nruster	Normal	Thuster	DIGNIII.	Normal	Thrieter		Normal	Thruster	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Dough	SSOH	All Power-Up	All Power-Up	All Power-Up	All Power-Up	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	Normal	SSOH	Early Orbit	Early Orbit					
S	ဟ		n	တ	Ø	,	S	U.	,	တ	ဟ	₹	₹	₹	¥	¥	₹	₹	₹	₹	တ	₹	₹,	တ	U	0	ΑP	Ф	₹	₹ ′	n vo	S	ဟ	S	S	ທີ່	S	တ	S	S	၈	S	ဟ
SPU B	SPUA	200	A D Lo	SPUB	SPUB		SPUA	Allds		SPUB.	SPUB	ΤE	2L	2	2 2	<u>P</u>	⊒L	Œ	<u> 1</u>	2	₽	⊇.	2	TIU	Ē	à	TNK	TNK	YK.	Z S	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPUA	SPUA	SPUB	BDP-IP	SPUA	SPUA
T&C	T&C	()	8	78C	1 1 1		T&C	T &C		28 L	T&C	ည္ရွင္	ည္တ	ي د د	2 C	18C	TI&C	TI&C	28C	ည္ဆင္	TI&C	18C	<u>ဒ</u>	T&C	7.8.T	2 SS	RCS	RCS	S 5	3 2	ABS ABS	ADS	ADS	SQ.	SQ:	A S	ADS	ADS	ADS	SQ V	38	TT&C	TI&C
TIU FRAME COUNT	TIU POWER	TILLBOWER		TIU POWER	TIU POWER		TIU READBACK	TIU READBACK		TIU READBACK	TIU READBACK	TIU A 1.763V TLM	TIU B 1.763V TLM	TILL BO 194V T.M	TIU A 3.294V TLM	TIU B 3.294V TLM	TIU A 4.892V TLM			IIU B PASSIVE TLM CALIBRATE	TELEMETRY FORMAT	TIU GND TLM 1	IIO GIND I FIM Z	TELEMETRY MODE	TELEMETRY DWNLNK RATE	TIMED SYS TEST SCHED		RCS TANK 2 TEMP	RCS TANK 1 XDCR PRESSURE	RCS LANK Z AUCK PRESSURE	TORQUE DEMAND PITCH (1 OF 2)	TORQUE DEMAND PITCH (2 OF 2)	TORQUE DEMAND PITCH (1 OF 2)	TORQUE DEMAND PITCH (2 OF 2)	TORQUE DEMAND ROLL (1 OF 2)	TOROUE DEMAND ROLL (2 OF 2)	TORQUE DEMAND ROLL (2 OF 2),	TORQUE DEMAND YAW (1 OF 2)	TORQUE DEMAND YAW (2 OF 2)	TOROUE DEMAND YAW (1 OF 2)	TIME-OUT TASK FLAG	TPF THRUSTER BURNTIME (1 OF 2)	TPF THRUSTER BURNTIME (2 OF 2)
TIUFCNTB	TIUPWRA	TIHIDAVRA		TIUPWRB	TIUPWRB		TIURDBKA	TIURDBKA		TIURDBKB	TIURDBKB	TLM176A	TLM176B	TIMIGAR	TLM329A	TLM329B	TLM489A	TLM489B	TUMCALA	ILMCALB	TLMFMT	TLMGNDA	LMGNDB	TLMMODE	TIMBATE	TMSYSTST	TNK1T	TNK2T	TNKPRES1	TOABBOX	TOROPITA	TOROPITA	TOROPITB	TOROPITB	TORGROLA	TORORO! B	TORGROLB			TOPOVAIA			TPFBURNA
TIUFCNTB	TIUPWRA	TILIDARA		TIUPWRB	TIUPWRB		TIURDBKA	TIURDBKA		TIURDBKB	TIURDBKB	TLM176A	TLM176B	TI MISAR	TLM329A	TLM329B	TLM489A	TLM489B	IMCALA	ILMCALB	TLMFMT	TLMGNDA	a Carlo	TLMMODE	TIMBATE	TMSYSTST	TNK1T	TNK2T	THEOPEST	TOADBOY	TOROPITA	TOROPITA	TORQPITB	TOROPITB	TORGROLA	TORORO! B	TORGROLB	TORQYAWA	TORQYAWA	TOPOVAIVE	TOTASK	TPFBURNA	TPFBURNA
6 5 61 1 5 5 1	7 55 1 4 4 1	5 53 1 4 4 1		6 7 83 1 4 4 1	5 61 1 4 4 1		7 55 1 3 3 1	5 53 1 3 1		7 83 1	5 61 1 3 3 1	26 8 0 7	6 5 8 0 7 8	0 0	7 0 8 95	1 56 8 0 7 8	8 0 7	8 0 7	7 8 0	/ n 8 /c	10 1 1	2 26 8 0 7 8	s o 8	1 10 2 2 3 2	10 1	NA NA	7 0 8	8 0 7	0 0	A V O O V V O VIO	3 54 8 0	3 55 8 0 7 16	62 8 0 7	8 8 0 7	52 8 0 7	3 8 0 7 7 10	61 8 0 7	8 0 7 16	53 8 0 7 16	4 60 8 0 / 16	NA NA O NA	52 8 0 7	8 53 8 0 7 16

		1=Kunning 0=Not Running	1=Running 0=Not Running	0=Not Selected	0=Not Selected	0=Not Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1≕Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected	0=Not Selected	0=Not Selected 1=Selected	0=Not Selected	0=Not Selected	0=Not Selected 1=Selected
seconds	seconds										· · · · · · · · · · · · · · · · · · ·			<u>-</u> .														
Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit
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SPUB	SPUB	SPUA	SPU B	SPUA	SPU B	SPU A	SPU B	SPUA	SPU B	SPUA	SPUB	SPU A	SPU B	SPU A	SPUB	SPUA	SPU B	SPU A	SPUB	SPUA	SPU B	SPUA	SPU B	SPU A	SPU B	SPUA	SPUB	SPUA
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TPF THRUSTER BURNTIME (1 OF 2)	-	TPF RUN FLAG		SEL	1		TPF THRUSTER SELECTION -REA 02		TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA		TPF THRUSTER SELECTION -REA				TPF THRUSTER SELECTION -REA			TPF THRUSTER SELECTION -REA			TPF THRUSTER SELECTION -REA	F THRUSTER SEL	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	F THRUSTER SEL	TPF THRUSTER SELECTION -REA
TPFBURNB	TPFBURNB	TPFENA	TPFENB	TPFSL01A	TPFSL01B	TPFSL02A	TPFSL02B	TPFSL03A	TPFSL03B	TPFSL04A	TPFSL04B	TPFSL05A	TPFSL05B	TPFSL06A	TPFSL06B	TPFSL07A	TPFSL07B	TPFSL08A	TPFSL08B	TPFSL09A	TPFSL09B	TPFSL10A	TPFSL10B	TPFSL11A	TPFSL11B	TPFSL12A	TPFSL12B	TPFSL13A
16 TPFBURNB	TPFBURNB	1 TPFENA	1 TPFENB	1 TPFSL01A	1 TPFSL01B	1 TPFSL02A	1 TPFSL02B	1 TPFSL03A	1 TPFSL03B	1 TPFSL04A	1 TPFSL04B	1 TPFSL05A	1 TPFSL05B	1 TPFSL06A	1 TPFSL06B	1 TPFSL07A	1 TPFSL07B	1 TPFSL08A	1 TPFSL08B	1 TPFSL09A	1 TPFSL09B	1 TPFSL10A	1 TPFSL10B	1 TPFSL11A	1 TPFSL11B	1 TPFSL12A		
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											(lower half-second word)	RDMGMT Flag Word 55 (lower half-second word)	RDMGMT Flag Word 61	RDMGMT Flag Word 63	(lower half-second word)	RDMGMT Flag Word 55 (upper half-second word)	RDMGMT Flag Word 53	RDMGMT Flag Word 63	(upper half-second word)	(upper half-second word)	+-	 	34	3015	3028	3029		217			See S-Band Mode Table	See S-Band Mode Table	See S-Band Mode Table	2960	2961
0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected 1=Selected	0=Not Selected	0=Not Selected	0=Not Selected	1=Selected				0=Disabled 1=Enabled	0=Disabled 1=Enabled	0=Disabled	0=Disabled	1=Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled 1=Test Enabled	0=Test Disabled	1=1 est Enabled	U= I est Disabled 1=Test Enabled		1=Counter OK 0=Counter Overflow	1=Counter OK 0=Counter Overflow		100 min 100 mi										
							coconde	seconds	seconds	seconds																	Celsius	Celsins	Celsius	Celsius					
Early Orbit	Early Orbit	Early Orbit	Early Orbit	Early Orbit	Fark Orbit		Early Orbit	Early Orbit	Early Orbit	Early Orbit	Normal	Normal	Normal		Normal	Normal	Normal		Normai	Normal	SSOH	All Power-Up	All Power-Up	SSOH	HOSS	ED86	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	All Power-Up	HOSS	HOSS
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TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	TPF THRUSTER SELECTION -REA	F COUNTDOWN	TPF COUNTDOWN TIMER (2 OF 2)	TPF COUNTDOWN TIMER (1 OF 2)	1PT COON LOOVEN LIMER (2 OF 2)	TORQUE COILS	TORQUE COILS	TORQUE COILS	O IIOO LI TOROT	I ORGUE COILS	TORQUE COIL HIGH CURRENT	TORQUE COIL HIGH CURRENT	TOPOLIE COIL HIGH CLIBBENIT		TORQUE COIL HIGH CURRENT	TRAP	MDU A TRIGGER GO	MDU B TRIGGER GO	TESTMEMOVERWRITBYWHS	ZTIME FOR TEST MEM H18 ZTIME FOR TEST MEM LOS	-X BUS PNL'S-BAND XPONDER I/F	TEMP C	UHF ANTENNA PNL ELEM 10 TEMP	UHF ANTENNA PNL ELEM 7 TEMP A			S-BAND UPLNK/XSTP STAT 0-B	S-BAND UPLNK/XSTP STAT 1-B		UMBRA (8 LSB)
TPFSL13B	TPFSL14A	TPFSL14B	TPFSL15A	TPFSL15B	TPFSL16A	TPFSI 16B	TPFTIMRA	TPFTIMRA	TPFTIMRB	QVINII 1 J.L.1	TOCENA	TOCENA	TOCENB	TOCENIB	CCENB	TACHCURA	TACHCURA	TOCHCIBB	2	TACHCURB	TRAPINT	TRIGGOA		$\neg \tau$	TSTMEMTH		TAYOCOMP	1	UHFEL7T			ULXST0B	T		UMBRAL
TPFSL13B	TPFSL14A	TPFSL14B	TPFSL15A	TPFSL15B	TPFSL16A	TPFSL16B	TPFTIMRA	TPFTIMRA	TPFTIMRB	QVINIT LL1	TOCENA	TOCENA	TOCENB	TOCENID	0 000	TACHCURA	TACHCURA	TOCHCURA	2000	TACHCURB	TRAPINT	TRIGGOA	TRIGGOB	TSTMEMOV	TSTMEMTH		TWOCOMP	UHFEL10T	UHFEL7T	UHFEL9T	ULXSTOA	ULXST0B	ULXST1B	UMBRAH	UMBRAL
5 8 61 1 4 4 1	5 8 53 1 5 5 1	5 8 61 1 5 5 1	5 8 53 1 6 6 1	5 8 61 1 6 6 1	5 8 53 1 7 7 1	5 8 61 1 7 7 1	8 54 8 0	2 8 8 0 7	4 8 62 8 0 7 16	3	6 8 53 1 2 2 1	7 4 55 1 2 2 1	6 8 61 1 2 2 1	7 4 63 1 2 2 1	7 - 3	6 7 55 1 7 7 1	6 5 53 1 7 7 1	6 7 63 1 7 7 1		5 61 1 7 7	NA NA NA 1	A 1 41 1 3 3 1	1 42 1 3	NA NA NA 2	NA NA NA NA NA NA NA NA NA NA NA NA NA N	1	NA NA NA NA 6 NA 1	1 58 8 0	2 5 58 8 0 7 8	6 58 8 0 7	-	A 7 16 1 7 7 1	2 16 1 7 7	0 V	NA NA NA NA O NA 8

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1 0 0 1 UPINVLDB UPINVLDB	INVALID STATUS	INVALIDSTATUS	UPLINK BUFFER FULL	UPLINK BUFFER FULL	UPLOAD EE FLAG	XFER MSG FLAG UPLOAD	RST USART&SEND16EOMS	VCC WORD (2 OF 3)	VCC WORD (3 OF 3)	VCC WORD (1 OF 3)	VCC WORD (2 OF 3)	VCC WORD (1 OF 3)	OCU A PYROS (W-ANT) ARMED	OCU B PYROS (W-ANT) ARMED	W-HI ELE SPOOL POT WIP POS	W-HI INNER HNGE DMP TEMP	W-FILINIER HINGE FOL WIF FOR			W-LO ELE SPOOL POT WIP POS		W-LO INNER HNGE POT WIP POS	W-LO OUTER HINGE DMP TEMP	W-LO ELE SPOOL DMP TEMP	CMDERCNT-DATAINCONSIST	SERDATAERCNT-MSGCORRUPT	NOOPERERCNT-UNABLETOACT	SOVY DELAYED CALIBRA	TIMER TIMEOUT ER CNT	MATCHED WHS EV CNT	WHS LAST EV MSG XFER	IMP RIP TAKEO ITEL COMMO	WHS TMP BUFF I/P PNT	WHS TMP BUFF O/P PNT	WHS TMP BUFF QUE CNT	TMP BUF TAKOUTFLGS:WHX	VLS SAVEADDR ENTRY 10	VLS SAVEADDR ENTRY 2		VLS SAVEADDR ENTRY 4	WLS SAVEADDR ENTRY 5	VLS SAVEADUR ENTRY 6	VLS SAVEADDR ENTRY 8
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HOSS	SSOH	HOSS	SSOH	SSOH	SSOH	SSOH	HOSS	SSOH	SSOH	SSOH	SSOH	SSOH	SSOH	HOSS	SSOH	HOS S	- D	SSOH	HOSS S	1000	1000	HOSS		LOSS HOSS	1000	3 2	H 000	HOSS	-	All Power-Up	All Power-Up	All Power-Up	All Power-Up		All Power-Up	All Power-Up	All Power-Up	al Lauren	HOSS HOSS	-11	do lawor in	do-Jawei-In	All Power-Up	All Power-Up	All Power-Up	All Power-Up
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WLS SAVEADDR ENTRY 9	WLS L3 OUTPUT COUNT	WLS LAST EV MSG XFER	WLS PLINK EV XFERFLG	TMP BUF TAKEOUTFLGS:WLS	WLS TMP BUFF I/P PNT	WLS TMP BUFF O/P PNT	WLS IMP BUF QUEUECNT	IMP BOF TAKEOUTFLGS:WLX	A MUSE OF START ADDR	LOBY IE OF STAKI ADDR	MIDBY IE OF START ADDR	MEMORY LOAD DATA	WRITE REFRESH BDY	WRITE REFRESH GDR	WRITE REFRESH BUP IP	_	-	BOIM OVE TEST EXECUTE	BOW DISCRETE SYSTEST	SYSTEM TEST TIME	WRITE UPLOAD BOY	WRITE UPLOAD GOR	WRITE LIPLOAD BOD ID	WRITE LIPLOAD BIDD MP	WHXMIXIASTEVMSGXER	WHXAAI X PI NKEVXEBOELO	ENABLE X-TRIG-Y	INTER(PARA FIEO XFER)		S-BAND XMTR 1 28VDC ON/OFF	S-BAND XMTR 1 RF PWR OUT	S-BAND AMIK 1 LEMP	S-BAND XMTR 1 TLM ENABLE	THOMAS CONTRACTOR STANDARD	S-BAND XMTR 2 RF PWR OUT	S-BAND XMTR 2 TEMP	S-BAND XMTR 2 TLM ENABLE	S-BAND XMTR SELECT 1/2	X TRIGGER SOURCE	XSTRAP LATCH VALVE PWR	XSTRAP LATCH VALVE PWR		XSTRP LATCH VALVE 3 CLOSE	XSTRP LATCH VALVE 4 CLOSE	XSTRP LATCH VALVE 3 OPEN	XSTRP LATCH VALVE 4 OPEN
WLSADD9	WLSL30UT	WLSPLNK	WLSOPLNK	WLSTBFTO	WLSTBIP	WLSTBOP	WLS IBOUE		VANIENCON	VVINEMUUL	VVMEMLUM	WMLCDDA	WRETBUY	WREFGOR	WKEFIF	WSDMPADH	WSDMPADI	WSTST1EX	WSTSTDEX	WSTSTTM	WUPLBDY	WUPLGDR	di idi iM	WUPIMP	WXPINK	WXOPI NK	X-YTRIG	XFRINTER		XMTR1PWR	XMIRIREP	ZMIKI	XMTR1TLM	VAITESCENIE		1	XMTR2TLM	MSTRSE	XSOURCE	XST34ARM	T	 	XSTPCLS3	XSTPCLS4	XSTOPON3	XSTOPON4
WLSADD9	WLSL3OUT	WLSPLNK	WLSGPLNK	WLSTBFTO	WLSTBIP	WLSTBOP	WLSTBCOE	VALATER DE	VANAENI DI	VVINEMEDE	VVINEMICUM	WMCCCCA	VVKETBUY	WKETGUK	WREFIF	WSDMPADH	WSDMPADI	WSTST1FX	WSTST2EX	WSTSTTM	WUPLBDY	WUPLGDR	WUPLIP	WUPLMP	WXPLNK	WXOPI NK	X-YTRIG	XFRINTER		XMTR1PWR	XMIKIKIP	AMIKII	XMTR1TLM	YAATDOOMAD	XMTR2RFP	XMTR2T	XMTR2TLM	XMTRSFL	XSOURCE	XST34ARM	XST34PWR		XSTPCLS3	XSTPCLS4	XSTOPON3	XSTOPON4
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						radians	radians	radians	radians	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	rad/sec	in-lbf-sec	in-lbf-sec	in-lbf-sec	in-lbf-sec	rad/sec	rad/sec	rad/sec	rad/sec	radians	radians	radians	acia				
HOSS	HOSS	HOSS	HOSS	All Power-Up	HOSS	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Thruster	Thruster	Thruster	Thruster	Normal	Normal	Normal	Normal	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal Thruster	Normal	Normal	Normal	SSOH	HOSS	HOSS	FON HOUSE	SSOH
S	တ	S	တ	ဟ	S	S	ဟ	ဟ	တ	ဟ	S	S	တ	တ	S	လ	တ	S	S	တ	ဟ	တ	S	S	တ	S	S	တ	S	S	S	מ	S
ВОР	ВОР	BDP	ВОР	EDX	BDY	SPUA	SPUA	SPU B	SPU B	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPUB	SPUB	SPUA	SPUA	SPU B	SPU B	SPU A	SPUA	SPU B	SPUB	SPUA	SPUA	SPUB	BDP	BDP	BDP-MP	RDP-IP	BDP-IP
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BDX/D SYS TEST EXECUTIVE	BDX DISCRETE SYSTEST	BDX SYSTSTENTIMEBITS	BDX SYSTEM TEST	BDX SYSTEM TEST	X TRIGGER Y	YAW ATTITUDE ERROR (1 OF 2)	YAW ATTITUDE ERROR (2 OF 2)	YAW ATTITUDE ERROR (1 OF 2)		YAW ATTITUDE INTEG ERROR (1 OF 2)		TTITUDE IN	YAW ATTITUDE INTEG ERROR (2 OF 2)	YAW ATTITUDE INTEG ERROR (1 OF 2)	YAW ATTITUDE INTEG ERROR (2 OF 2)	YAW ATTITUDE INTEG ERROR (1 OF 2)	YAW ATTITUDE INTEG ERROR (2 OF 2)	YAW MOMENTUM ERROR (1 OF 2)	YAW MOMENTUM ERROR (2 OF 2)	YAW MOMENTUM ERROR (1 OF 2)	YAW MOMENTUM ERROR (2 OF 2)	YAW ATTITUDE RATE ERROR (1 OF 2)	YAW ATTITUDE RATÉ ERROR (2 OF 2)	YAW ATTITUDE RATE ERROR (1 OF 2)	YAW ATTITUDE RATE ERROR (2 OF 2)	YAW ANGLE SUN NADIR (1 OF 2)	YAW ANGLE SUN NADIR (2 OF 2)	YAW ANGLE SUN NADIR (1 OF 2)	DISABLE YD 2-10	DISABLE AUTO YD	YD L3 OUTPUT COUNT	FORCE BUT STRATEGICS	YD PLINK EV XFER FLG
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REFERENCE

C-1. GPS IIR Orbital Operatons Handbook (OOH), Volume II - Telemetry Processing, G73-OOH-0031B, Martin Marietta Corp. Philadelphia, PA., 25 January 1995.

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